

From last time:

$$\underbrace{\int_e^e U^T C U dv}_{m^e} \ddot{a} + \underbrace{\left(\int_e^e U^T dU \right)}_{C_b^e} \dot{a} + \underbrace{\int_e^e (\nabla U^T \nabla U)}_{K_b^e} da - \int_e^e U^T f dv$$

$$+ \int_e^e \hat{U} (-\hat{\sigma}_n^\oplus) ds + \int_e^e \hat{\sigma}_n \cdot n (-v^\oplus + v) ds = 0 \quad (1)$$

Deriving the matrices for linear elements in 1D

1D, p=1

$$m^e = \int_e^e U^T C U dv = \int_e^e \begin{bmatrix} 1 \\ x \end{bmatrix}^T c \begin{bmatrix} 1 \\ x \end{bmatrix} (h dx) = ch \begin{bmatrix} 1 & 1/2 \\ 1/2 & 1/3 \end{bmatrix}$$

$$C_b^e = \int_e^e U^T dU = dh =$$

$\kappa = \frac{x - x_0}{h}$
 $U = \begin{bmatrix} 1 \\ x \end{bmatrix}$
 $\nabla U = \frac{dU}{dx} = \begin{bmatrix} 0 \\ 1/h \end{bmatrix}$

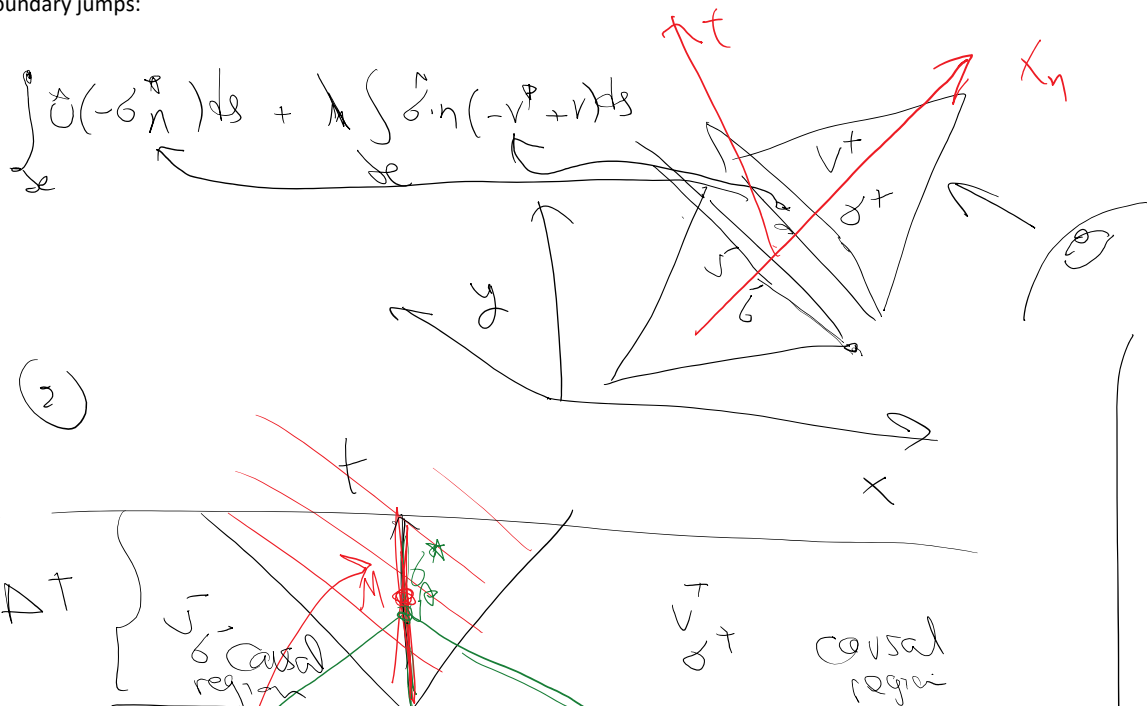
Damping matrix from the interior (bulk) of the element

$$K_b^e = \int_e^e \nabla U^T k \nabla U = \int_0^1 \begin{bmatrix} 0 \\ 1/h \end{bmatrix}^T k \begin{bmatrix} 0 \\ 1/h \end{bmatrix} (h dx) = \frac{k}{h} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Form term

$$\int_e^e U^T s dv = \begin{bmatrix} s \\ h \end{bmatrix} \cdot \begin{bmatrix} 1/2 & 1/2 \\ 1/6 & 1/3 \end{bmatrix}$$


