

Recall that any 2nd order tensor can be decomposed to its symmetric and skew-symmetric parts:

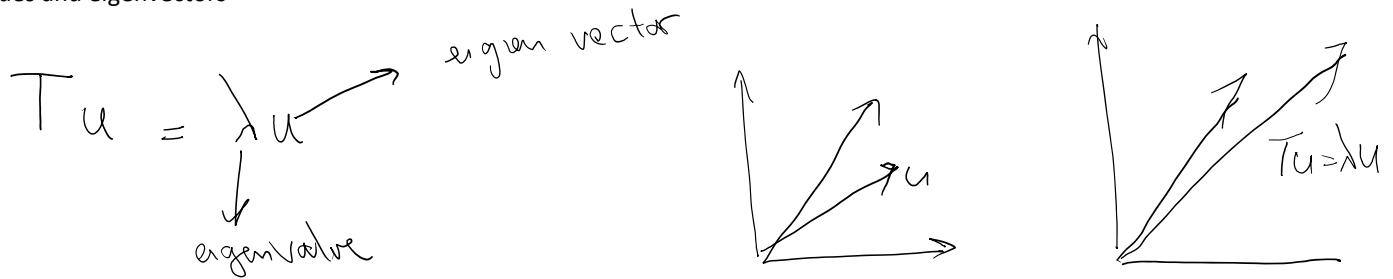
$$T = S + W$$

$$S = \text{Sym}T = \frac{T + T^T}{2}$$

$$W = \text{Skew}T = \frac{T - T^T}{2} \rightarrow \text{small rotation}$$

Today's focus will be on symmetric 2nd order tensors

Eigenvalues and eigenvectors



Assume T is n by n and has n distinct and linearly independent eigenvectors?

$$\left. \begin{aligned} Tu_{(1)} &= \lambda_1 u_{(1)} \\ \vdots \\ Tu_{(n)} &= \lambda_n u_{(n)} \end{aligned} \right\}$$

$$T_{n \times n} u_{(i)} = \lambda_i u_{(i)} \quad \text{no summation on } i$$

$$T \left[\begin{array}{c|c|c|c} u_{(1)} & u_{(2)} & \dots & u_{(n)} \end{array} \right] = \left[\begin{array}{c|c|c|c} \lambda_1 u_{(1)} & \dots & \dots & \lambda_n u_{(n)} \end{array} \right] =$$

$$\underbrace{\left[\begin{array}{c|c|c|c} u_{(1)} & \dots & \dots & u_{(n)} \end{array} \right]}_{\text{eigenvector matrix}} \underbrace{\left[\begin{array}{c} \lambda_1 \\ \dots \\ \dots \\ \lambda_n \end{array} \right]}_{\Lambda = \text{Diag}(\lambda_i) \text{ eigenvalue matrix}}$$

$$TU = U\Lambda \quad \times U^{-1} \text{ (} u_{(i)} \text{'s are linearly independent)}$$

$$\boxed{T = U \Lambda U^{-1}}$$

T is diagonalizable tensor

$$\begin{aligned} T^2 &= (U \Lambda U^{-1})(U \Lambda U^{-1}) = U \Lambda \underbrace{U^{-1}U}_I \Lambda U^{-1} \\ &= U \Lambda^2 U^{-1} = U \begin{bmatrix} \lambda_1^2 & & \\ & \ddots & \\ & & \lambda_n^2 \end{bmatrix} U^{-1} \end{aligned}$$

$$T^{100} = U \Lambda^{100} U^{-1}$$

$$\begin{aligned} e^T &= T + \frac{1}{2!} T^2 + \frac{1}{3!} T^3 + \dots = U \Lambda U^{-1} + \frac{1}{2!} U \Lambda^2 U^{-1} + \dots + \frac{1}{n!} U \Lambda^n U^{-1} \\ &= U \begin{bmatrix} \lambda_1 + \frac{\lambda_1^2}{2!} + \frac{\lambda_1^3}{3!} + \dots & & \\ e^{\lambda_1} & & \\ & \lambda_2 + \frac{\lambda_2^2}{2!} + \dots & \\ & e^{\lambda_2} & \\ & & \lambda_n + \frac{\lambda_n^2}{2!} + \dots \end{bmatrix} U^{-1} \end{aligned}$$

