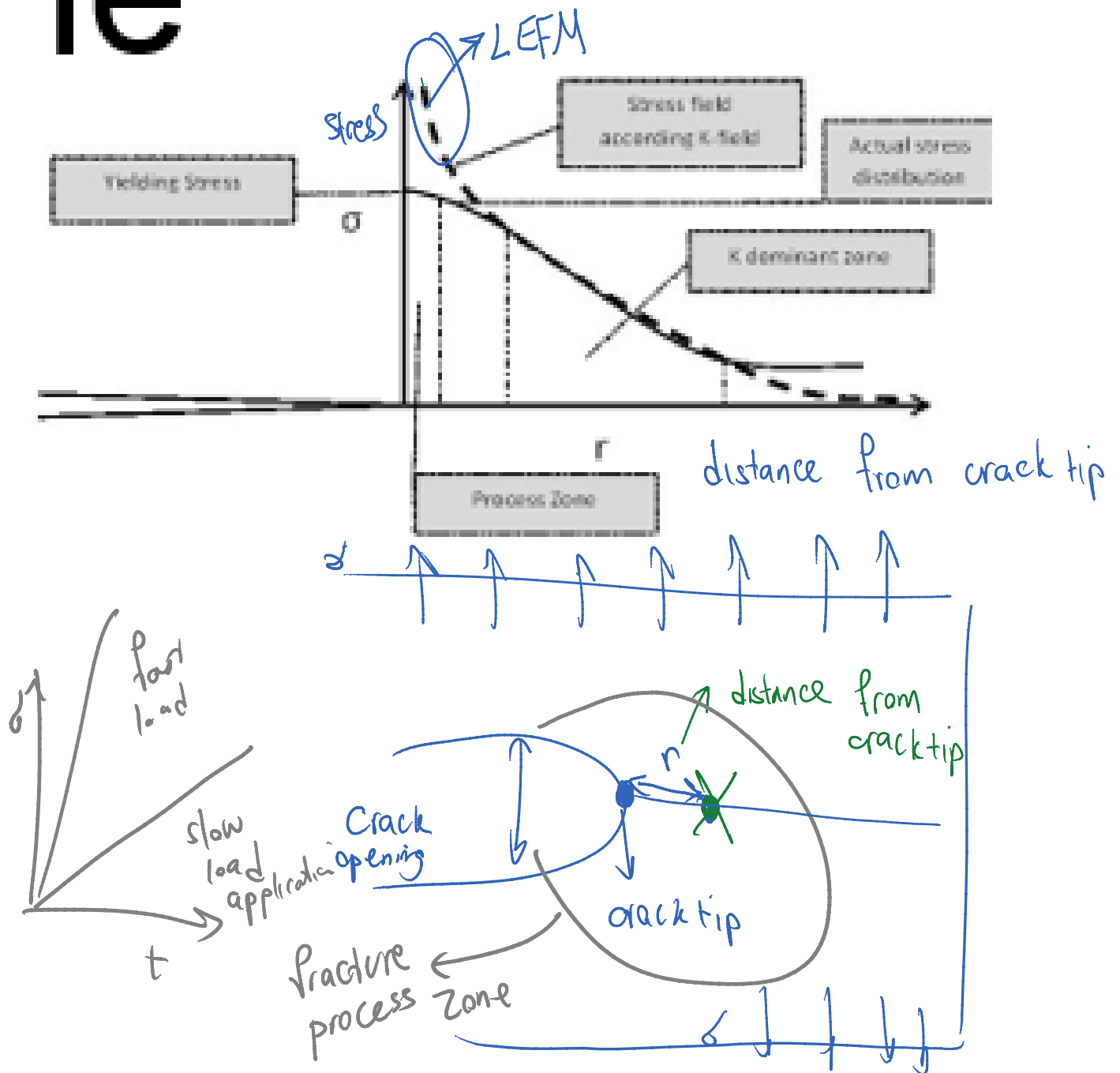


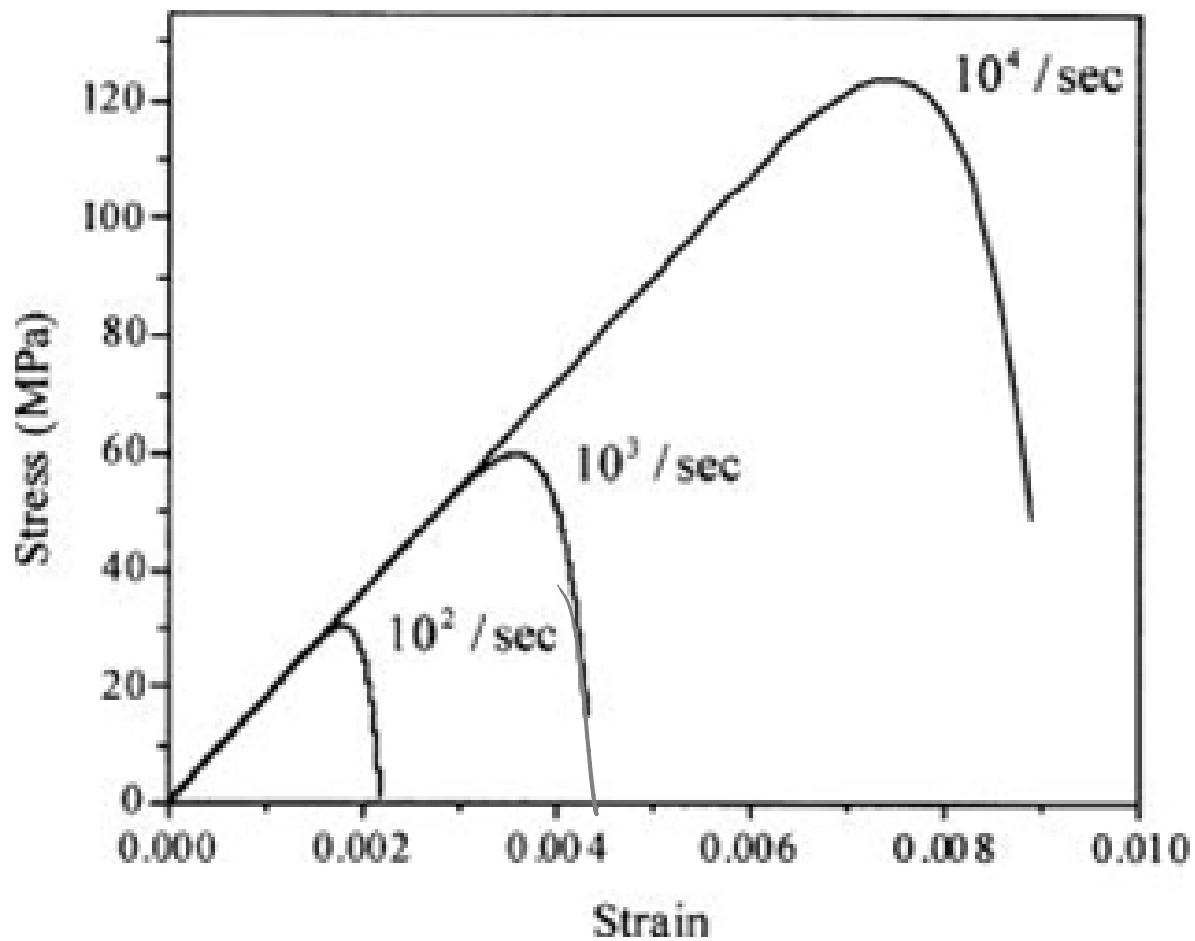
2016/08/23

Tuesday, August 23, 2016
8:40 AM

IC

