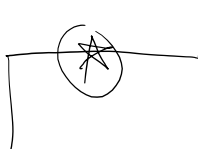


Previously, we used averages for parabolic heat conduction. Here, we are solving an elliptic PDE (CT dot term is absent from the PDE). So, we need to use elliptic fluxes.

In Arnold 2000, Arnold 20002 papers, many different formulas are given for star values of elliptic PDEs.

A general form can be given as follows:



$$q^* = \{q\} + \beta [q] + K\alpha [T]$$

$$T^* = \{T\} + \delta [T]$$

LDG Fluxes
"Cockburn & Shu"

$$G = \nabla u$$

Method	$h_{\sigma}^{e,K}$	$h_u^{e,K}$
Bassi-Rebay 1	$\{\sigma_h\}$	$\{u_h\}$
Brezzi et al. 1	$\{\sigma_h\} - \eta^e \{r_e([u_h])\}$	$\{u_h\}$
LDG	$\{\sigma_h\} - \eta^e [u_h] + \beta^e [\sigma_h]$	$\{u_h\} + \gamma^e [u_h]$

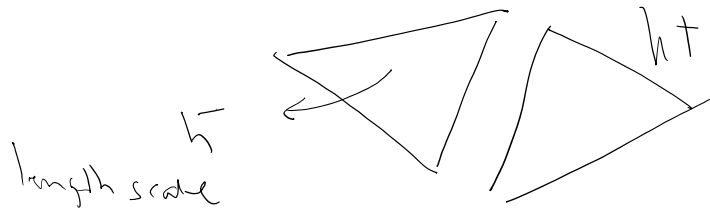
We'll get back to (*) to discuss the effect of α, β, δ

$-\alpha = K\alpha$ $[\{q\}] = [K\alpha [T]]$ Dimension

Dimension of $\alpha \leftarrow \frac{1}{L}$ $q = -K \frac{\nabla T}{[T] [L]}$

$$\alpha = \frac{\gamma_0}{h_{\min}}$$

$h_{\min} = \min\{h, h^+\}$



$$\alpha \propto \frac{1}{h}$$

for LDG (*)

$\gamma_0 > 0$
is sufficient for stability

Arnold 2002 paper

TABLE 6.1
Properties of the DG methods

Method	cons.	a.c.	stab.	type	cond.	H^1	L^2
Brezzi et al. [18]	✓	✓	✓	α^r	$\eta_0 > 0$	h^p	h^{p+1}
LDG [35]	✓	✓	✓	α^j	$\eta_0 > 0$	h^p	h^{p+1}
IP [43]	✓	✓	✓	α^j	$\eta_0 > \eta^*$	h^p	h^{p+1}
Bassi et al. [10]	✓	✓	✓	α^r	$\eta_0 > 3$	h^p	h^{p+1}

IP [43]	✓	✓	✓	α^j	$\eta_0 > \eta^*$	h^p	h^{p+1}
Bassi et al. [10]	✓	✓	✓	α^r	$\eta_0 > 3$	h^p	h^{p+1}
NIPG [53]	✓	x	✓	α^j	$\eta_0 > 0$	h^p	h^p
Babuška Zlámal [6]	x	x	✓	α^j	$\eta_0 \approx h^{-2p}$	h^p	h^{p+1}
Brezzi et al. [19]	x	x	✓	α^r	$\eta_0 \approx h^{-2p}$	h^p	h^{p+1}
Baumann Oden ($p = 1$)	✓	x	x	-	-	x	x
Baumann Oden ($p \geq 2$)	✓	x	x	-	-	h^p	h^p
Bassi Rebay [9]	✓	✓	x	-	-	$[h^p]$	$[h^{p+1}]$

hirable

$\vec{\gamma}, \vec{\beta}$ are two vectors, generally $\vec{\gamma} = -\vec{\beta}$

We'll talk about how these two vectors can result in an alternating flux scheme.