$$e^T = U \begin{bmatrix} e^{\lambda_1} & & \\ & \ddots & \\ & & e^{\lambda_n} \end{bmatrix} U^{-1} = U e^{\Lambda} U^{-1}$$

$$f(T) = U f(\Lambda) U^{-1} = U \begin{bmatrix} f(\lambda_1) & & \\ & \ddots & \\ & & f(\lambda_n) \end{bmatrix} U^{-1}$$

Are all 2nd order tensors diagonalizable?

- If a matrix has n distinct eigenvalues their corresponding eigenvectors are linearly independent

$$\lambda_1 \neq \lambda_2 \neq \dots \neq \lambda_n$$



- Matrix may not be diagonalizable if it has repeated eigenvalues

$$T = \begin{pmatrix} 5 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

algebraic multiplicity = 2

$$\lambda_{1,2} = 3 \quad \lambda_3 = 5$$

eigenspace

$$T = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$\lambda_1 = \lambda_2 = 1 \quad m_A(1) = 2$

it only has 1 eigenvector

$$m_G(1) = 1 \quad \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ a \\ \beta \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

linearly independent

geometric multiplicity = 2

→ In general $T = U J U^{-1}$

$$\begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \dots & \\ & & & \lambda_n \end{bmatrix}$$

repeated

Jordan form

$$A u_{(1)} = \lambda_1 u_{(1)}$$

$$A u_{(2)} = \lambda_2 u_{(2)}$$

$$\vdots$$
$$e_i \cdot e_j = \delta_{ij}$$

$$e_1^* = \frac{u_1}{|u_1|}$$

$$\rightarrow e_2^* = \frac{u_2}{|u_2|}$$

$$A e_1^* = \lambda_1 e_1^*$$

$$A e_2^* = \lambda_2 e_2^*$$

so far as long as all eigenvalues are distinct

What happens when eigenvalues are not distinct

For symmetric matrices even if we have repeated eigenvalues the matrix is diagonalizable and we can choose n (dimension of matrix) orthonormal eigenvectors.

Example:

2D

$$A = \begin{bmatrix} a & b \\ b & d \end{bmatrix}$$

$$\lambda u = Au \Rightarrow \det(A - \lambda I) = 0$$

$$\det \begin{bmatrix} a - \lambda & b \\ b & d - \lambda \end{bmatrix} = 0 \Rightarrow$$

$$\lambda^2 - \underbrace{(a+d)}_{\text{trace } A} \lambda + \underbrace{ad - b^2}_{\det A} = 0$$

$$\Rightarrow \lambda = \frac{(a+d) \pm \sqrt{(a+d)^2 - 4(ad - b^2)}}{2}$$

$$\lambda = \frac{(a+d) \pm \sqrt{(a-d)^2 + 4b^2}}{2} = 0$$

Repeated eigenvalues

$$a = d$$
$$b = 0$$

$$A = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$$

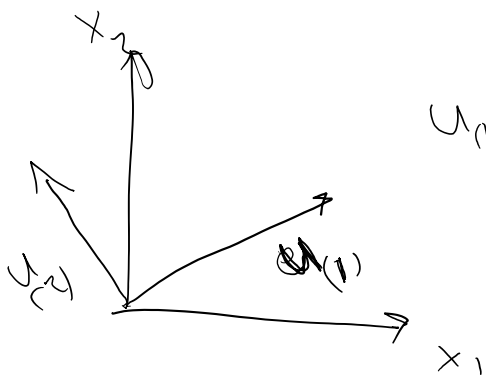
$$\lambda_{1,2} = a$$

Eigenvectors: Any vector in \mathbb{R}^2 is an eigenvector!