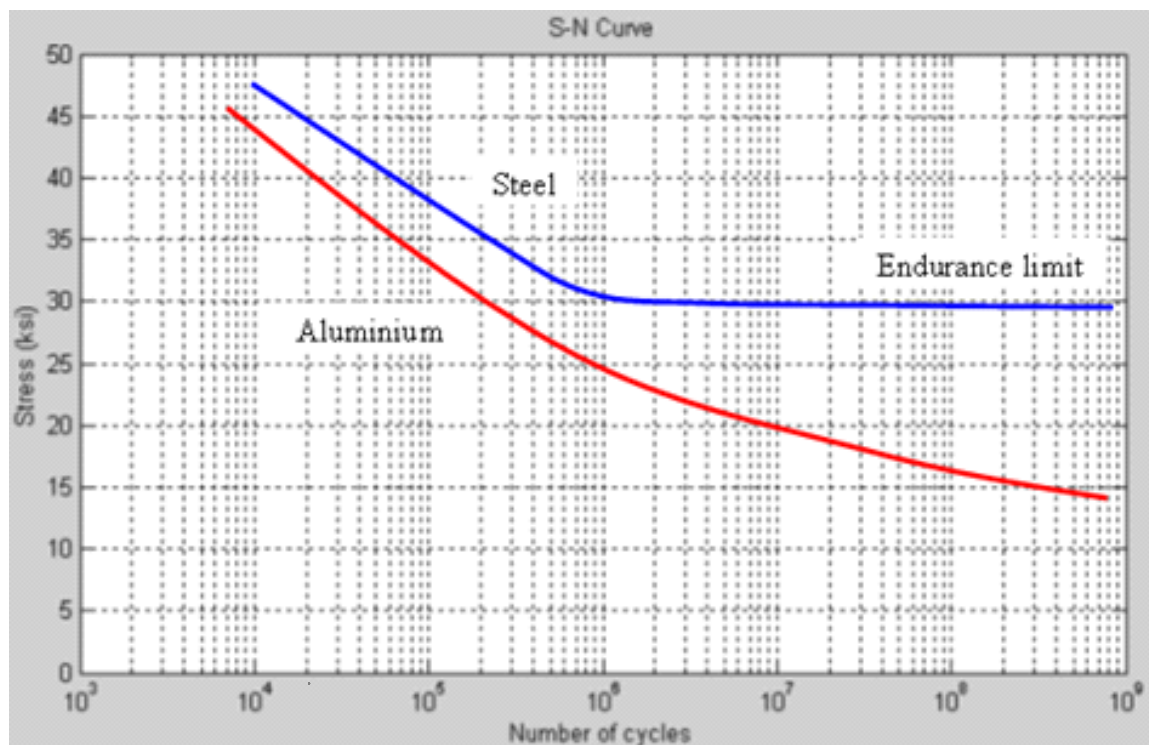


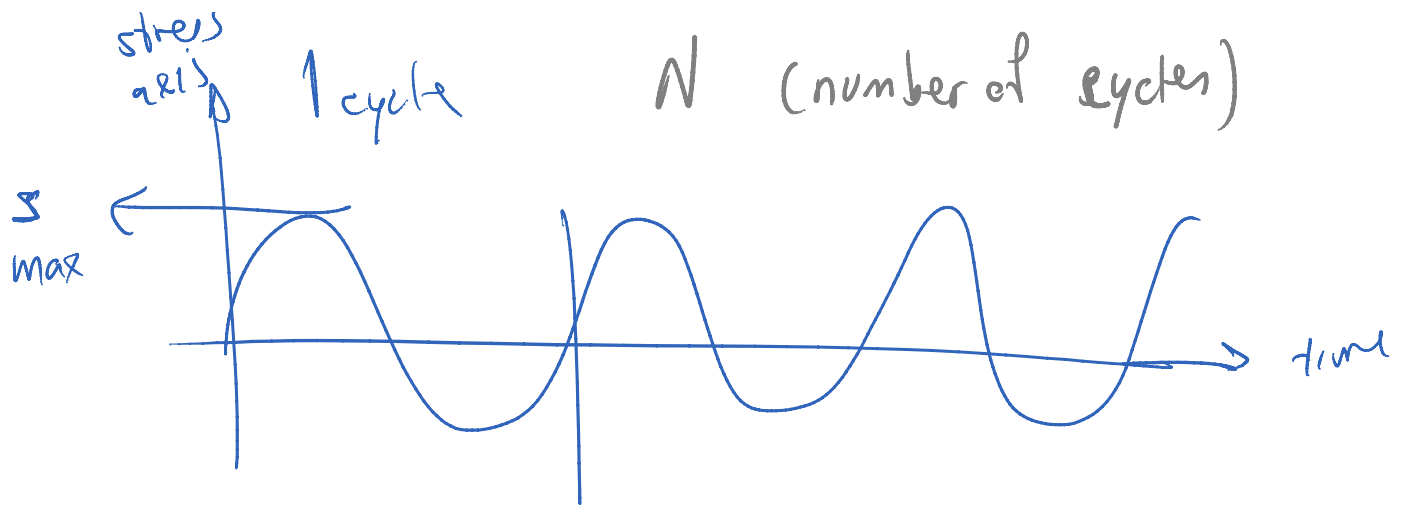
Dynamic fracture
Rate effect



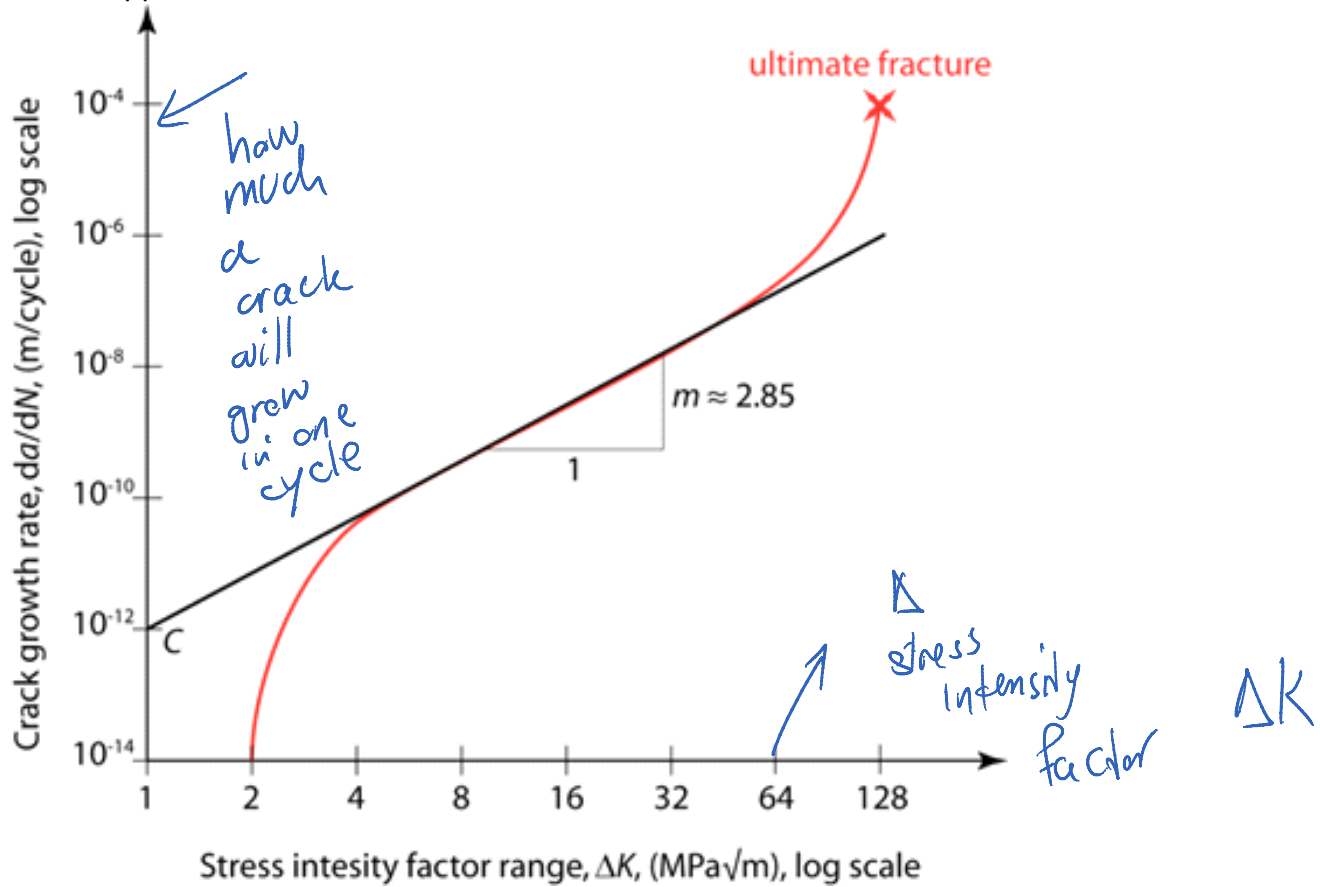
