https://rezaabedi.com/teaching/continuum-mechanics/

Course assignments are mostly from TAM551.pdf

Abeyaratne_Brief Review of Some Mathematical_ElasticSolids-Vol.1-Math.pdf Abeyaratne_Continuum Mechanics_RCA_Vol_II.pdf

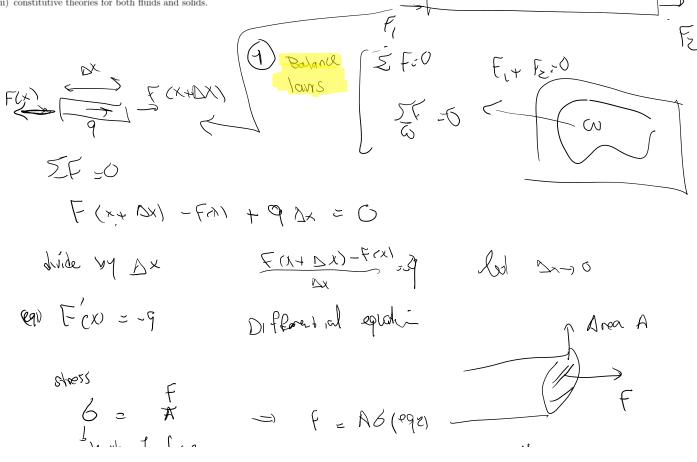
Grade breakdown: Mostly HW assignments plus a term project

9 HW assignments (about 80%)

Term project 1: Includes (About equal weights are allocated to each part)

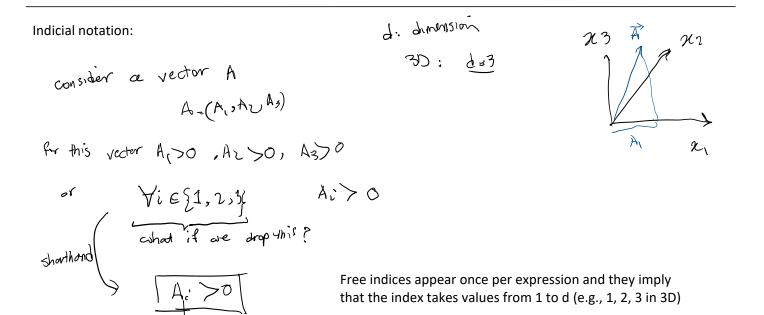
- 1) An up to 4 pages paper/proposal(including references if any) on a topic related to continuum mechanics. The format of the document is either that of a
 - 0 Research article mostly focusing on introducing a topic of interest and presenting related results. Suggested sections are abstract, introduction, formulation, results (can present results from existing literature, doesn't need to be from your own research), conclusion.
 - O Research proposal that basically introduces a problem, discusses current state of the art and research gaps, and finally proposes a new approach to address the mentioned research gaps, and infan by proposed a new approach to address the infinite of the art and research gaps, and infan proposed a new approach to address the infinite of the research gaps. Suggested sections are (abstract), introduction (why this problem is important and what is the main contribution of the proposed work), background (state of the art and what are the existing gaps and challenges), objective (describing the goal and objectives of the research), research tasks (what is proposed to be done). Some optional sections are intellectual merits and broader impacts as often required in research proposals.
- 2) Presentation of the article on the "Presentation day". Each student will have about 15 minutes to present the material in the article (and related to it) to the entire class.

- (i) kinematics (geometrical description of deformation);
- (ii) basic balance laws; and
- (iii) constitutive theories for both fluids and solids.



First section: Mathematical background: - Indicial notation

- Vector spaces
- vector space
- <mark>Tensors</mark>



riee muices appear once per expression and mey imply that the index takes values from 1 to d (e.g., 1, 2, 3 in 3D)

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We deal with addition and subtractions of terms as follows:

$$\frac{1}{\sqrt{ie\xi 1,2,3}} = \frac{a_i}{a_i} + A_{ij}b_{j} + C_{i2}d_2 = \frac{1}{\sqrt{k}}\frac{d_{i'k}}{d_{k'k}} + \cos(e_i) + \frac{1}{\sqrt{k}} + \frac{5}{\sqrt{k}}$$

i appears just once in all the terms in this expression + b_{ik}b_{i} + b_{ik}b_{i}

Other examples:

The following expression does not make sense

Examples of vector operations and products

Examples of vector operations and products

$$\vec{a}_{s}\vec{b} = \vec{b}_{i}$$
 $\vec{a}_{i} = \vec{b}_{i}$ $(a_{i} \cdot \vec{b}_{i})$
 $\vec{a}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} b_{1} \\ b_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ b_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{2} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{3} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{1} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{1} \\ b_{3} \end{bmatrix}$ $\vec{b}_{s} = \begin{bmatrix} a_{1} \\ a_{1} \\ b_{2} \end{bmatrix}$ $\vec{b}_{1} \end{bmatrix}$ $\vec{b}_{1} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{1} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{1} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{1} = \begin{bmatrix} a_{1} \\ a_{2} \\ a_{3} \end{bmatrix}$ $\vec{b}_{$

$$a^{\dagger} b + [a_{1} a_{2} a_{3}]_{us} \begin{bmatrix} a_{1} b_{1} \\ b_{3} a_{1} b_{1} \\ \hline a_{1} b_{2} a_{1} b_{1} \\ \hline a_{2} b_{2} a_{2} b_{3} \\ \hline a_{2} b_{3} a_{2} b_{3} \\ \hline a_{3} b_{3} a_{3} b_{3} \\ \hline a_{3} b$$

$$b = Aa$$

$$verter matrix (coeptid etter)
$$b_{1} = \begin{pmatrix} b_{1} \\ b_{2} \\ b_{3} \end{pmatrix} = \begin{pmatrix} A_{1} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{33} \\ A_{22} & A_{33} & A_{33} \\ A_{23} & A_{33} & A_{33} \\ A_{33} & A_{33} & A_{$$$$

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b. Aa
b. Aa
c = Bb

$$(C_i = Bi_j b_j)$$

 $(C_i = Bi_j b_j)$
 $(C$