Now we focus on terms related to boundary jumps:

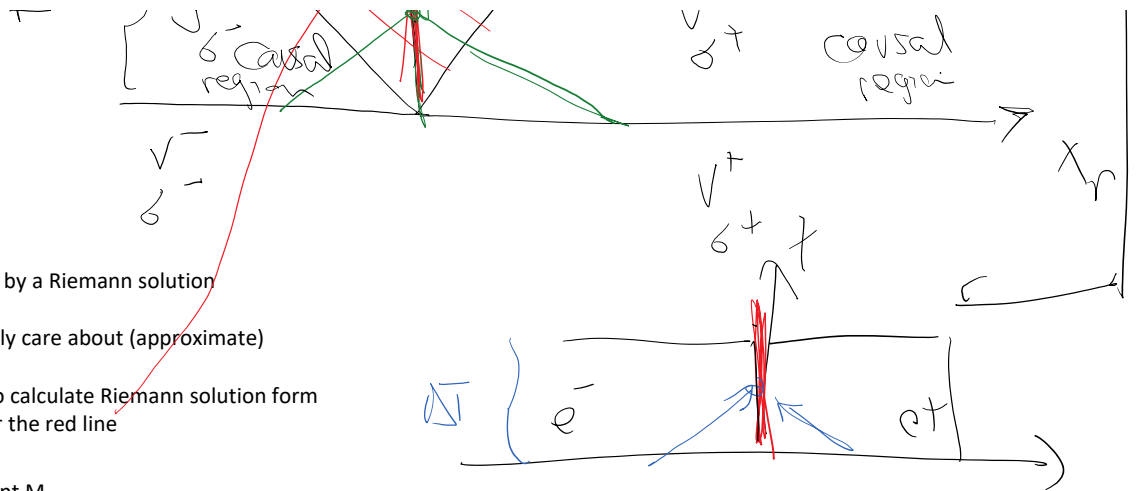


Choices are average fluxes

$$\bar{v}_n = \frac{v^- + v^+}{2} \quad (2)$$

$$\bar{\sigma}_n^\oplus = \frac{\sigma^- + \sigma^+}{2}$$

Or use Riemann solutions



We find the solution on vertical line by a Riemann solution

With time marching schemes we only care about (approximate)

Riemann solution on vertical lines.

If we have source terms, we need to calculate Riemann solution from time 0 to Delta t and average it over the red line

or computing the value at mid-point M

Solution procedure
 $\dot{q} + Aq, x = 0$
 $\dot{q} + Aq, x = 0$
 eigen decomposition:
 $A = \begin{bmatrix} 0 & 1 \\ -E & 0 \end{bmatrix}$
 left eigenvalues
 $(\lambda_1 \dots \lambda_n) A = \lambda (\lambda_1 \dots \lambda_n)$

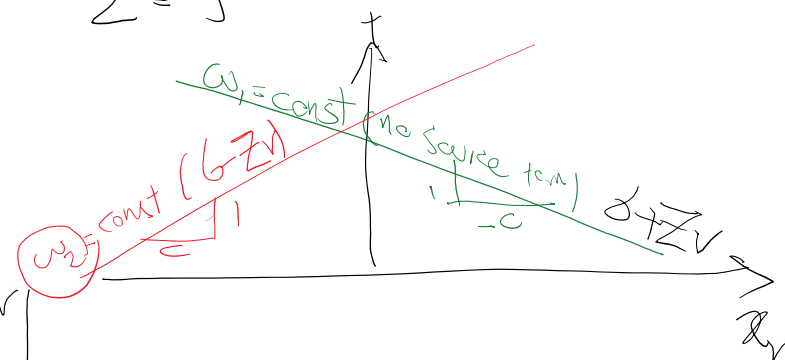
$\begin{bmatrix} \lambda^1 \\ \lambda^2 \end{bmatrix} A = \begin{bmatrix} \lambda^1 \\ \lambda^2 \end{bmatrix} \begin{bmatrix} \lambda^{(1)} \\ \lambda^{(2)} \end{bmatrix}$
 $[LA = \Lambda L]$
 $q + Aq, x = 0$
 premultiply by L
 $(Lq) + \Lambda(Lq), x = 0$
 characteristic parameter ω

$\omega = Lq$
 $\dot{\omega} + \Lambda \omega, x = 0$

L for $A = \begin{bmatrix} 0 & 1 \\ -E & 0 \end{bmatrix}$ is $L = \begin{bmatrix} c\rho & 1 \\ -c\rho & 1 \end{bmatrix}$ & $\Lambda = \begin{bmatrix} c & 0 \\ 0 & -c \end{bmatrix}$

