

From last time

For interior boundaries

$$R_{\Gamma e^+}(\hat{T}, T) = \int_{\Gamma e^+} \hat{T}_1 \, ds + \varepsilon \int_{\Gamma e^+} \hat{T}_2 \, ds$$

$$= \int_{\Gamma e^+} \llbracket \hat{T} \rrbracket \cdot \hat{q} \, ds + \varepsilon \int_{\Gamma e^+} (\llbracket \hat{q} \rrbracket^T - \llbracket \hat{q} \rrbracket) \{T\} - \{\hat{q}\} \llbracket T \rrbracket \, ds$$

$$R_{\Gamma e^+}(\hat{T}) = \varepsilon \int_{\Gamma e^+} (\llbracket \hat{q} \rrbracket) (T^* - \{T\}) - \{\hat{q}\} \llbracket T \rrbracket \, ds + \int_{\Gamma e^+} \llbracket \hat{T} \rrbracket \hat{q} \, ds$$

Interior terms (I)

Next, we'll discuss the star value options:

The star values for elliptic and parabolic equations are generally the same.

Now, we are solving an elliptic PDE without the $C\dot{T}$

Read Arnold 2000 and 2002 papers

Local Discontinuous Galerkin (LDG) Fluxes
Cockburn & Shu

$$q^* = \{q\} + \beta \llbracket q \rrbracket + K \alpha \llbracket T \rrbracket$$

$$T^* = \{T\} + \gamma \llbracket T \rrbracket$$

(1)

has a stabilization effect.

Previously, we used average fluxes for the parabolic heat conduction problem.

Here we are solving an elliptic PDE ($C\dot{T}$ is absent from the PDE). So, we need to use elliptic fluxes.

Formula 1 is a general form of star values for elliptic PDEs

Method	$h_\sigma^e K$	$h_u^e K$
Bassi-Rebay 1	$\{\sigma_h\}$	$\{u_h\}$
Brezzi et al. 1	$\{\sigma_h\} - \eta^e \{r_e(\llbracket u_h \rrbracket)\}$	$\{u_h\}$
LDG	$\{\sigma_h\} - \eta^e \llbracket u_h \rrbracket + \beta^e \llbracket \sigma_h \rrbracket$	$\{u_h\} + \gamma^e \llbracket u_h \rrbracket$
IP	$\{\nabla u_h\} - \eta^e \llbracket u_h \rrbracket$	$\{u_h\}$
Bassi-Rebay 2	$\{\nabla u_h\} - \eta^e \{r_e(\llbracket u_h \rrbracket)\}$	$\{u_h\}$
Baumann-Oden	$\{\nabla u_h\}$	$\{u_h\} - \llbracket u_h \rrbracket \cdot n_K$
Babuška-Zlámal	$-\eta^e \llbracket u_h \rrbracket$	$u_h _K$
Brezzi et al. 2	$-\eta^e \{r_e(\llbracket u_h \rrbracket)\}$	$u_h _K$

$$T \rightarrow u$$

$$\nabla u \rightarrow \sigma \quad (K\sigma = q)$$

$\eta \llbracket T \rrbracket$ is an operator on $\llbracket T \rrbracket$

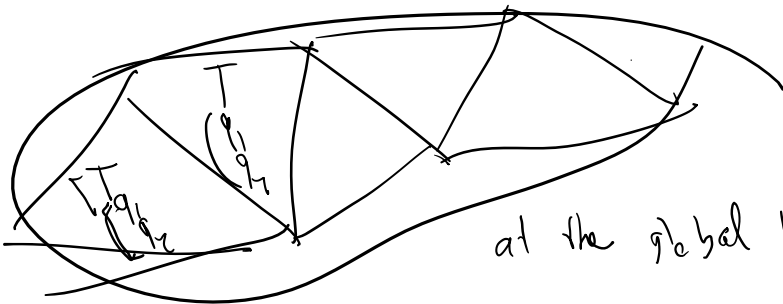
a simple choice is like above

$$\eta(\llbracket T \rrbracket) = \alpha \llbracket T \rrbracket$$

Why not have a term like $\langle q \rangle$ in T^*

$$T^* = \{T\} + \delta\{T\} - \langle q \rangle$$

If we don't have this term (which is the case) through a lengthy process for 2-field formulations where T & q are both primary solution unknowns q can be condensed out from the global system