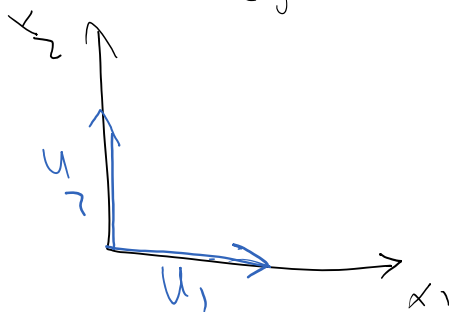
$$A = aI$$

$$Au = (aI)u = au$$

↓
eigenvalue



$$u_{(1)} \perp u_{(2)}$$



3D

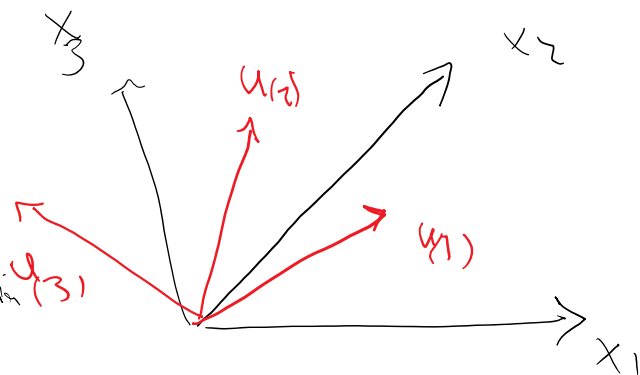
$$A = \begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix}$$

1) $\lambda_1 \neq \lambda_2$ $\lambda_2 \neq \lambda_3$ $\lambda_1 \neq \lambda_3$ distinct eigenvalues

Unique directions for $u(1)$, $u(2)$, $u(3)$ and then having these Normal eigenvectors we can normalize them

$$A u(i) = \lambda_i u(i)$$

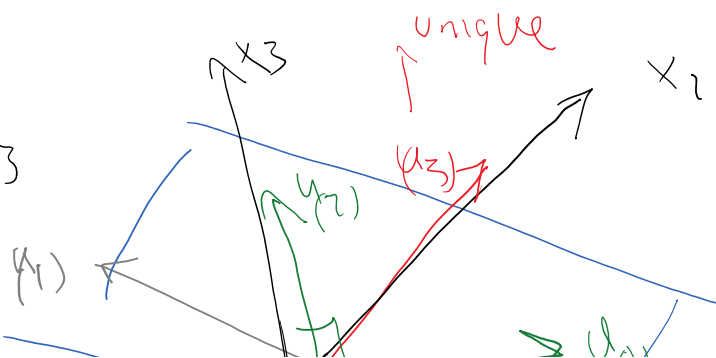
No summation



$$u(i) \cdot u(j) = \delta_{ij}$$

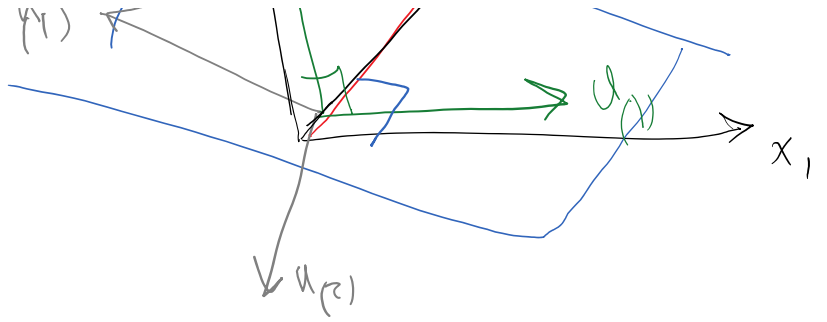
2) $\lambda_1 = \lambda_2$ $\lambda_2 \neq \lambda_3$

