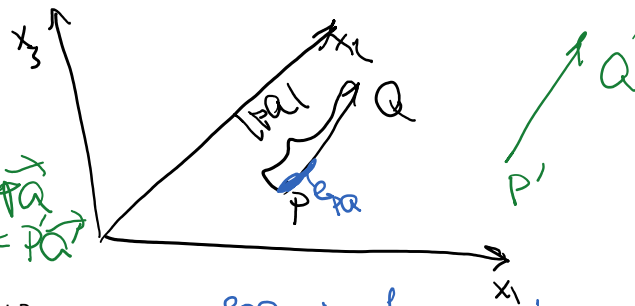


Vector spaces

Vector PQ is identified by 3 things:

1. Length of PQ: $|PQ|$
2. Direction of PQ: e_{PQ}

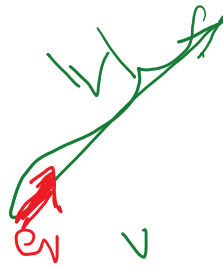
] okem $\vec{PQ} = \vec{PA}$



e_{PQ} is of length 1 & direction of PQ

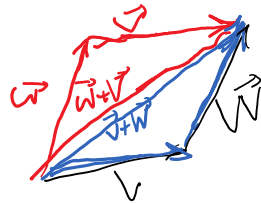
3. Sometimes we also care about base point P (often we don't care about this).
If we differentiate vectors by their base point as well, they are called bound vectors

non-bound vectors



$$e_v = \frac{\vec{v}}{|v|}$$

Addition



$$\vec{w} + \vec{v} = \vec{v} + \vec{w}$$

Scalar product

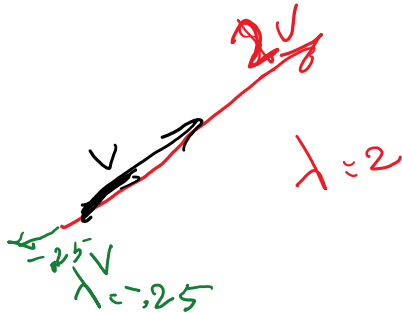
$$\lambda \in \mathbb{R}$$

$$\vec{v}$$

$$\lambda \vec{v} :$$

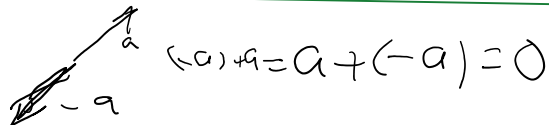
$$|\lambda \vec{v}| = |\lambda| |\vec{v}|$$

$$e_{\lambda \vec{v}} = \begin{cases} e_v & \lambda > 0 \\ -e_v & \lambda < 0 \\ = & \lambda = 0 \end{cases}$$



$$-a := (-1)a$$

$$a - b = a + (-b)$$



$$a - b = a + (-b)$$

Properties of vectors

- need to be proved for any vector space
- A1) $\vec{a} + \vec{b} = \vec{b} + \vec{a}$ commutative Addition
- A2) $\vec{a} + (\vec{b} + \vec{c}) = (\vec{a} + \vec{b}) + \vec{c}$ associative
- A3) $\vec{a} + \vec{0} = \vec{0} + \vec{a} = \vec{a}$ neutral member w.r.t addition

Vector space is an Abelian group w.r.t +

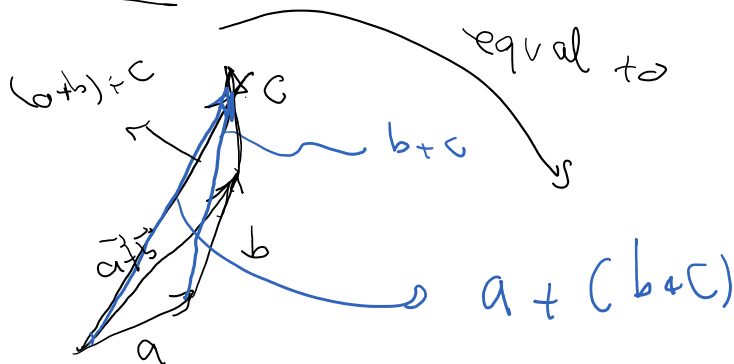
Proved

$$\forall a \exists (-a) \ni a + (-a) = (-a) + a = 0$$

It's not added as an axiom of vector space

B) Scalar properties $\lambda, \mu \in \mathbb{R}$, a, b vectors

- B1) $(\mu\lambda)a = \mu(\lambda a)$ scalar product property
- B2) $(\lambda + \mu)a = \lambda a + \mu a$ distributive with respect to scalar addition
- B3) $\lambda(a + b) = \lambda a + \lambda b$ " " " " vector addition
- B4) $1 \cdot a = a$



show this

$0 \cdot a = 0$

scalar zero zero vector

$a + 0 \cdot a$

 $= 1 \cdot a + 0 \cdot a = (1+0) \cdot a = 1 \cdot a = a$

B4 B4

$a = 1 \cdot a$

$1 \cdot a = a$

B4

must be zero

why

 $a + (-1)a = 0$

def.