Last section of the course:
Fatigue

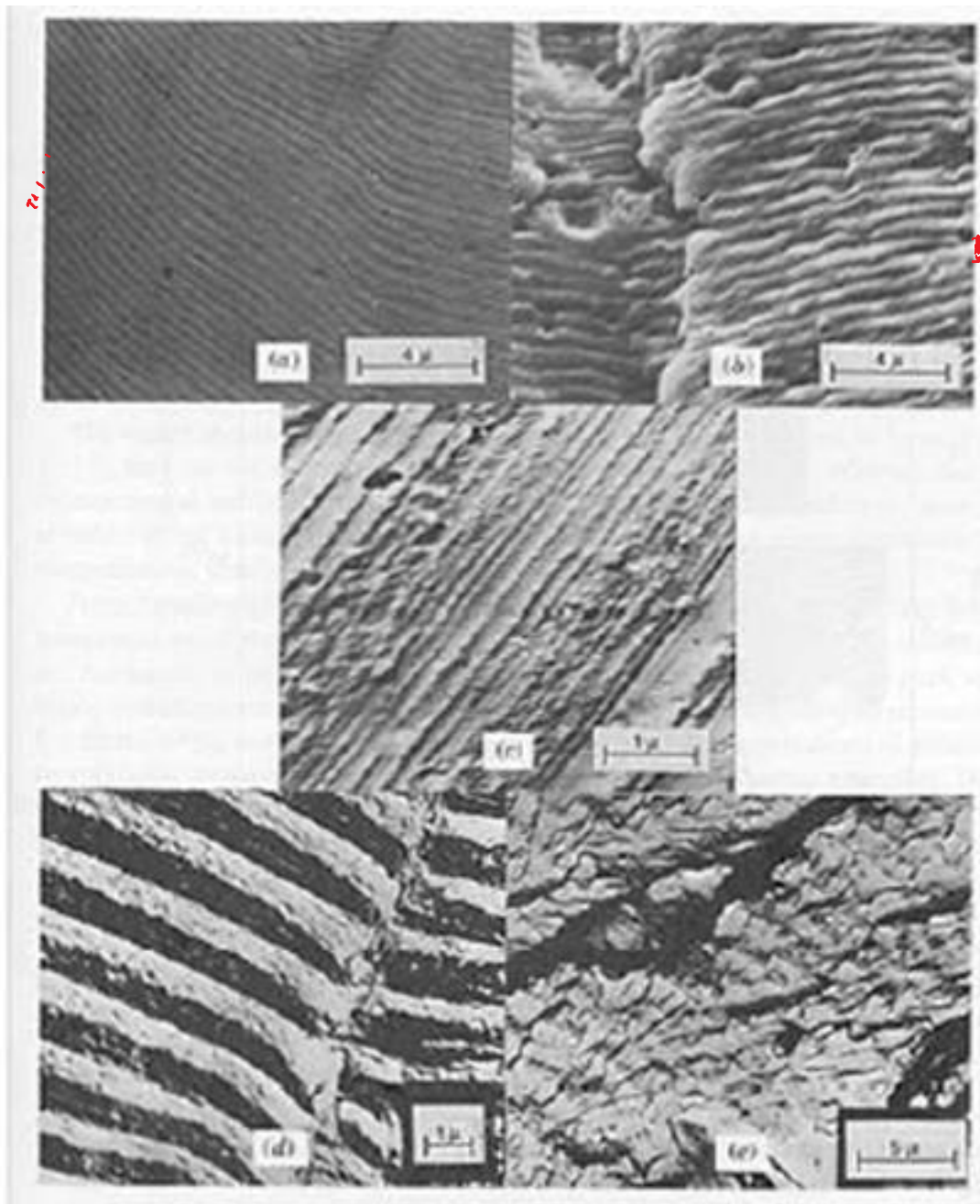
S
stress





Newer approach is Paris law





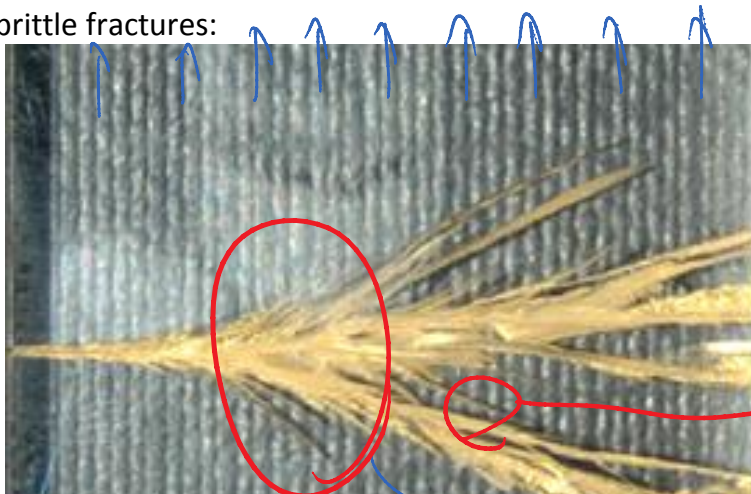