$C = \sqrt{E/\rho}$ ($c\rho \dot{u} - -Eu, x$) $Z = c\rho$ impedance

$\dot{\omega}_1 + \lambda_1 \omega_1, x = 0 \quad \lambda_1 = -c$
 $\dot{\omega}_2 + \lambda_2 \omega_2, x = 0 \quad \lambda_2 = c$



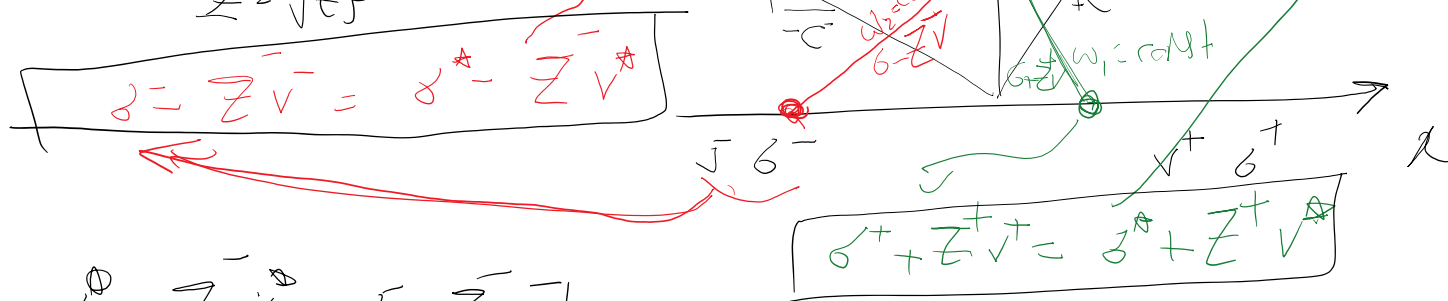
$\begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix} = \begin{bmatrix} Z & 1 \\ -Z & 1 \end{bmatrix} \begin{bmatrix} v \\ \delta \end{bmatrix} = \begin{bmatrix} b + Zv \\ b - Zv \end{bmatrix}$

by using characteristics we can solve the Riemann soln
 $\begin{bmatrix} + \\ - \end{bmatrix} \begin{bmatrix} + \\ - \end{bmatrix}$

$\begin{bmatrix} + \\ - \end{bmatrix} \begin{bmatrix} + \\ - \end{bmatrix} \begin{bmatrix} + \\ - \end{bmatrix}$

by using circ

$$\begin{aligned} \bar{C} &= \sqrt{\bar{E} \bar{P}^-} \\ \bar{Z} &= \sqrt{\bar{E} \bar{P}^-} \end{aligned} \left\{ \begin{array}{l} \bar{P}^- \\ \bar{E} \end{array} \right.$$



$$\begin{aligned} \bar{P}^+ &= \frac{C^+ |E^+|^2}{Z^+} \\ \bar{E} &= \sqrt{\bar{E} \bar{P}^+} \end{aligned}$$

$$\left. \begin{aligned} \delta^- - Z^- v^- &= \delta^+ - Z^- v^+ \\ \delta^+ + Z^+ v^+ &= \delta^+ + Z^+ v^+ \end{aligned} \right\} \rightarrow$$

$$\delta^* = \left(\frac{Z^- \delta^+ + Z^+ \delta^-}{Z^- + Z^+} \right) + \frac{Z^- Z^+}{Z^- + Z^+} (v^+ - v^-)$$

$$v^* = \frac{1}{Z^- + Z^+} (\delta^+ - \delta^-) + \frac{Z^- v^+ - Z^+ v^-}{Z^- + Z^+}$$

if impedances are equal $Z^- = Z^+ = Z$

$$\delta^0 = \left(\frac{\delta^- + \delta^+}{2} \right)$$

$$v^0 = \left(\frac{v^- + v^+}{2} \right)$$

average flux

$$\begin{aligned} &+ \frac{Z}{2} (v^+ - v^-) \\ &+ \frac{1}{2Z} (\delta^+ - \delta^-) \end{aligned}$$

will add to damping matrix

some added jump terms

(3)

General expression of δ^* solutions for this linear PDE:

$$\delta^* = \sum_{\delta^-} \delta^- + \sum_{\delta^+} \delta^+ + \sum_{v^-} v^- + \sum_{v^+} v^+$$

$$v^* = \sum_{\delta^-} \delta^- + \sum_{\delta^+} \delta^+ + \sum_{v^-} v^- + \sum_{v^+} v^+$$

$$\begin{bmatrix} \sum_{\delta^-} \delta^- \\ \sum_{\delta^+} \delta^+ \\ \sum_{v^-} v^- \\ \sum_{v^+} v^+ \end{bmatrix}$$

Similar to ...

