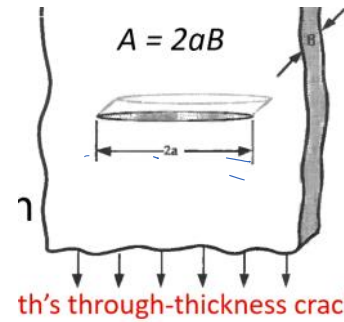
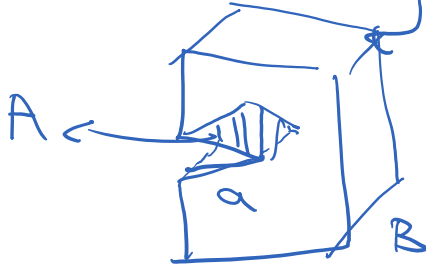


From last time

$$2\delta_s = - \frac{1}{B} \frac{\partial \Pi}{\partial a} = - \frac{\partial \Pi}{\partial A}$$



potential energy

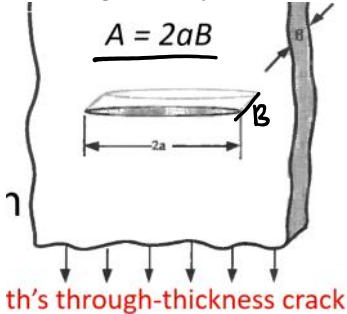
$$-\frac{\partial \Pi}{\partial A} = 2\delta_s$$

crack surface

how much energy is required per unit area of crack

How much energy released per unit surface of crack advance

For this geometry:



From theory of elasticity Inglis

$$\Pi(a) - \Pi(0) = - \frac{\pi a^2 \sigma^2 B}{E}$$

$$\frac{d\Pi}{dA} = \frac{d(-\frac{\pi a^2 \sigma^2 B}{E})}{d(2aB)} = - \frac{\pi a \sigma^2}{E}$$

constant

$$-\frac{d\Pi}{dA} = 2\delta_s$$

σ_f

$$\frac{\pi a \sigma_f^2}{E} = 2\delta_s$$

failure strength (causes crack propagation) for an infinite domain containing a mid-crack of length $2a$ is:

$$\frac{\pi a \sigma_f^2}{E} = 2\delta_s \rightarrow \sigma_f = \sqrt{\frac{E \delta_s}{\pi a}}$$

Last time

$$\sigma_f = \sqrt{\frac{E\gamma_s}{4a}}$$

stress concentration argument

$$\approx .5 \sqrt{\frac{E\gamma_s}{a}}$$

compare this with atomistic-based strength which was:

$$\sigma_c = \sqrt{\frac{E\gamma_s}{\lambda_0}} \gg \sigma_f$$

because $\lambda_0 \ll a$

This time

$$\sigma_f = \sqrt{\frac{E\gamma_s}{\frac{\pi}{2}a}}$$

$$\approx .8 \sqrt{\frac{E\gamma_s}{a}}$$

Stress approach:

Stress Concentration

$$\sigma_f = 0.5 \sqrt{\frac{E\gamma_s}{a}}$$

Energy approach:

Griffith

$$\sigma_f = \sqrt{\frac{2}{\pi}} \sqrt{\frac{E\gamma_s}{a}} \approx 0.8 \sqrt{\frac{E\gamma_s}{a}}$$

From last time:

crack growth

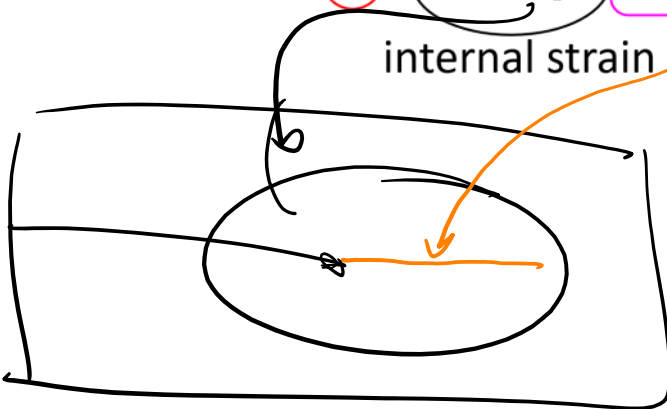
external work

kinetic energy

surface energy

$$\dot{W} = \dot{U}_e + \dot{U}_p + \dot{U}_k + \dot{U}_\Gamma$$

internal strain energy



Plane stress

$$\sigma_c = \sqrt{\frac{2E\gamma_s}{\pi a}}$$

Griffith (1921), ideally brittle solids

$$\sigma_c = \sqrt{\frac{2E(\gamma_s + \gamma_p)}{\pi a}}$$

Irwin, Orowan (1948), metals

$$\gamma_p \gg \gamma_s$$

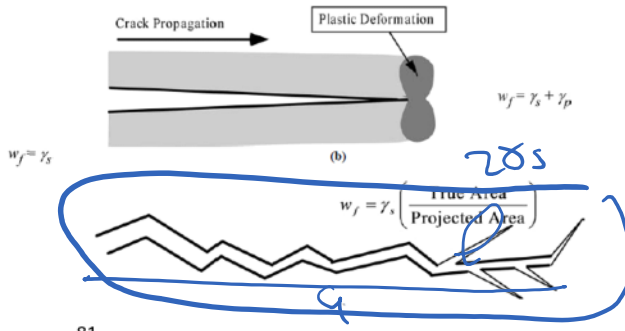
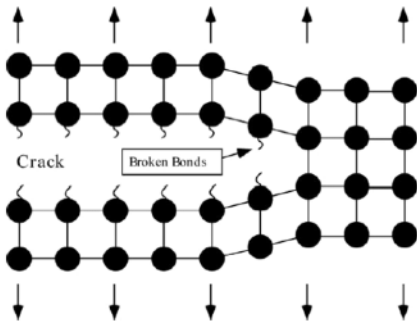
$$\gamma_p \approx 10^3 \gamma_s \text{ (metals)}$$

general form of the equation

energy needed to advance the crack per unit area

$$\sigma_f = \sqrt{\frac{2E w_f}{\pi a}}$$

- w_f : Fracture energy from plastic, viscoelastic, or viscoplastic effects
- w_f can also be influenced by crack meandering and branching
- Caution: If nonlinear displacement regions are large enough this equation is not accurate as it is based on linear elastic solution ($\Pi = \Pi_0 - \frac{\pi \sigma^2 a^2 B}{E}$)



Energy release rate

Irwin 1956

$$G \equiv - \frac{d\Pi}{dA}$$

a.k.a

Crack extension force
Crack driving force

Potential energy

$$G = - \frac{d\Pi}{dA}$$

crack surface

how much energy is going to be released per surface of crack (per unit time)

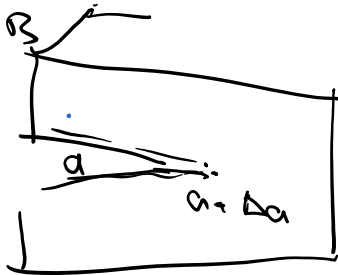
R

resistance

$$= 2w_p$$

How much energy is required to create a unit surface of crack

material property, also depend on crack length



$A = aB$

$\Pi(a)$

$\Pi(a + \Delta a)$

$$G(a) = - \frac{d\Pi}{dA}$$

$$= - \frac{\Pi(a + \Delta a) - \Pi(a)}{\Delta a B}$$

$G < R$ crack does not propagate (not enough energy released)