Front of the crack

$N \approx 10^3$

$N = 10^3$ — crack

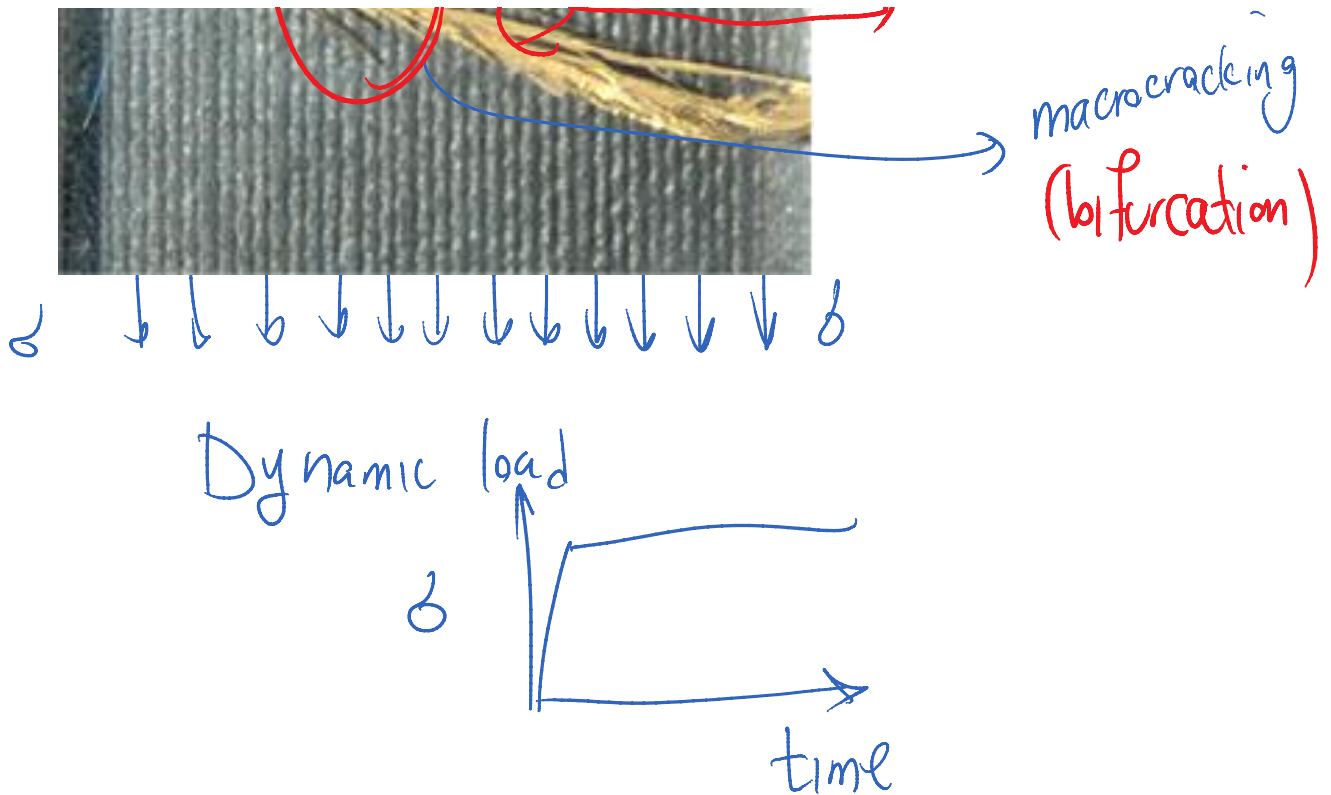
$N \approx 10^6$

Typical brittle fractures:



microcracks

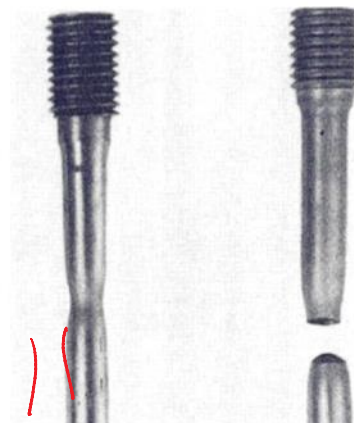
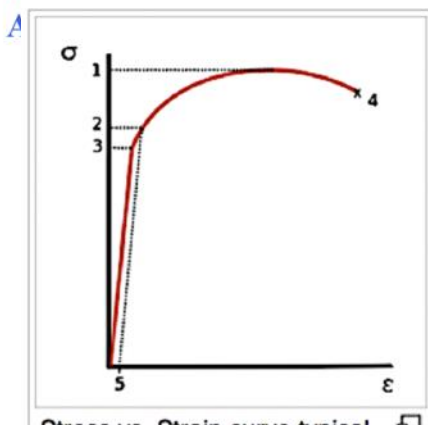
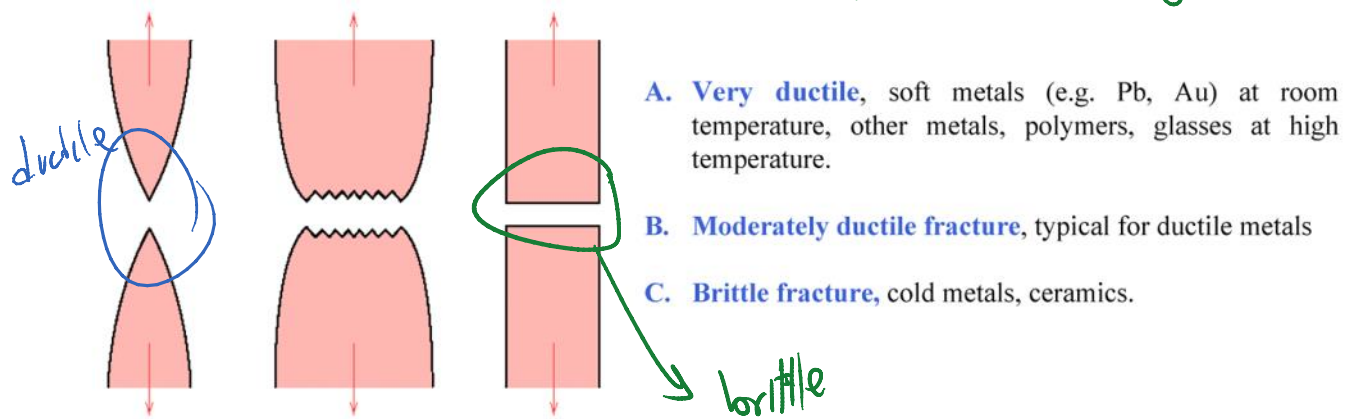
microcracking

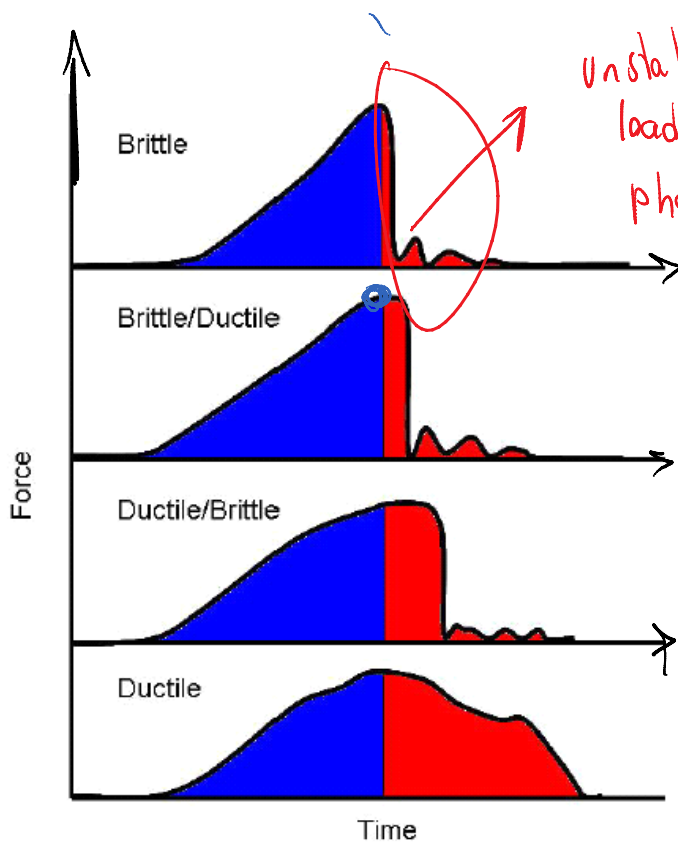
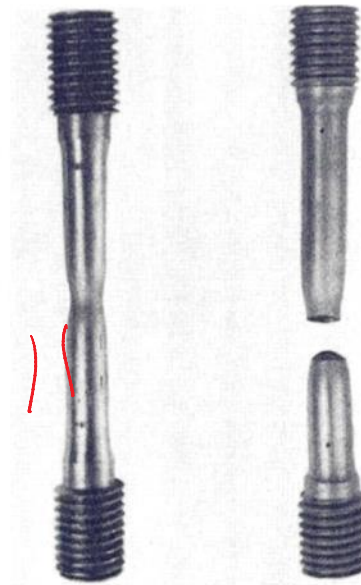
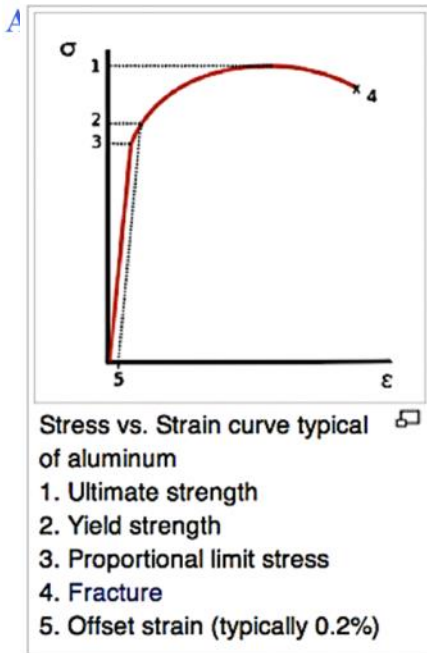