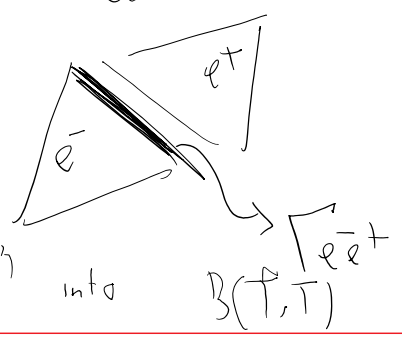
For the moment, assume $\vec{\gamma}, \vec{\beta} = 0$

$$\hat{T} = \{ \{ q \} \} + \bar{\alpha} [[T]]$$

$$T = \{ \{ T \} \}$$

(*) LDG
for $\vec{\beta} = \vec{\gamma} = 0$

Recall $R(\hat{T}, T) = B(\hat{T}, T) = \int_{\Gamma_{e^+}} [[\hat{q}]] (T - \{ \{ T \} \}) - \{ \{ \hat{q} \} \} [[T]] ds$
 $+ \int_{\Gamma_{e^+}} [[\hat{T}]] q ds$

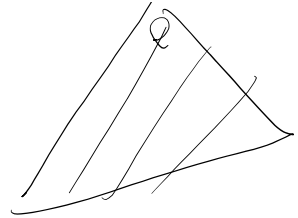


$$B(\hat{T}, T) = \int_{\Gamma_{e^+}} [[\hat{T}]] (\{ \{ q \} \} + \bar{\alpha} [[T]]) ds + \int_{\Gamma_{e^+}} (- \{ \{ \hat{q} \} \} [[T]]) ds \quad (1)$$

Contribution from inside the element

$$D(\hat{T}, T) = (r, \hat{T} q, \hat{T} n)_{\Omega}$$

$$R(\hat{T}, \pi) = \int_e (-\nabla \hat{T} \cdot \hat{q} - \hat{T} Q) dv$$



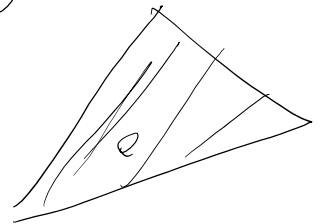
$$= \underbrace{\int_e \nabla \hat{T} \cdot \hat{q} dv}_{\text{goes to bilinear form}} - \underbrace{\int_e \hat{T} Q dv}_{\text{goes to RHS}}$$

$$B_i^e(\hat{T}, T) = \int_e \nabla \hat{T} \cdot \hat{q} \nabla T dv$$

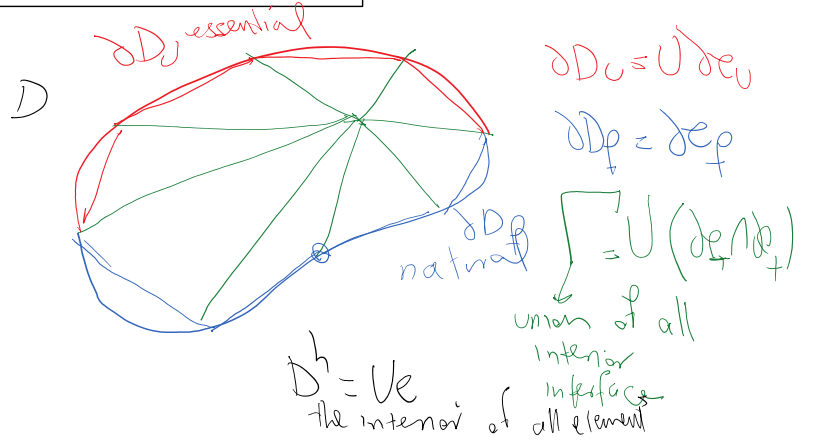
$$L_i^e(\hat{T}) = \int_e \hat{T} Q dv$$

inside the element

(2)



- Now we need to add up all the contributions from Essential BC (last time)
- Natural BC (last time)
- Interior interfaces (finished this time (equation 1))
- Interior of the elements (this time, equation 2))
- To get the global system of equations