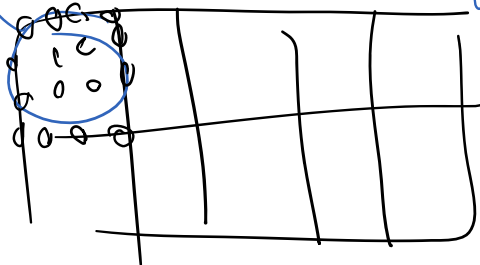


$$T^* = \{T\} + \delta\{T\} - \langle q \rangle$$

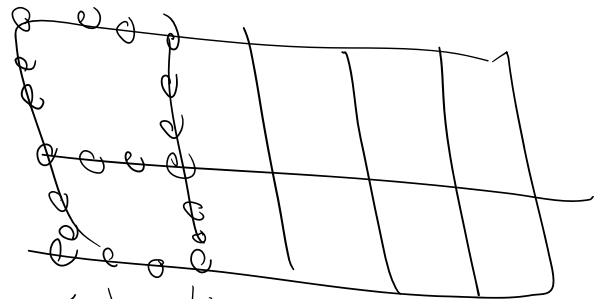
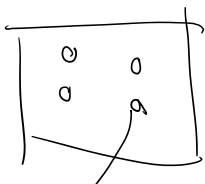
at the global level we only deal with

unknowns of T ($\frac{1}{3}$ of all d.o.f. in 2D if T & q have the same polynomial order) \rightarrow we go back to elements after T is solved & locally solve for each element's q .

Similar to CFEM static condensation
get rid of inside dot for global solve



each element



Solve this

$p_m \rightarrow$ these dets

Flux equation: The effect of each term

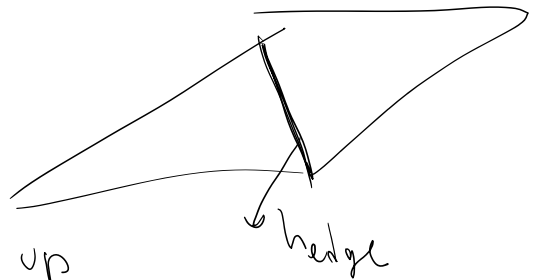
$$q^* = \{q\} + \vec{\beta} [\![q]\!] + k \alpha \left(\frac{m_0}{h} \right)$$

$[q]$ = physical dimension

$$[\alpha] = \frac{[q]}{[\frac{m_0}{h}]} = \frac{[q][T]}{[k][T]} = \frac{1}{L} \quad q = -k \nabla T$$

α has the dimension of $\frac{1}{\text{length}}$

$$\alpha = \frac{\eta_0}{h}$$



there are so many choices to come up with a length scale from the two neighboring elements.
 Easier one is $h = \frac{L}{n_{\text{edge}}}$

What should be chosen for η_0 for Elliptic PDEs?

TABLE 6.1
Properties of the DG methods

Method	cons.	a.c.	stab.	type	cond.	H^1	L^2
Brezzi et al. [18]	✓	✓	✓	α^r	$\eta_0 > 0$	h^p	h^{p+1}
LDG [35]	✓	✓	✓	α^r	$\eta_0 > 0$	h^p	h^{p+1}
IP [43]	✓	✓	✓	α^j	$\eta_0 > \eta^*$	h^p	h^{p+1}
Bassi et al. [10]	✓	✓	✓	α^r	$\eta_0 > 3$	h^p	h^{p+1}
NIPG [53]	✓	x	✓	α^j	$\eta_0 > 0$	h^p	h^p
Babuška-Zlámal [6]	x	x	✓	α^j	$\eta_0 \approx h^{-2p}$	h^p	h^{p+1}
Brezzi et al. [19]	x	x	✓	α^r	$\eta_0 \approx h^{-2p}$	h^p	h^{p+1}
Baumann-Oden ($p=1$)	✓	x	x	-	-	x	x
Baumann-Oden ($p \geq 2$)	✓	x	x	-	-	h^p	h^p
Bassi-Rebay [9]	✓	✓	x	-	-	$[h^p]$	$[h^{p+1}]$

interior penalty
only
T is interpenetrable

condition for stability

*s from ①
 $\eta_0 > 0$
 T & q are interpenetrable and q can be condensed out from the global system

$\vec{\gamma}$ & $\vec{\beta}$ are two user defined vectors.

- They can change point-to-point
- Generally $\vec{\gamma} = -\vec{\rho}$

As we'll see one choice of these values results in alternating fluxes.

For now, I choose these values to be zero

$$\textcircled{2} \quad \begin{cases} \mathbf{q}^{\text{sp}} = \{ \hat{\rho} + \bar{\alpha} [\mathbf{T}] \} & \bar{\alpha} = \alpha \mathcal{K}, \alpha = \frac{\eta_0}{h} \\ \mathbf{T}^{\text{sp}} = \{ \mathbf{T} \} \end{cases}$$

Recall

$$R(\hat{\mathbf{T}}, \mathbf{T}) = B_{\Gamma_{\text{ext}}}(\hat{\mathbf{T}}, \mathbf{T}) + \varepsilon \int_{\Gamma_{\text{ext}}} [\hat{\mathbf{T}}] (\mathbf{T}^{\text{sp}} - \{ \mathbf{T} \}) - \{ \hat{\rho} \} [\mathbf{T}] ds$$

$$+ \int_{\Gamma_{\text{ext}}} [\hat{\mathbf{T}}] \mathbf{q}^{\text{sp}} ds$$

\rightarrow from \mathbf{q}^{sp}

for average $\bar{\alpha} > 0$ option we have:

$$B_{\Gamma_{\text{ext}}}(\hat{\mathbf{T}}, \mathbf{T}) = \int_{\Gamma_{\text{ext}}} [\hat{\mathbf{T}}] (\{ \hat{\rho} \} + \bar{\alpha} [\mathbf{T}]) ds + \varepsilon \int_{\Gamma_{\text{ext}}} - \{ \hat{\rho} \} [\mathbf{T}] ds$$

$$B_{\Gamma_{\text{ext}}}(\hat{\mathbf{T}}, \mathbf{T}) = \int_{\Gamma_{\text{ext}}} [\hat{\mathbf{T}}] \bar{\alpha} [\mathbf{T}] ds + \int_{\Gamma_{\text{ext}}} [\hat{\mathbf{T}}] \{ \hat{\rho} \} - \varepsilon \{ \hat{\rho} \} [\mathbf{T}] ds$$