Expressions of these coefficients

(A) overage $\left\{ \begin{array}{l} \Sigma_{\sigma^-} = \frac{1}{2} \quad \Sigma_{\sigma^+} = \frac{1}{2} \quad \Sigma_{v^-} = 0 \quad \Sigma_{v^+} = 0 \\ \bar{V}_{\sigma^-} = 0 \quad \bar{V}_{\sigma^+} = 0 \quad \bar{V}_{v^-} = \frac{1}{2} \quad \bar{V}_{v^+} = \frac{1}{2} \end{array} \right. \begin{array}{l} (\sigma^- = (\frac{\sigma^-}{2}) \\ (v^- = (\frac{v^-}{2}) \end{array}$

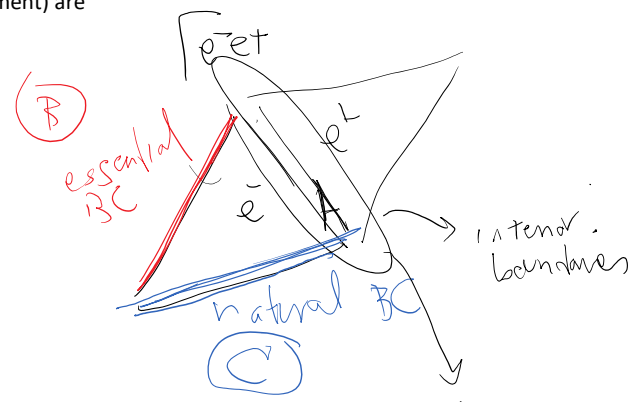
(B) Remain $\left\{ \begin{array}{l} \Sigma_{\sigma^-} = \frac{z^+}{z^+ + z^-} \quad \Sigma_{\sigma^+} = \frac{z^-}{z^+ + z^-} \quad \Sigma_{v^-} = -\frac{z^+ z^-}{z^+ + z^-} \quad \Sigma_{v^+} = -\Sigma_{v^-} \\ \bar{V}_{\sigma^-} = \frac{-1}{z^+ + z^-} \quad \bar{V}_{\sigma^+} = -\bar{V}_{\sigma^-} \quad \bar{V}_{v^-} = \frac{z^-}{z^+ + z^-} \quad \bar{V}_{v^+} = \frac{z^+}{z^+ + z^-} \end{array} \right.$

(4)

We'll talk about star values for nonlinear PDEs later

So, the only two terms that we have not discussed in detail yet in equation (1) (weak statement) are

$$\int_{\partial \Omega} \tilde{U} (-\sigma_n^\ominus) ds + \lambda \int_{\partial \Omega} \hat{\sigma} \cdot n (-v^+ + v^-) ds$$



Case A: Interior of the domain contribution: We'll try to cast it in the form of IP method:

$$\int_{\Gamma_{e^-e^+}} \tilde{U}^- (-\hat{\sigma} \cdot n^-) ds + \lambda \int_{\Gamma_{e^-e^+}} \hat{\sigma} \cdot n^- (-v^+ + v^-) ds + \int_{\Gamma_{e^+e^-}} \tilde{U}^+ (\hat{\sigma} \cdot n^+) ds + \lambda \int_{\Gamma_{e^+e^-}} \hat{\sigma} \cdot n^+ (-v^+ + v^-) ds$$

$\sigma_n^\ominus = \hat{\sigma} \cdot n$
 $n = n^+ n^-$

$$B(\tilde{U}, v) \rightarrow B(\hat{U}, v) = \int_{\Gamma_{e^-e^+}} -(\hat{U}^- n^- + \hat{U}^+ n^+) \sigma^\ominus ds + \int_{\Gamma_{e^-e^+}} [\lambda \hat{\sigma} \cdot n^- (-v^+ + v^-) + \lambda \hat{\sigma} \cdot n^+ (-v^+ + v^-)] ds$$

(5)

Simplify the equation above for 1D case:

$$B_{\Gamma_{e^-e^+}} = [\tilde{U}] \sigma^\ominus + (\lambda \hat{\sigma} \cdot n^- (-v^+ + v^-) + \lambda \hat{\sigma} \cdot n^+ (-v^+ + v^-))$$