Find T such that for all \hat{T} :

$$B(\hat{T}, T) = L(\hat{T})$$

$$B(\hat{T}, T) \rightarrow \sum_{\text{interior of elements}} R_i^e(\hat{T}, T) + \sum_{\partial \omega} B_{\omega}^e(\hat{T}, T) + \sum_{\Gamma \in \mathcal{T}_h} B_{\Gamma}^e(\hat{T}, T)$$

$$L(\hat{T}) = \sum_e L_i^e(\hat{T}) + \sum_{\partial \omega} L_{\omega}^e(\hat{T}) + \sum_{\text{def}} L_{\Gamma}^e(\hat{T})$$

$$R_i^e = \int -\nabla \hat{T} \cdot \nabla T = \int \nabla \hat{T} \cdot \nabla T \, dv \quad L_i^e = \int \hat{T} Q \, dv \quad \text{interior of element}$$

$$B_{\omega}^e = \int_{\partial \omega} (\hat{T} q - \varepsilon T \hat{q}) \, ds \quad L_{\omega}^e(\hat{T}) = -\varepsilon \int_{\partial \omega} \hat{q} \cdot n \, T \, ds \quad \text{essential BC}$$

$$B_{\Gamma}^e(\hat{T}, T) = 0 \quad L_{\Gamma}^e(\hat{T}) = -\int_{\text{def}} \hat{T} \hat{q} \, ds \quad \text{natural BC}$$

$$B_{\Gamma}^{e \pm} = \int_{\Gamma \in \mathcal{T}_h} [\llbracket \hat{T} \rrbracket] \hat{q}^{\pm} \, ds + \varepsilon \int_{\Gamma \in \mathcal{T}_h} \llbracket \hat{q} \rrbracket (T^{\pm} - \{T\}) - \llbracket \hat{q} \rrbracket \llbracket T \rrbracket \, ds$$

$$B_{\Gamma}^{e \pm} = \int_{\Gamma \in \mathcal{T}_h} \llbracket \hat{T} \rrbracket (\llbracket \hat{q} \rrbracket + \alpha \llbracket T \rrbracket) \, ds + \varepsilon \int_{\Gamma \in \mathcal{T}_h} \llbracket \hat{q} \rrbracket \llbracket T \rrbracket \, ds$$

Bilinear statement

(BLS)

Arnold 2002

Method	$B_h(u, v)$
Bassi Rebay [9]	$(\nabla_h u + R(u), \nabla_h v + R(v))$
Brezzi et al. [18]	$(\nabla_h u + R(u), \nabla_h v + R(v)) + \alpha^r(u, v)$
LDG [35]	$(\nabla_h u + R(u) + L_{\beta}(u), \nabla_h v + R(v) + L_{\beta}(v)) + \alpha^j(u, v)$
IP [43]	$(\nabla_h u, \nabla_h v) + (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^j(u, v)$
Bassi et al. [10]	$(\nabla_h u, \nabla_h v) + (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^r(u, v)$
Baumann Oden [12]	$(\nabla_h u, \nabla_h v) - (R(u), \nabla_h v) + (\nabla_h u, R(v))$
NIPG [53]	$(\nabla_h u, \nabla_h v) - (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^j(u, v)$
Babuška Zlámal [6]	$(\nabla_h u, \nabla_h v) + \alpha^j(u, v)$
Brezzi et al. [19]	$(\nabla_h u, \nabla_h v) + \alpha^r(u, v)$

we've explicitly added BC contributions

3 discussion points on bilinear form:

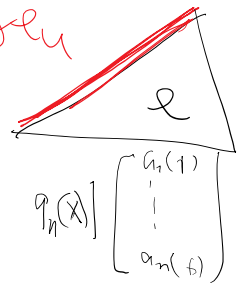
1. Symmetry of stiffness K
2. Is the bilinear form coercive $(B(T, T) \geq c |T|)$? -> Is related to the stability of method
3. Explicitly expand these equations for 1D case so we can more clearly see how K and F look like in discrete form. This will be used in your HW assignments.