$\textcircled{3}$ interior integral bilinear form for average $\bar{\alpha} > 0$ choice (2)

Interior term

2 field formulation:

$$R_i(\hat{\mathbf{T}}, \mathbf{T}) = \int (-\nabla \hat{\mathbf{T}} \mathbf{q} - \hat{\mathbf{T}} \mathbf{Q}) ds + \int_V \hat{\mathbf{q}} (\mathbf{q} + \mathcal{K} \nabla \mathbf{T}) dv$$

let's just continue with 1 field

\mathbf{T} & \mathbf{q} are interpolated

let's just continue with a field

T & q are interpolated

$$B_i(\hat{T}, T) = \int_e \nabla \hat{T} \cdot \nabla T \, dv - \int_e \hat{T} q \, ds$$

$\underbrace{\int_e \nabla \hat{T} \cdot \nabla T \, dv}_{\text{goes to the bilinear for } \dots}$
 $\underbrace{\int_e \hat{T} q \, ds}_{\text{goes to the RHS}}$

for LDG

for a field (eg. IP) we only have T and this term is dropped

$$B_i^e(\hat{T}, T) = \int_e \nabla \hat{T} \cdot \nabla T \, dv + \text{for 2 field}$$

$$L_i^e(\hat{T}) = \int_e \hat{T} q \, ds$$

(4)

$$B(\hat{T}, T) = L(\hat{T})$$

$$B(\hat{T}, T) = \sum_e B_i^e(\hat{T}, T) + \sum_{\partial e_j} B_u^e(\hat{T}, T) + \sum_{\substack{\partial e^+ \\ \partial e^-}} B_f^e(\hat{T}, T)$$

interior nodes

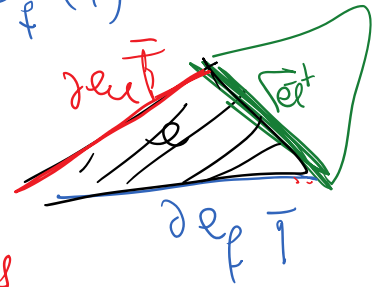
$$L(\hat{T}) = \sum_e L_i^e(\hat{T}) + \sum_{\partial e_u} L_u^e(\hat{T}) + \sum_{\partial e_f} L_f^e(\hat{T})$$

$$B_i^e = \int_e -\nabla \hat{T} \cdot \nabla T \, ds \quad L_i^e = \int_e \hat{T} q \, ds$$

$$B_u^e = \int_{\partial e_u} (\hat{T} q - \epsilon T \hat{q}) \, ds \quad L_u^e(\hat{T}) = -\epsilon \int_{\partial e_u} \hat{q} n \hat{T} \, ds$$

$$B_f^e = 0 \quad L_f^e(\hat{T}) = \int_{\partial e_f} \hat{T} \hat{q} \, ds$$

$$B_{\text{int}}^e = \int_e [\hat{T}](\hat{q} \hat{q} + \alpha [T]) \, ds - \epsilon \int_e [\hat{q}] [\hat{T}] \, ds \quad \text{eq 3}$$



(5)

TABLE 4.1
 Bilinear forms restricted to $V_h \times V_h$ for some DG methods.

Method	$B_h(u, v)$
Bassi-Rebay [9]	$(\nabla_h u + R(u), \nabla_h v + R(v))$
Brezzi et al. [18]	$(\nabla_h u + R(u), \nabla_h v + R(v)) + \alpha^r(u, v)$
LDG [35]	$(\nabla_h u + R(u) + L_\beta(u), \nabla_h v + R(v) + L_\beta(v)) + \alpha^j(u, v)$
IP [43]	$(\nabla_h u, \nabla_h v) + (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^j(u, v)$
Bassi et al. [10]	$(\nabla_h u, \nabla_h v) + (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^r(u, v)$
Baumann-Oden [12]	$(\nabla_h u, \nabla_h v) - (R(u), \nabla_h v) + (\nabla_h u, R(v))$
NIPG [53]	$(\nabla_h u, \nabla_h v) - (R(u), \nabla_h v) + (\nabla_h u, R(v)) + \alpha^j(u, v)$
Babuška-Zlámal [6]	$(\nabla_h u, \nabla_h v) + \alpha^j(u, v)$
Brezzi et al. [19]	$(\nabla_h u, \nabla_h v) + \alpha^r(u, v)$