 $1 \cdot a + (-1)a = (1 + (-1))a = 0 \cdot a = 0$

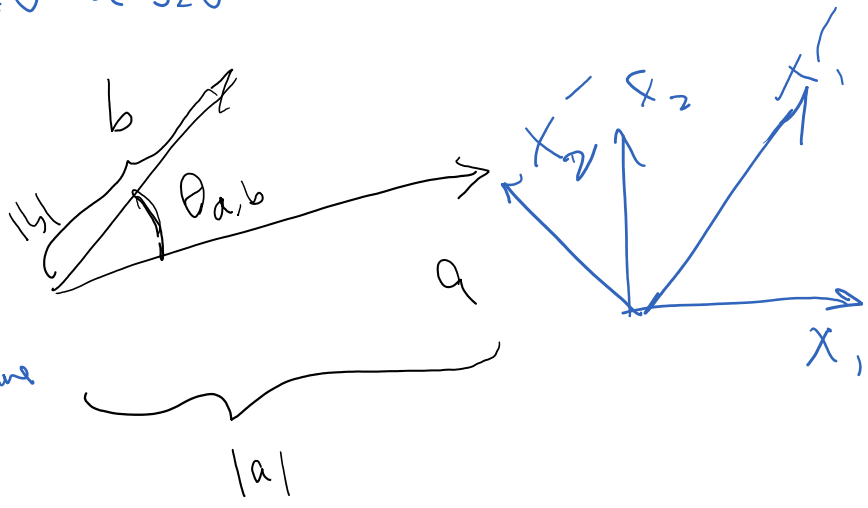
B4

Inner product of vectors

$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta_{a,b}$

good definition for any coordinate system (defined later) we get the same value

if $r > 0$ or $b = 0$ or $a \cdot b > 0$

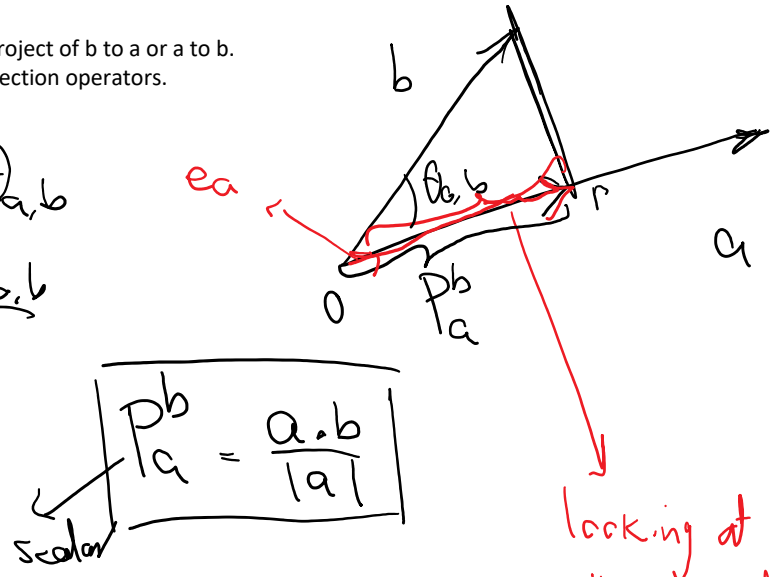


We use inner product to compute the project of b to a or a to b. In general we use inner product for projection operators.

$$p_a^b = |b| \cos \theta_{a,b}$$

$$= \frac{|a| |b| \cos \theta_{a,b}}{|a|}$$

$$= \frac{a \cdot b}{|a|}$$



this a vector
of length $\frac{pb}{|a|}$
oriented in a

$$\vec{p}_a^b = \frac{\vec{b} \cdot \vec{a}}{|\vec{a}|^2} \vec{a} = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|^2} \vec{a}$$

$$\vec{p}_a^b = \left(\frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \right) \vec{a} = \left(\frac{\vec{a} \cdot \vec{b}}{|\vec{a}|^2} \right) \vec{a}$$

A few examples:

