

$u, v, \frac{g \cdot \nabla u}{2}$, Tangential strain

$$\int_V \hat{V} (\rho \dot{v} + \text{div} - \nabla \cdot \sigma - s) dV - \int_{\partial e} \hat{V} (\sigma_n^* - \sigma \cdot n) ds$$

$$- \varepsilon \left(\int_{\partial e} \hat{\sigma} \cdot n (v^* - v) ds + \int_e \hat{\sigma} : (C^{-1} \hat{\sigma} - \nabla v) \right)$$

$$+ \alpha \int \hat{u} (\dot{u} - v) \Rightarrow$$

$\sigma = C \varepsilon \rightarrow \varepsilon = C^{-1} \sigma$

2 field formulation: $\delta = C \rho \dot{u} = \rho C \nabla u$ wave
 $[C (\frac{\nabla u + \nabla u^T}{2})]$ solid mechanics

u, v mass matrix

$$\int_V \rho \dot{v} dV + \frac{1}{2} \int_V \hat{u} \rho \dot{u} dV + \int_V (\hat{V} \text{div} + \nabla \hat{V} \cdot \sigma) dV$$

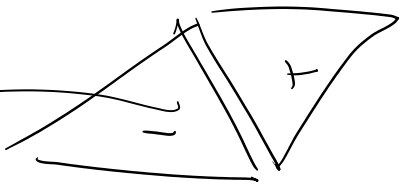
$$- \int_{\partial e} (\hat{V} \sigma_n^* - \varepsilon \hat{\sigma} \cdot n (v^* - v)) ds = \int_V \hat{V} s dV$$

$f(x)$

$$\frac{\tau}{T} = \frac{h}{c} \quad \alpha = \left(\frac{h}{c}\right)^2$$

$\sigma_n = \sigma \cdot n \hat{g}$ v^* now depend on $\delta^T = C \nabla u^T$ & v^T
 it does not involve any \dot{a}

$$\bar{u}(x) = \bar{H}_u(x) U(t)$$

$$= [\bar{u}_1(x) \ \bar{u}_2(x) \ \dots \ \bar{u}_n(x)] \begin{bmatrix} \bar{u}_1(t) \\ \bar{u}_2(t) \\ \vdots \\ \bar{u}_n(t) \end{bmatrix}$$


$$\bar{V}(x) = \bar{H}_v(x) V(t)$$

$$= [\bar{V}_1(x) \ \dots \ \bar{V}_n(x)] \begin{bmatrix} \bar{V}_1(t) \\ \bar{V}_2(t) \\ \vdots \\ \bar{V}_n(t) \end{bmatrix}$$

$$= \begin{bmatrix} \bar{V}_1(x) & \dots & \bar{V}_n(x) \end{bmatrix} \begin{bmatrix} v_2 \\ \vdots \\ v_n \end{bmatrix} (t)$$

$$a = \begin{bmatrix} v_1(t) \\ \vdots \\ v_n(t) \end{bmatrix}$$

Since v is now interpolated, there is no contribution to damping matrix when dealing with star values \Rightarrow we'll end up with block diagonal matrix equations

$$M \ddot{a} + \underline{f(a)} = F$$

linear in $f(a) = Ka$

Forward Euler $M \left(\frac{a_{n+1} - a_n}{\Delta t} \right) + \underline{f(a_n)} = F_n$

$$M a_{n+1} = M a_n + \Delta t f(a_n) - F_n$$

\downarrow block diagonal

\downarrow don't need to

we can solve it one element at a time

$M a_{n+1} = -RHS$ all from time step n



side note

$$\Pi = U - W_{\text{external work}}$$

$$= \frac{1}{2} \int \sigma \epsilon - \int p$$

energy

solution

Dynamic AC

$$\rho \ddot{u} + d \dot{u} - \nabla \cdot \sigma = s$$

steady state ($\dot{} = 0$)

$$-\nabla \cdot \sigma = s$$

$s = p b$

Elliptic

fixed frequency

$$u(x,t) = U(x) e^{i\omega t}$$

$$b(x,t) = \sum U(x) e^{i\omega t}$$

$$e^{i\omega t} (\rho U \omega^2 + d U \omega - \nabla \cdot \Sigma(U)) = e^{i\omega t} S(x)$$

$$-\rho U \omega^2 + i\omega d U - \nabla \cdot \Sigma = S(x)$$

DC elliptic PDE

- Helmholtz equation is indeterminate (eigen values of stiffness are both positive & negative)
- solution is highly oscillatory