Symmetry:

Symmetry:

Look at stiffness from all 4 contributions:
a. Essential BC

$$B_U(\hat{T}, T) = \int_{\partial \Omega} (\hat{T} q - \epsilon T \hat{q}) \, ds$$



$$T = [T_1(x) \ T_2(x) \ \dots \ T_n(x)]$$

basis functions

$$\begin{bmatrix} q_1(t) \\ q_2(t) \\ \vdots \\ q_n(t) \end{bmatrix}$$

$$q = -k \nabla T = [q_1(x) \ \dots \ q_n(x)] \begin{bmatrix} q_1(t) \\ \vdots \\ q_n(t) \end{bmatrix}$$

$q_i(t)$: parabolic PDE q_i : Elliptic PDE

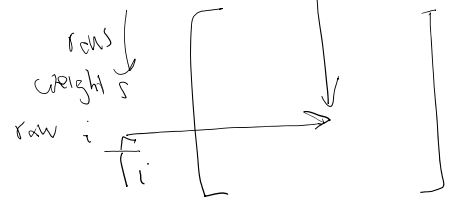
$$q_i = -k \nabla T_i$$

basis functions for q columns are sh columns

$$K_{ij} = ? \text{ from } B_U(\hat{T}, T)$$

$$K_{ij} = B_U(T_i, T_j)$$

$$\hat{T} = T_i \quad T = T_j$$



$$K_{ij} = \int (\hat{T}_i q_j - \epsilon T_j q_i) \, ds$$

$$K_{ji} = \int (T_j q_i - \epsilon T_i q_j) \, ds \quad i \leftrightarrow j$$

$\epsilon = -1 \quad K_{ji} = K_{ij} \quad \text{sym}$
 $\epsilon = 1 \quad K_{ji} = -K_{ij} \quad \text{skew sym}$
 $\epsilon = 0 \text{ \& other } \epsilon \quad \text{neither one}$

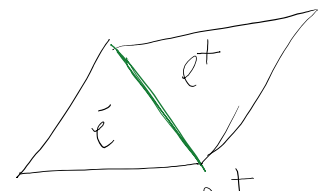
Essential BC

① sym or not

$\epsilon = -1$ is what we did in class in the beginning of the course

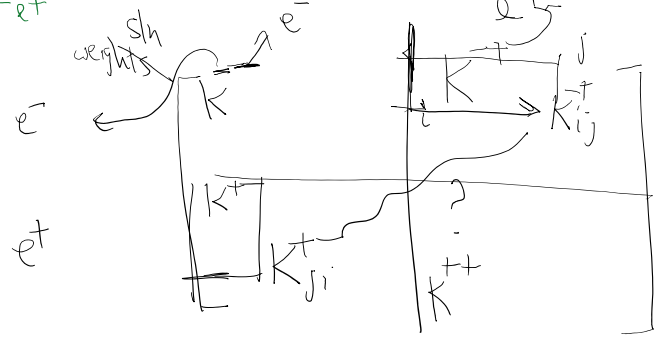
sym & not interior interfaces:

$$B_{\Gamma}(\hat{T}, T) = \int_{\Gamma} (\hat{T} q + \bar{\alpha} T \hat{q}) \, ds + \epsilon \int_{\Gamma} \hat{q} [T] \, ds$$



$$K_{ij} = B_{\Gamma}(\hat{T}, T)$$

for $\hat{T} = T_i^-$
 $T = T_j^+$



let's compute this

$$K_{ij} \quad \hat{T} = T_i^-$$

$$[f] = \hat{T}^- n^- + \hat{T}^+ n^+ = T_i^- n^- + 0 n^+ = T_i^- n^- \quad T = T_j^+$$

$$[T] = T^- n^- + T^+ n^+ = 0 n^- + T_j^+ n^+ = T_j^+ n^+$$