∞



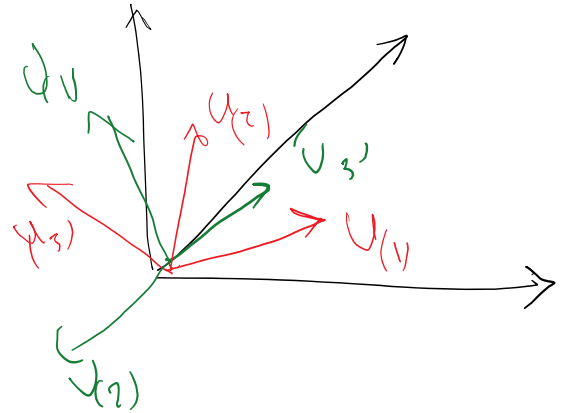
$$T = U \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix} U^{-1}$$

equal



3) $\lambda_1 = \lambda_2 = \lambda_3 = \lambda$

$$T = U^{-1} \underbrace{\begin{pmatrix} \lambda & & \\ & \lambda & \\ & & \lambda \end{pmatrix}}_{\lambda I} U = \begin{pmatrix} \lambda & & \\ & \lambda & \\ & & \lambda \end{pmatrix}$$



How to calculate eigenvalues of a symmetric matrix in 3D?

$$(S - \delta I) u = 0$$

eigenvalue

$$\det(S - \delta I) = 0$$

$$\det \begin{pmatrix} S_{11} - \delta & S_{12} & S_{13} \\ S_{21} & S_{22} - \delta & S_{23} \\ S_{31} & S_{32} & S_{33} - \delta \end{pmatrix} = 0$$

$S_{ij} = S_{ji}$
symmetric

Cayley-Hamilton equation:
 Or characteristic equation of the tensor:

$$-\sigma^3 + I_1 \sigma^2 - I_2 \sigma + I_3 = 0$$

$$I_1 = \text{tr}(\mathcal{S}) = S_{11} + S_{22} + S_{33}$$

$$I_2 = \frac{1}{2} [(\text{tr} \mathcal{S})^2 - \text{tr}(\mathcal{S}^2)] = \frac{1}{2} (S_{ii} S_{jj} - S_{ij} S_{ij})$$

$$I_3 = \det \mathcal{S}$$

We call I_1, I_2, I_3 the invariants of a symmetric second-order tensor

If we have a function of a second order tensor that is objective (does not depend on coordinate frame) then it can be written in terms of eigenvalues of invariants

$$f(\mathcal{S}) = f(\underbrace{S_{11}, S_{22}, S_{33}, S_{12}, S_{23}, S_{31}}_{6 \text{ arguments}})$$

$$= f_{\sigma}(\underbrace{\sigma_1, \sigma_2, \sigma_3}_{3 \text{ arguments}})$$

$$= f_I(\underbrace{I_1, I_2, I_3}_{3 \text{ arguments}}) \text{ that are easier to compute}$$

Related theorem
 Cayley-Hamilton theorem
 A matrix satisfies its characteristic polynomial