Difference between ductile and brittle fracture

Brittle vs. Ductile Fracture

quasi-static loading

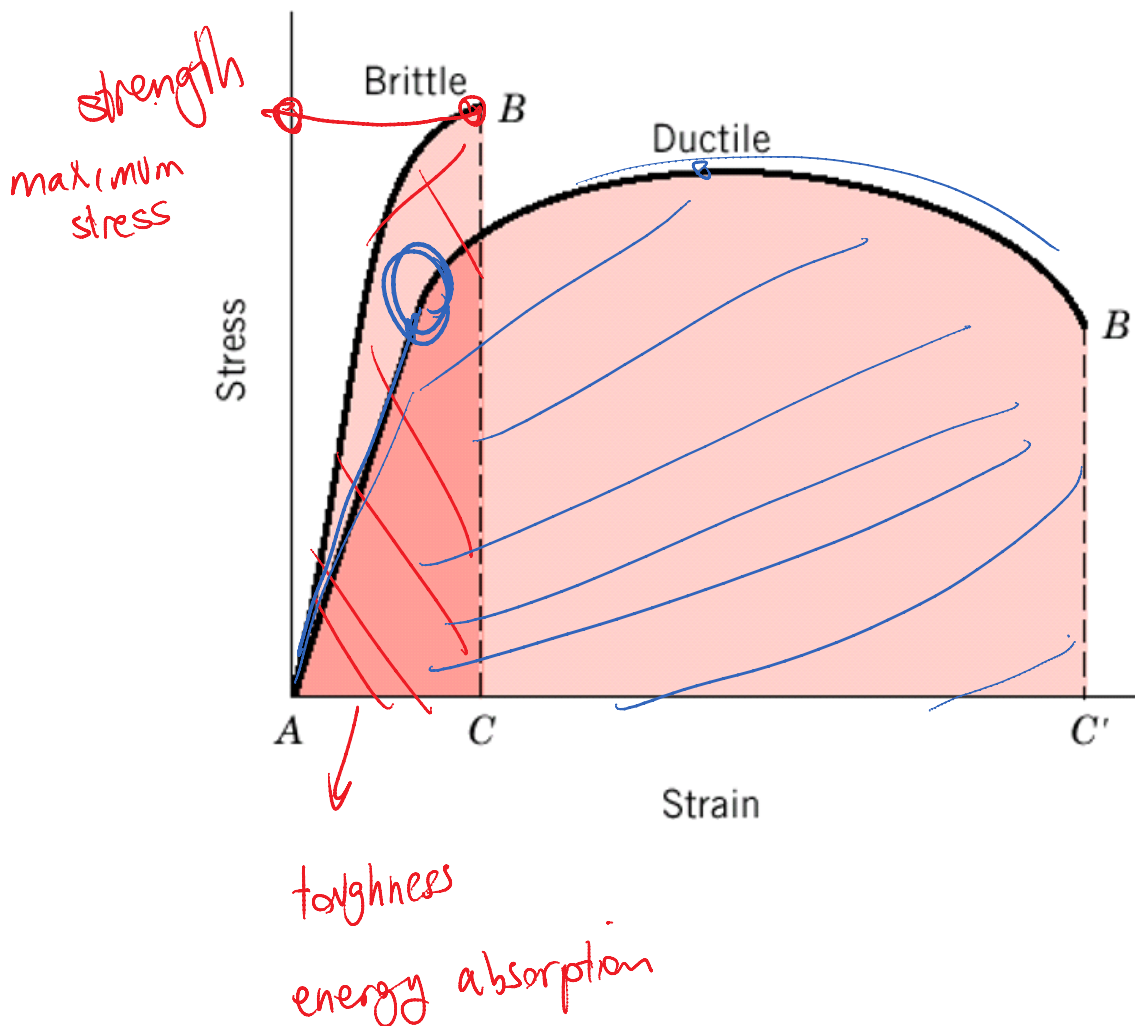




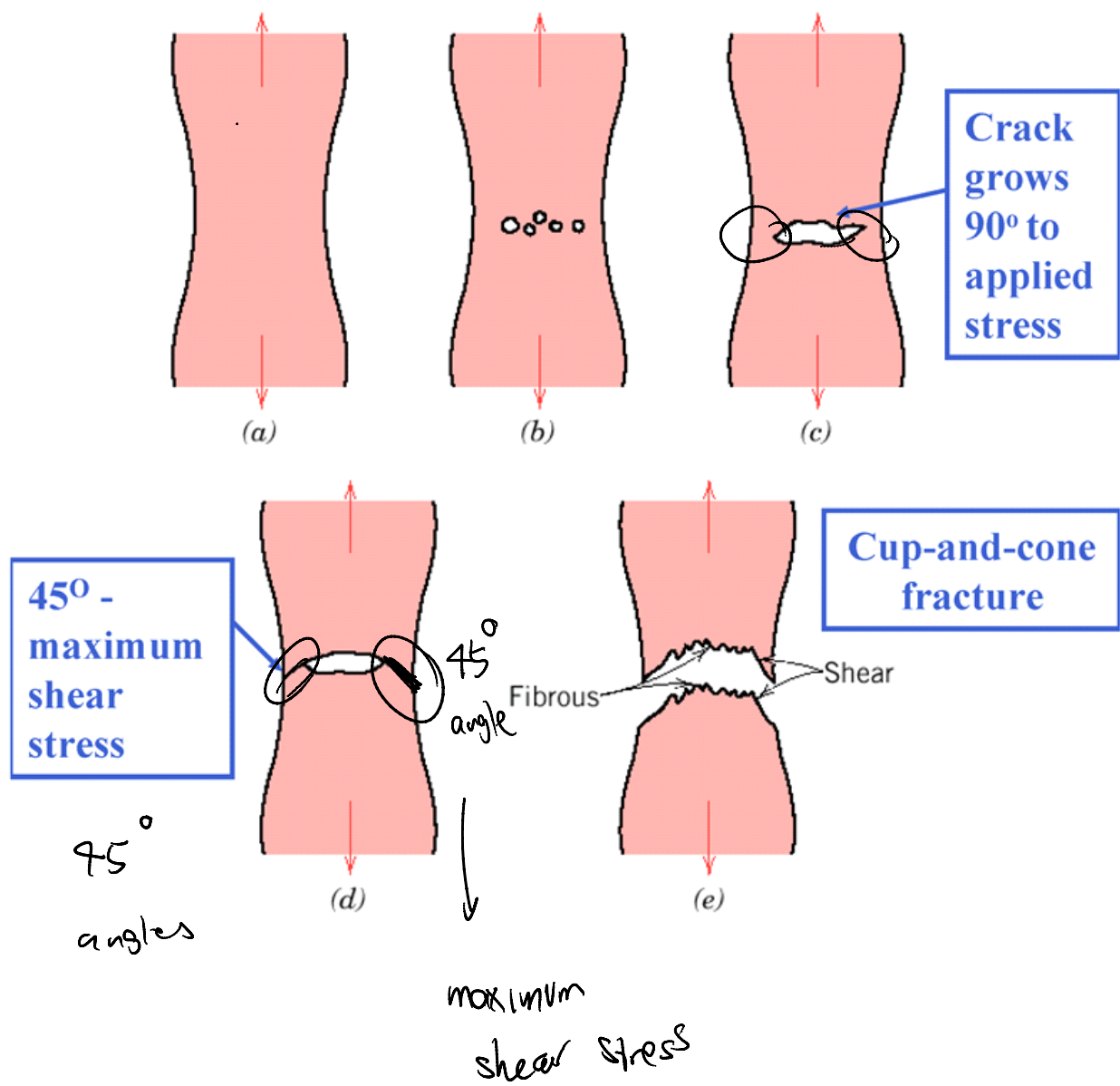
Ductile vs. brittle
energy absorption
properties