Solution is highly \circ

$$\left. \begin{aligned} U^\star &= \{ U \} \\ \Sigma^\star &= \{ \Sigma \} + \frac{\tau_0 c}{h} [U] \end{aligned} \right\}$$

free elliptic fluxes don't work well

$$\delta^\star = \{ \delta \} - \frac{\mathbb{Z}}{2} (v^+ - v^-)$$

Riemann

$$v^\star = \{ v \} - \frac{1}{2\mathbb{Z}} (\delta^+ - \delta^-)$$

solution

$$v = \dot{u}$$

$$V(x) = i\omega U(x)$$

$$\left. \begin{aligned} \Sigma^\star &= \{ \Sigma \} - \frac{\mathbb{Z} i\omega}{2} (U^+ - U^-) \\ U^\star &= \{ U \} - \frac{1}{2\mathbb{Z} i\omega} (\Sigma^+ - \Sigma^-) \end{aligned} \right\}$$

We can use these fluxes for Helmholtz equation

Spacetime balance laws

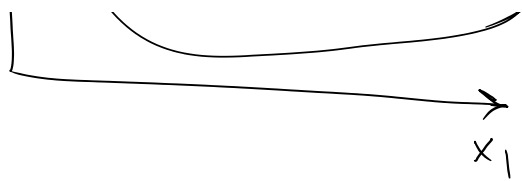
Steady state balance laws

$$\int_{\partial\omega} f_{\text{on } \partial\omega} + \int_{\omega} s \, dv = 0$$

ω \downarrow term



$\int \frac{d}{dt} \omega$ ↓ without spatial flux density
 $\int \omega$ ↓ source term



Examples:

Linear momentum $f_x = -\sigma$ $s = \rho b$

$$\int \frac{d}{dt} \omega \cdot n ds + \int \rho b dV = 0$$

Energy (with only thermal effects) $f_x = q$ $s = Q$

$$-\int q \cdot n ds + \int Q dV = 0$$

Dynamic form

$$\frac{D}{Dt} \int \omega dV = - \int \frac{d}{dt} f_x \cdot n ds + \int s dV$$

only thermal effects $e = \rho T$ temporal flux of balanced quantity

$$\frac{D}{Dt} \int \rho dV = - \int q \cdot n ds + \int Q dV$$

energy density per volume

Linear momentum

$$\frac{D}{Dt} P = \Sigma \text{ forces} \quad p = \rho \vec{v} = \text{linear momentum density}$$

$$P = \Sigma m v = \int \vec{v} (\rho dV) = \int (\rho \vec{v}) dV$$

$$\frac{D}{Dt} \int \rho \vec{v} dV = \int \frac{d}{dt} \rho \cdot n ds + \int \rho b dV$$

ΣF

$\rho = \rho \vec{v}$

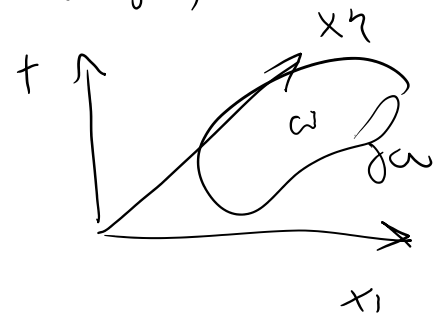
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In general we have

$$\frac{D}{Dt} F = \frac{d}{dt} \int_{\omega} f_t dV = - \int_{\partial\omega} f_{k\alpha} n_{\alpha} dS + \int_{\omega} s dV$$

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↓

Balanced quantity (PE)
 temporal flux density of balanced quantity
 outward spatial flux density (↑ tensor order higher)



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$$e = u^h - u$$

$$a(w^h, e) = \partial_{kk}$$

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$$U^h \in \mathcal{S}^u$$

$$a(e, e) \leq a(u^h - u, u^h - u) \rightarrow$$

$$a(w^h, u) = (w^h, e) + (w^h, u)$$

$$0 = a(w^h, u^h) - a(w^h, u) = a(w^h, e)$$

$$a(e + w^h, e + w^h) = a(e, e) + 2a(w^h, e) + a(w^h, w^h)$$

$$a(w^h, w^h) \gg 0$$

$$a(e, e) \leq a(e + w^h, e + w^h)$$

$$u^h = u + w^h, \quad e = u^h - u$$

$$a(u + w^h, u + w^h)$$

$$a(u^h, u^h)$$

$$a(u, u) = a(u^h, u^h) + a(e, e)$$

$$\hookrightarrow a(e, e) = a(u, u) - a(u^h, u^h)$$

$$\frac{a(u^h, u^h)}{a(u, u)} \leq 1$$