$$-\sigma^3 + I_1 \sigma^2 - I_2 \sigma + I_3 \mathbf{1} = \mathbf{0}$$

σ^0

σ^1

σ^2

σ^3

σ^4

σ^5

σ^6

$$-\mathcal{I}_3^3 + \mathcal{I}_2 S^2 - \mathcal{I}_1 S + \mathcal{I}_3 I = 0$$

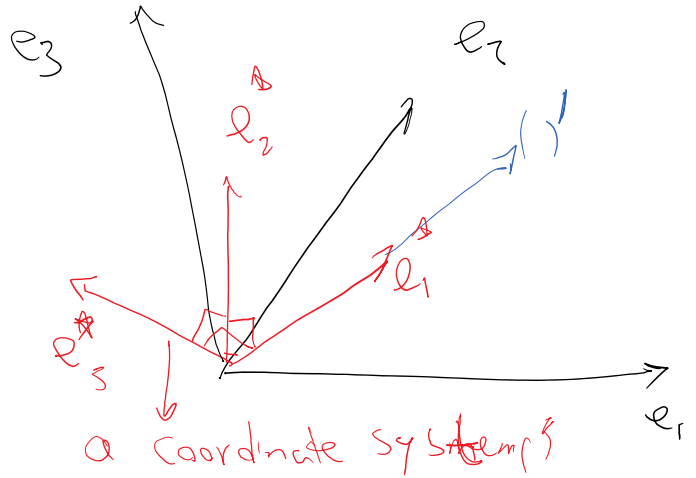
Representation of symmetric tensors

$$S_{ij} = \sigma_i \underline{u}(i)$$

↓
normalize these

$$S e_i^* = \sigma_i e_i^*$$

$$e_i^* \cdot e_j^* = \delta_{ij}$$



$$S'_{ij} = Q_{im} Q_{jn} S_{mn}$$

$$Q = \begin{bmatrix} e_1^* \\ e_2^* \\ e_3^* \end{bmatrix}$$

$$S^* = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix}$$

Representation of a symmetric tensor in its eigenvector coordinate system

$$T_{ij} = e_i \cdot T e_j \quad \text{Recall}$$

$$S'_{ij} = e_i^* \cdot \underbrace{(S e_j^*)}_{\sigma_j e_j^* \text{ no summation}} = \sigma_j \underbrace{e_i^* \cdot e_j^*}_{\delta_{ij}}$$

$$\Rightarrow S'_{ij} = \sigma_j \delta_{ij} \quad \text{no summation on } j$$

$$= 5 \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} + 10 \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$= 5 \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} + 10 \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{15}{2} & -\frac{5}{2} \\ -\frac{5}{2} & \frac{15}{2} \end{pmatrix} \begin{matrix} \rightarrow e_2 \\ \rightarrow e_1 \end{matrix}$$

Example 2

$$S = \sum \sigma_i e_i^* \otimes e_i$$

$$S = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix} \quad \det S = \sigma_1 \sigma_2 \sigma_3$$

$$S^{-1} = \sum \frac{1}{\sigma_i} e_i^* \otimes e_i$$

$$\sigma_1, \sigma_2, \sigma_3 \neq 0$$

$$\begin{bmatrix} \sigma_1 & & \\ & \sigma_2 & \\ & & \sigma_3 \end{bmatrix} \begin{pmatrix} \frac{1}{\sigma_1} & & \\ & \frac{1}{\sigma_2} & \\ & & \frac{1}{\sigma_3} \end{pmatrix} = \mathbb{1}$$

$$\ln S = \sum_{i=1}^3 \ln \sigma_i e_i^* \otimes e_i$$

Positive definite tensors

$$u \cdot T u = u \cdot (\text{Sym} T + \text{Skew} T) u$$

$$\text{sym} T = \frac{T + T^t}{2}$$

$$\text{skew} T = \frac{T - T^t}{2}$$

$$= u \cdot (\text{Sym} T) u + u \cdot (\text{Skew} T) u$$

$$= u_i u_j (\text{Sym} T)_{ij} + \underbrace{u_i u_j}_{\text{sym}} (\text{Skew} T)_{ij} \quad \text{skew sym}$$

\Rightarrow

$$\boxed{U \cdot Tu = U \cdot \underline{\text{Sym}T}u} \quad \star$$

Skew-symmetric part does not contribute

Positive definite tensor T satisfies the following property:

$$\forall u \quad \underline{u \cdot Tu} > 0 \quad \& \quad u \cdot Tu = 0$$

$$\iff u = 0$$

A positive or semi-positive definite tensor satisfies

$$\forall u \quad \underline{u \cdot Tu} \geq 0$$

X

Because of (*) we only need to work with symmetric tensors (i.e. symmetric part of a tensor) when talking about positive definiteness

$$T = \begin{bmatrix} 5 & 0 \\ 0 & 0 \end{bmatrix} \quad \text{not p. def}$$

$$\begin{bmatrix} 5 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \neq 0$$

$$T = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} \quad u \cdot Tu = u_1^2(5) + u_2^2(3) > 0$$

$$= 0 \text{ iff } \bar{u} = 0$$

$$T = \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix} \quad u \cdot Tu = 5u_1^2 - 3u_2^2 \not\geq 0$$

$$I = \begin{bmatrix} 0 & -3 \end{bmatrix}$$

$$u \cdot I u = 5u_1 - 3u_2 \neq 0$$

$$j = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

side not

~~is~~ pos def

$$\|u\|_T = \sqrt{u \cdot T u}$$

this is a norm