Brittle vs. Ductile Fracture

- **Ductile materials** - extensive plastic deformation and energy absorption (“toughness”) before fracture
- **Brittle materials** - little plastic deformation and low energy absorption before fracture

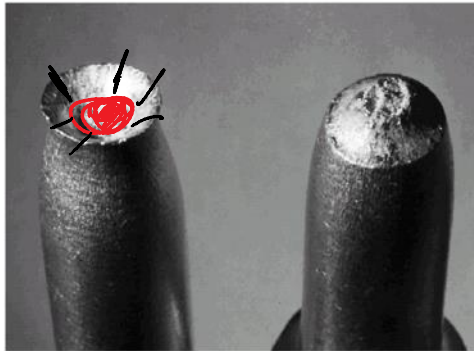


Ductile Fracture (Dislocation Mediated)

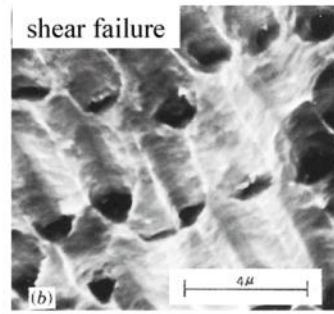
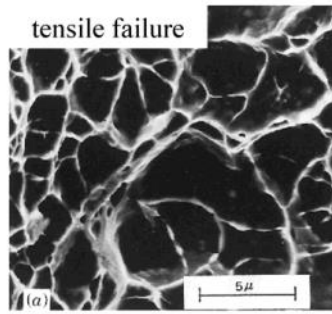


Ductile fracture

Ductile Fracture



(Cup-and-cone fracture in Al)

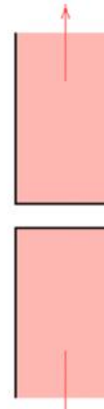


Scanning Electron Microscopy: *Fractographic* studies at high resolution. Spherical “dimples” correspond to microvoids that initiate crack formation.

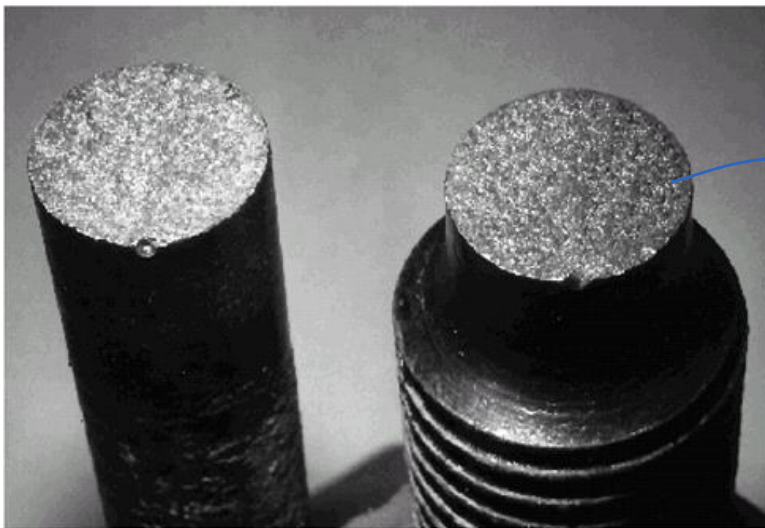
Brittle fracture:

Brittle Fracture (Limited Dislocation Mobility)

- No appreciable plastic deformation
- Crack propagation is very fast
- Crack propagates nearly perpendicular to the direction of the applied stress
- Crack often propagates by *cleavage* - breaking of atomic bonds along specific crystallographic planes (*cleavage planes*).



maximum
tensile
stress



Experiment
on brittle
fracture

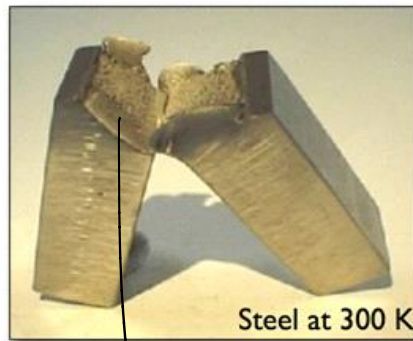
Brittle fracture in a mild steel

Brittle Fracture



smooth surface

Ductile Fracture



a large amount of plastic deformation before final failure



Because of all energy absorption mechanisms ductile materials are much more resistant to (manufacturing) defects and have much less scatter in their 1) ultimate load 2) toughness (energy absorption)

much more resistant to (manufacturing) defects and have much less scatter in their 1) ultimate load 2) toughness (energy absorption)

Background information

- Indicial notation

$$a_i \geq 0 \quad i = 1, 2, 3$$

↓ all the components are positive

$$\vec{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

$$\sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix}$$

stress tensor

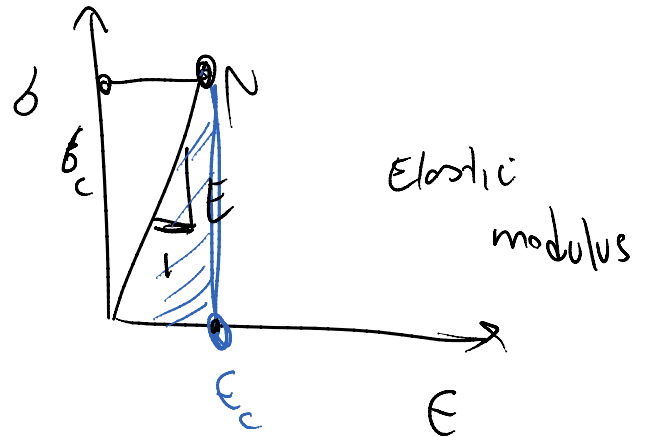
$$\sigma_{ii} = \sum_{i=1}^3 \sigma_{ii} = \sigma_{11} + \sigma_{22} + \sigma_{33}$$

repeated index

$$\epsilon = \begin{pmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{pmatrix}$$

$$\epsilon = \begin{bmatrix} \epsilon_{11} & \epsilon_{22} & \epsilon_{33} \end{bmatrix}$$

1D
case



what is this area?

$$u = \int_0^{\epsilon_c} \sigma d\epsilon = \text{energy density per unit volume}$$

for linear elastic material $u = \frac{1}{2} \sigma \epsilon$

What is energy density in 2D & 3D?

$$\epsilon = \begin{bmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{bmatrix} \quad \sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$

loading

initial state $\epsilon = 0 \longrightarrow \epsilon \neq 0$

How much energy is absorbed per unit volume?

