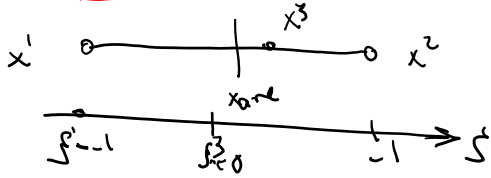


We want to numerically integrate  $k^e$  for 1D bar element  $p=2$   
 $L^e = x^2 - x^1$



$$J = 2\xi(x_{ave} - x^3) + \frac{L^e}{2}$$

$$k^e = \int_{-1}^1 \underbrace{\frac{AE(\xi)}{2\xi(x_{ave} - x^3) + \frac{L^e}{2}}}_{J(\xi)} \underbrace{\begin{bmatrix} \xi - \frac{1}{2} & \xi + \frac{1}{2} & -2\xi \\ -2\xi \end{bmatrix}}_{B_\xi} d\xi$$



Bar Element  $[p=2]$

$$N = \left[ \frac{\xi(\xi-1)}{2}, \frac{\xi(\xi+1)}{2}, 1-\xi^2 \right]$$

order general 1D bar  $p$

$$L_m = (\ )' \quad B_\xi = \frac{\partial}{\partial \xi} N = \left[ \xi - \frac{1}{2}, \xi + \frac{1}{2}, -2\xi \right] \quad p-1$$

Ignoring this part  $\rightarrow$  full integrand order  $\rightarrow$   $\int \frac{AE(\xi)}{J(\xi)} B(\xi) B(\xi) d\xi$   $2(p-1)$

Element order  
 $p$

Integrand order (o)  $2(p-1)$  # Gauss Pts (n)

$$\begin{aligned} n &= \text{ceil} \left( \frac{o+1}{2} \right) \\ &= \text{ceil} \left( \frac{2(p-1)+1}{2} \right) \\ &= \text{ceil} \left( p - \frac{1}{2} \right) = p \end{aligned}$$

Gauss

NC

$$\begin{aligned} n &= o+1 = 2(p-2)+1 \\ &= 2p-1 \end{aligned}$$

# Summary

1D bar order  $p$  needs

$p$  Gauss pts  
 $2p-1$  NC pts

For the example above  $p=2$  so we need

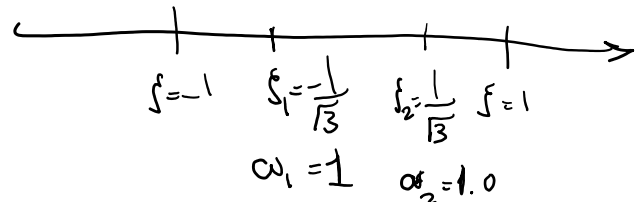
2 Gauss pts  
 NCs  $2 \times 2 - 1 = 3$  pts

Quadrature using Gauss pts:

2 Gauss pts

**TABLE 5.6** Sampling points and weights in Gauss-Legendre numerical integration (interval  $-1$  to  $+1$ )

$n$	$r_i$			$\alpha_i$		
1	0. (15 zeros)			2. (15 zeros)		
2	$\pm 0.57735$	0.2691	0.89626	1.00000	0.00000	0.00000
3	$\pm 0.77459$	0.66692	0.41483	0.55555	0.55555	0.55555
	0.00000	0.00000	0.00000	0.88888	0.88888	0.88888
4	$\pm 0.86113$	0.63115	0.94053	0.34785	0.48451	0.37454
	$\pm 0.33998$	0.10435	0.84856	0.65214	0.51548	0.62546
5	$\pm 0.90617$	0.98459	0.38664	0.23692	0.68850	0.56189
	$\pm 0.53846$	0.93101	0.05683	0.47862	0.86704	0.99366
	0.00000	0.00000	0.00000	0.56888	0.88888	0.88888
6	$\pm 0.93246$	0.95142	0.03152	0.17132	0.44923	0.79170
	$\pm 0.66120$	0.93864	0.66265	0.36076	0.15730	0.48139
	$\pm 0.23861$	0.91860	0.83197	0.46791	0.39345	0.72691