(6)

$$B_{free} = \underbrace{\left[\tilde{U} \right]}_{\tilde{J}_U} \delta^{\#} + \underbrace{\left(\tilde{\lambda} \delta \tilde{n}^- (-v_+ v_+) \lambda^T \delta n^+ (-v_+ v_+) \right)}_{\tilde{J}_\delta} \rightarrow \left[\begin{array}{c} \delta^{\#} \\ \delta^{\#} \end{array} \right] \quad (6)$$

Before evaluating equation (6) let's simplify fields from left and right

$$[\Phi] = \phi^- - \phi^+$$

$$U = \begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$\tilde{J}_U \rightarrow v_+ \times \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$\delta = dU \rightarrow \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \dot{a}_1 \\ \dot{a}_2 \end{bmatrix}$$

$$v = \dot{0} = \frac{d}{dt} \left(\begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \right) = \begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \dot{a}_1 \\ \dot{a}_2 \end{bmatrix}$$

$\tilde{v} = \begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \dot{a}_1 \\ \dot{a}_2 \end{bmatrix}$
 $\tilde{x} = \frac{x - x_0}{h}$
 $x = 1$
 $v = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}$
 $\delta = \frac{k}{h} \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}$
 $v^+ = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \dot{a}^+$
 $\delta^+ = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}^+$
 $v^- = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}^-$
 $\delta^- = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}^-$

we need $[\tilde{U}], v^{\pm}, \delta^{\pm}, \tilde{\lambda} \delta \tilde{n}^{\pm}, \lambda^T \delta n^{\pm}$

$$[\tilde{U}] = U \tilde{n}^- + U^+ n^+ = U^- - U^+ = \left(\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) a = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} a$$

$$v^- = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}^- \quad v^+ = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \dot{a}^+$$

$$\tilde{\lambda} \delta \tilde{n}^- = \begin{bmatrix} 0 & \frac{k}{h} \\ 0 & 0 \end{bmatrix} \dot{a}^- \quad \lambda^T \delta n^+ = \begin{bmatrix} 0 & 0 \\ 0 & -\frac{1+k}{h} \end{bmatrix} \dot{a}^+$$

$$\tilde{\lambda} \delta \tilde{n} := \tilde{\lambda} \delta \tilde{n}^- + \lambda^T \delta n^+ = \begin{bmatrix} 0 & \frac{k}{h} \\ 0 & -\frac{1+k}{h} \end{bmatrix} \dot{a}$$

$$\delta^- = \begin{bmatrix} 0 & \frac{k}{h} \\ 0 & 0 \end{bmatrix} \dot{a}^- \quad \delta^+ = \begin{bmatrix} 0 & 0 \\ 0 & \frac{k}{h} \end{bmatrix} \dot{a}^+$$

(7)

Terms for stiffness $\delta^{\#} = \sum_{\delta} \delta^- + \sum_{\delta} \delta^+ + \sum_{v^-} v^- + \sum_{v^+} v^+$

$$\tilde{J}_0 = -[\tilde{U}] \delta^{\#} = - \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \left(\sum_{\delta} \delta + \sum_{v^-} v^- + \sum_{v^+} v^+ \right)$$

$$= \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \left(\sum_{\delta} \begin{bmatrix} 0 & \frac{k}{h} \\ 0 & 0 \end{bmatrix} \dot{a}^- + \sum_{\delta} \begin{bmatrix} 0 & 0 \\ 0 & \frac{k}{h} \end{bmatrix} \dot{a}^+ + \sum_{v^-} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \dot{a}^- + \sum_{v^+} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \dot{a}^+ \right)$$

$\neq 0$ for Remann & these terms will be added

≠ 0 for Remann & these terms will be added

to damping

$$J_u = - \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \left(\underbrace{\Sigma_G \begin{bmatrix} 0 & \frac{k^-}{h^-} & 0 & 0 \end{bmatrix} + \Sigma_G \begin{bmatrix} 0 & 0 & 0 & \frac{k^+}{h^+} \end{bmatrix}}_{\text{goes to } K_{4 \times 4}^I} \right) \mathcal{Q}$$

$$- \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \left(\underbrace{\Sigma_V \begin{bmatrix} 1 & 1 & 0 & 0 \end{bmatrix} + \Sigma_V \begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix}}_{\text{goes to } C_{4 \times 4}^I \text{ interface damping}} \right) \mathcal{Q}$$

□