$$U = \frac{1}{2} \epsilon : \sigma = \frac{1}{2} (\epsilon_{11} \sigma_{11} + \epsilon_{12} \sigma_{12} + \epsilon_{13} \sigma_{13} + \epsilon_{21} \sigma_{21} + \epsilon_{22} \sigma_{22} + \epsilon_{23} \sigma_{23} + \epsilon_{31} \sigma_{31} + \epsilon_{32} \sigma_{32} + \epsilon_{33} \sigma_{33})$$

$$= \frac{1}{2} (\epsilon_{ij} \sigma_{ij})$$

repeated → repeated

$$= \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 \epsilon_{ij} \sigma_{ij}$$

Voigt notation

a more concise way to express stress & strain

$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$

$$\epsilon = \begin{bmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{bmatrix}$$

$$\begin{pmatrix} \dots & \dots & \dots \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix}$$

symmetric

$$\sigma_{12} = \sigma_{21} \dots$$

has
6
independent
values

$$\begin{pmatrix} \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{pmatrix}$$

Voigt notation

$$S = \left\{ \begin{array}{c|c} \begin{matrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{matrix} & \text{normal components} \\ \hline \begin{matrix} \sigma_{12} \\ \sigma_{23} \\ \sigma_{31} \end{matrix} & \text{shear stresses} \end{array} \right\}$$

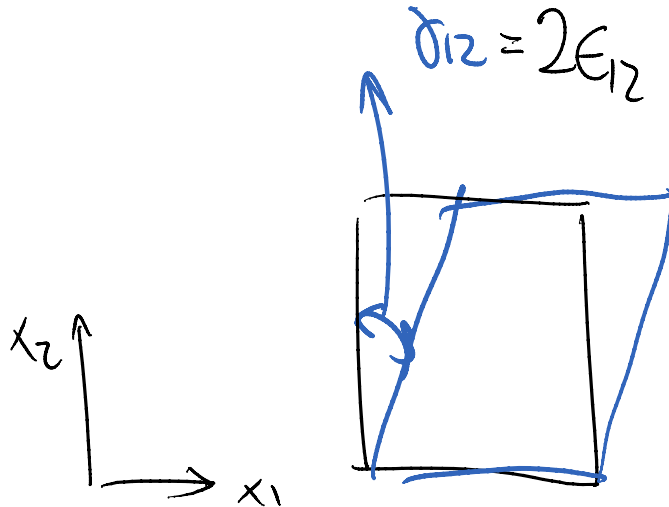
Voigt strain

$$\gamma = \left\{ \begin{array}{c|c} \begin{matrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \end{matrix} & \text{normal components} \\ \hline \begin{matrix} 2\epsilon_{12} \\ 2\epsilon_{23} \\ 2\epsilon_{31} \end{matrix} & \text{Engineering shear strains} \end{array} \right\}$$

$$\epsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i})$$

$$\sigma_{12} = 2\epsilon_{12} = 2 \times \frac{1}{2} (u_{1,2} + u_{2,1})$$

$$= u_{1,2} + u_{2,1}$$



$$\sigma_{3 \times 3} = \underbrace{C_{3 \times 3 \times 3 \times 3}}_{\text{}} \epsilon_{3 \times 3}$$

↓ 4th order Elasticity tensor

How is this done with

Voigt's notation γ

$$s_c \begin{bmatrix} b_{11} \\ b_{22} \\ b_{33} \\ b_{12} \\ b_{23} \\ b_{31} \end{bmatrix}_{6 \times 1} = \begin{bmatrix} \begin{bmatrix} E_{11} \\ E_{22} \\ E_{33} \\ 2E_{12} \\ 2E_{23} \\ 2E_{31} \end{bmatrix}_{6 \times 6} \end{bmatrix}_{6 \times 6}$$

↙ $C_{6 \times 6}$
Voigt elasticity matrix

$$u = \frac{1}{2} b : \epsilon$$

$$u = \frac{1}{2} \epsilon : b = \frac{1}{2} (E_{11} b_{11} + E_{12} b_{12} + E_{13} b_{13} + E_{21} b_{21} + E_{22} b_{22} + E_{23} b_{23} + E_{31} b_{31} + E_{32} b_{32} + E_{33} b_{33})$$

$$E_{12} = E_{21}$$

$$b_{12} = b_{21}$$

$$\epsilon_{12} = \epsilon_{21}$$

$$\sigma_{12} = \sigma_{21}$$

$$= \frac{1}{2} \left(E_{11} \epsilon_{11} + E_{22} \epsilon_{22} + E_{33} \epsilon_{33} + (2E_{12}) \epsilon_{12} + (2E_{23}) \epsilon_{23} + (2E_{31}) \epsilon_{31} \right)$$

$$= \frac{1}{2} \underbrace{\begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \epsilon_{12} \\ \epsilon_{23} \\ \epsilon_{31} \end{bmatrix}}_{\boldsymbol{\epsilon}} \cdot \underbrace{\begin{bmatrix} E_{11} \\ E_{22} \\ E_{33} \\ 2E_{12} \\ 2E_{23} \\ 2E_{31} \end{bmatrix}}_{\boldsymbol{\sigma}}$$

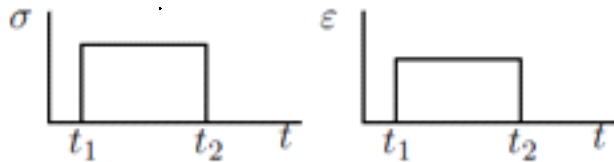
Vol. stress
& strain

$$U = \frac{1}{2} \boldsymbol{\epsilon} : \boldsymbol{\sigma} = \frac{1}{2} \boldsymbol{\epsilon} \cdot \boldsymbol{\sigma}$$

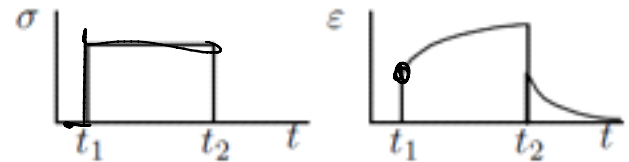
Material classification / Tensile test

δ, CE

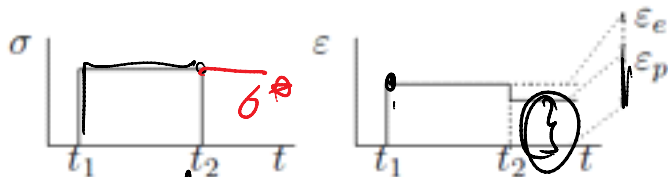
Elastic



Visoelastic



Elastic-Plastic



Visoplastic