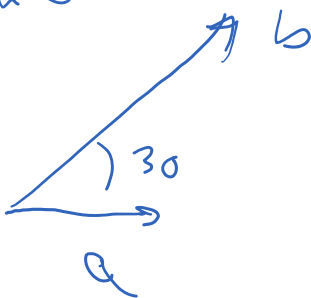
1)

$$\theta_{a,b} = 0$$



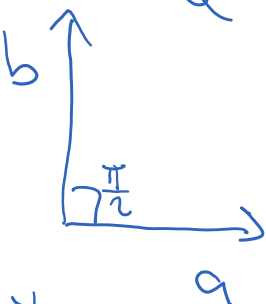
$$a \cdot b = |a||b| \cos \theta_{a,b} = |a||b|$$

a is aligned with b



$a \cdot b$ gets smaller

2) $\theta = \frac{\pi}{2}$

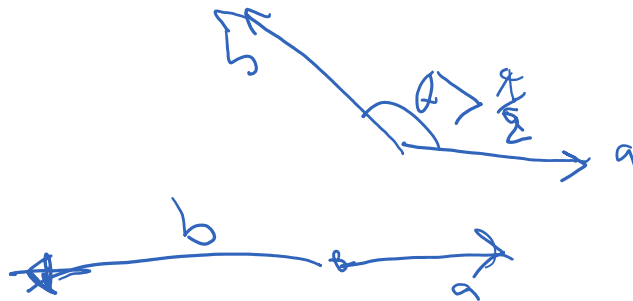


$$a \cdot b = |a||b| \cos \frac{\pi}{2} = 0$$

$$\theta = \frac{\pi}{2} \Leftrightarrow a \cdot b = 0$$

$a \perp b$

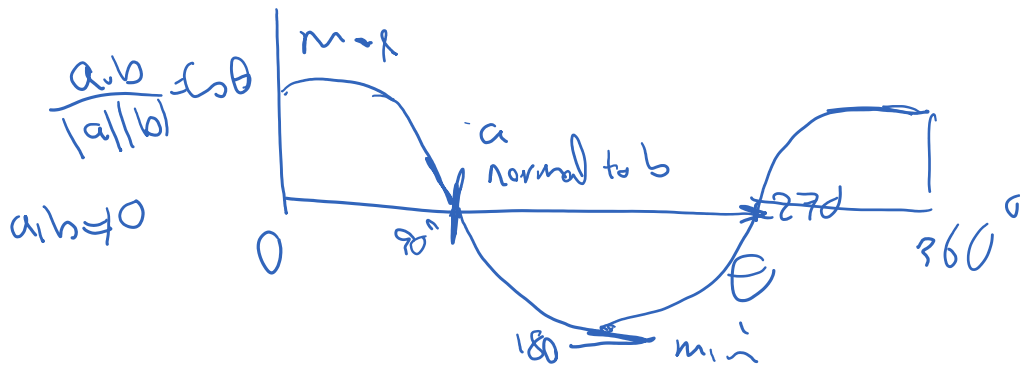
3) $\theta = \pi$



$a \cdot b < 0$
 $\cos \theta < 0$

$$a \cdot b = |a||b| \cos \pi = -|a||b|$$

$$a \cdot b = |a||b| \cos \theta \Rightarrow |a||b|$$



Properties of inner product:

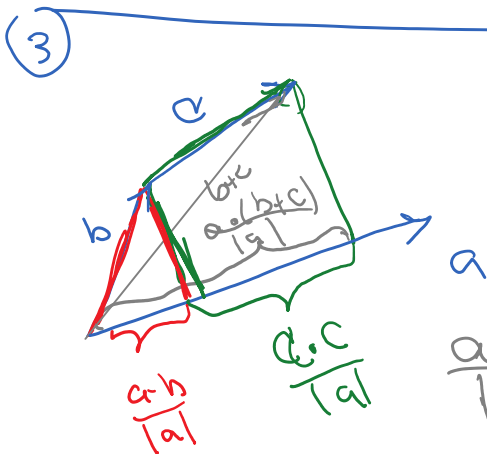
1) $a \cdot b = b \cdot a$

2) $a \cdot (\lambda b) = \lambda(a \cdot b)$ scalar property

3) $a \cdot (b+c) = a \cdot b + a \cdot c$
distributive with respect to vector addition

① $b \cdot a = |b||a| \cos \theta_{ba}$
 $= |a||b| \cos 360^\circ - \theta_{a,b}$
 $= |a||b| \cos \theta_{a,b} = a \cdot b$

② $a \cdot b = |a||b| \cos \theta_{a,b}$
 $= |a||b| \cos \theta_{a,b}$
 show $= \lambda |a||b| \cos \theta_{a,b}$
 $= \lambda a \cdot b$
 each case
 $a \cdot (\lambda b) = \lambda(a \cdot b)$



$$\frac{a \cdot (b+c)}{|a|} = \frac{a \cdot b}{|a|} + \frac{a \cdot c}{|a|}$$

→ we get property 3

Note about HW1

5. (20 Points) Show that the components of the inverse of a matrix satisfy,

$$A^{-1} \begin{pmatrix} 1 & & \\ & 1 & \\ & & \ddots \end{pmatrix} = I$$

5. (20 Points) Show that the components of the inverse of a matrix satisfy,

$$A_{rk}^{-1} = \frac{1}{2 \det A} \epsilon_{ijk} \epsilon_{pqr} A_{ip} A_{jq} \quad (6)$$

Hint: Compute $A_{rk}^{-1} A_{km}$.

This is very important

$$= (A^{-1} A)_{rm} = \delta_{rm}$$