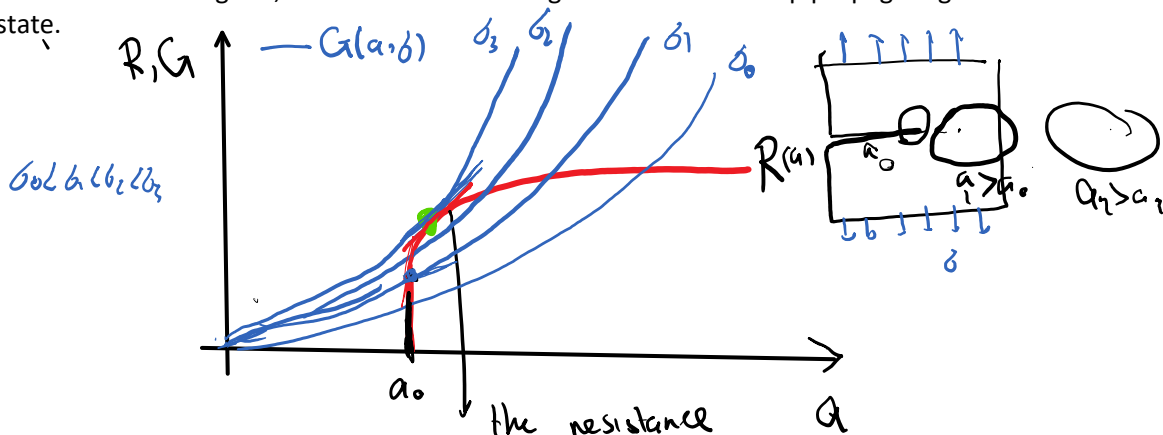
$G = R$ crack advances.

$G > R$ extra energy goes to dynamic effects, heating of the crack

tip, etc.

Stable vs. unstable crack growth:

For both crack will grow, but for unstable crack growth it will not stop propagating with the current "loading" state.



the resistance sometimes grows as crack propagates since plastic field around crack tip fully develops

- crack does not grow until δ_1 for which $G(a, \delta_1) = R(a)$ for lower loads, $G < R$.

- between δ_1 & δ_3 we need to keep increasing the load δ for the crack to keep propagating.

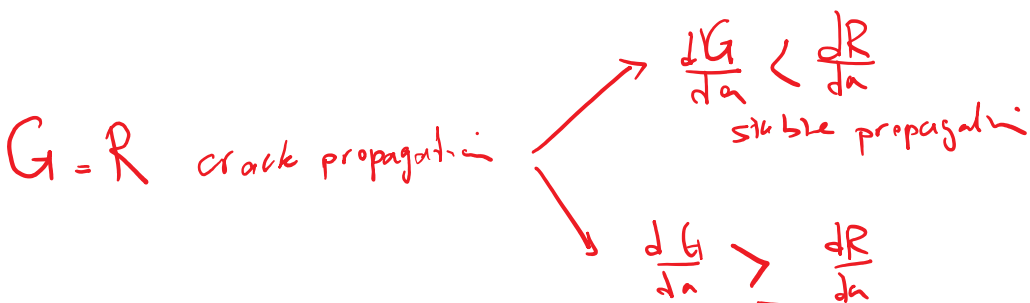
This is because $\frac{dG}{da} < \frac{dR}{da}$ in this range.

stable crack propagation

- at the critical load δ_3 we have

$$G = R \quad \& \quad \frac{dG}{da}(\delta_3) = \frac{dR}{da}$$

based on the curvatures the crack propagates for this load δ_3 (with no need to increase it) past this point.

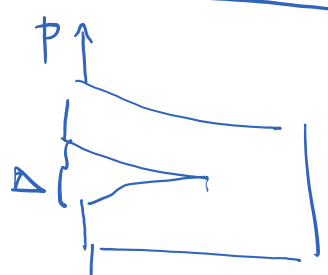


unstable propagation

A key question is how to calculate G

Different ways to calculate G:

- G from $P \times \Delta$ today



used to calculate G

we'll drive analytical expressions

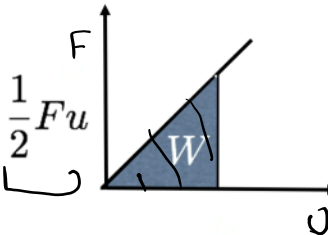
$$G = \frac{P^2}{2B} \frac{dC}{da} \text{ Compliance}$$

stress intensity factors

$$G = \frac{K_I^2 + K_{II}^2}{E'}$$

will learn this later

Consider a linear elastic bar of stiffness k, length L, area A, subjected to a force F, the work is

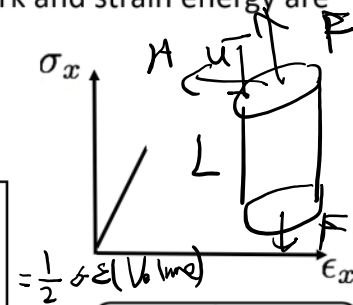
$$W = \int_0^u F du = \int_0^u k u du = \frac{1}{2} k u^2 = \frac{1}{2} F u$$


This work will be completely stored in the structure in the form of strain energy. Therefore, the external work and strain energy are equal to one another

$$U = W = \frac{1}{2} F u$$

In terms of stress/strain

$$U = \frac{1}{2} F u = \frac{1}{2} \frac{F}{A L} u A L$$



Strain energy density $[J/m^3]$

$$u = \frac{1}{2} \sigma_x \epsilon_x$$

$$u = \int \sigma_x d\epsilon_x$$

$$W = \int \underbrace{\frac{1}{2} \sigma \cdot \epsilon}_u dV = U_e$$

strain energy density $\leftarrow u$ internal energy

$$\underbrace{\int \sigma \, d\epsilon}_{\text{strain energy external}} = \underbrace{U_e}_{\text{internal energy}}$$

For a quasi-static problem with no plasticity and fracture all external work goes to internal energy.

Evaluation of G

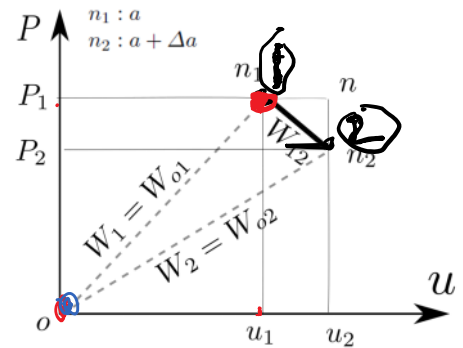
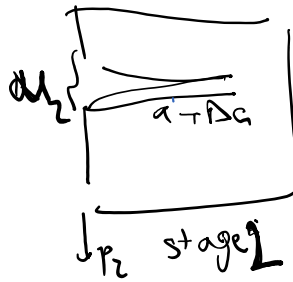
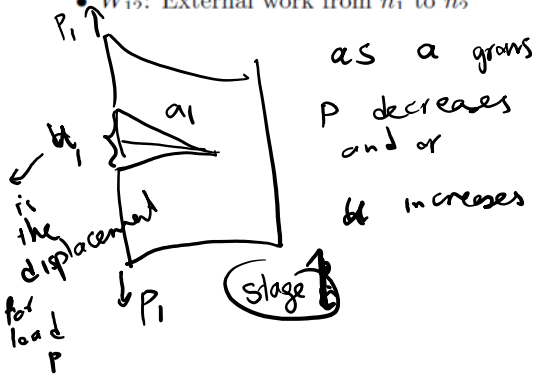
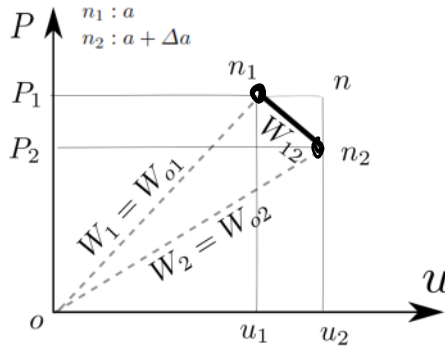
Given: A point load - displacement system with a crack and two data points:

- Load P_1 , displacement u_1 , & crack length a_1
- Load P_2 , displacement u_2 , & crack length $a_2 = a_1 + \Delta a$ (small Δa)

Goal: Compute G

Notation:

- $W_{1 \rightarrow 2}$: External work from n_1 to n_2



$$\Pi = U_e - W$$

$$\Delta \Pi = \Delta U_e - \Delta W$$

$$G = -\frac{d\Pi}{dA} \approx -\frac{\Delta \Pi}{B \Delta a}$$

$$\Delta \Pi = \Delta U_e - \Delta W$$

$$\Delta U_e = \underbrace{U_e(a + \Delta a)}_{\frac{1}{2} P_2 u_2} - \underbrace{U_e(a)}_{U_e(\text{stage 1})} = \frac{1}{2} P_1 u_1$$

= W_{o2}
external work

= W_{o1}
external work from 0

external
work
from 0
to stage 2

$-U_{o1}$
external
work from 0
to stage 1

ΔW = external work from stage 1
where crack length is a to stage 2
when u_1 " " u_2