Gauss scheme

$$K^e = \int_{-1}^1 I(\xi) d\xi = \sum \omega_i \cdot I(\xi_i)$$

$$= \omega_1 I(\xi_1) + \omega_2 I(\xi_2) = 1.0 I(-\frac{1}{\sqrt{3}}) + 1.0 I(\frac{1}{\sqrt{3}})$$

NC  $n = 3$

TABLE 5.5 Newton-Cotes numbers and error estimates

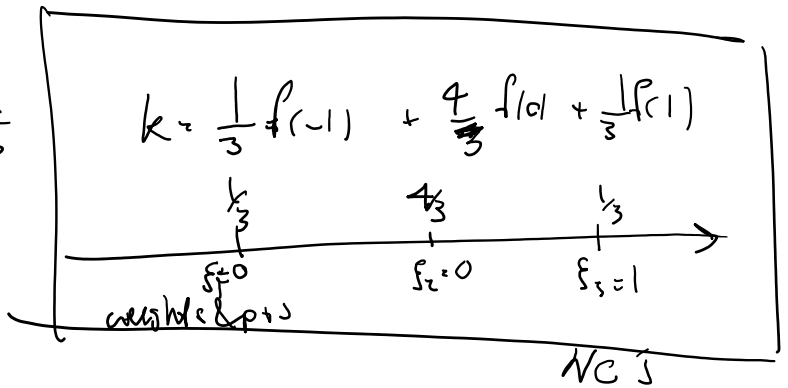
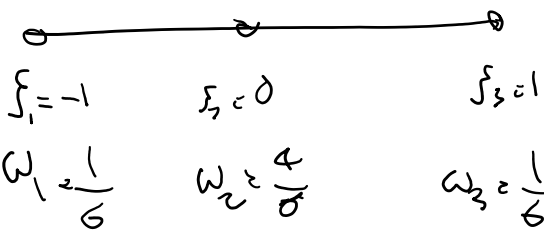
Number of intervals	Weights							Upper bound on error $R_n$ as a function of the derivative of $F$
	$C_0^1$	$C_1^1$	$C_2^1$	$C_3^1$	$C_4^1$	$C_5^1$	$C_6^1$	
1	$\frac{1}{2}$	$\frac{1}{2}$						$10^{-1}(b-a)^3 F'''(r)$
2	$\frac{1}{6}$	$\frac{4}{6}$	$\frac{1}{6}$					$10^{-3}(b-a)^5 F^{IV}(r)$
3	$\frac{1}{8}$	$\frac{3}{8}$	$\frac{3}{8}$	$\frac{1}{8}$				$10^{-3}(b-a)^5 F^{IV}(r)$
4	$\frac{7}{90}$	$\frac{32}{90}$	$\frac{12}{90}$	$\frac{32}{90}$	$\frac{7}{90}$			$10^{-6}(b-a)^7 F^{VI}(r)$
5	$\frac{19}{288}$	$\frac{75}{288}$	$\frac{50}{288}$	$\frac{50}{288}$	$\frac{75}{288}$	$\frac{19}{288}$		$10^{-6}(b-a)^7 F^{VI}(r)$
6	$\frac{41}{840}$	$\frac{216}{840}$	$\frac{27}{840}$	$\frac{272}{840}$	$\frac{27}{840}$	$\frac{216}{840}$	$\frac{41}{840}$	$10^{-9}(b-a)^9 F^{VIII}(r)$

Simpson's rule

NC  $K^p = \int_{-1}^1 I(\xi) d\xi = (1 - (-1)) \left( w_1 f(\xi_1) + w_2 f(\xi_2) + w_3 f(\xi_3) \right)$

NC always have  $b-a$  upfront

$$= 2 \left( \frac{1}{6} f(-1) + \frac{4}{6} f(0) + \frac{1}{6} f(1) \right)$$



$$K^e = \int_{-1}^1 \frac{A \xi(\xi)}{2 \xi(\xi_{ave} - \xi^3) + L \xi^2} \left[ \begin{matrix} \xi = -\frac{1}{2} \\ \xi = \frac{1}{2} \\ -2\xi \end{matrix} \right] \underbrace{\left[ \begin{matrix} \xi = -\frac{1}{2} & \xi = \frac{1}{2} & -2\xi \end{matrix} \right]}_{B_\xi} I(\xi) d\xi$$

$J(\xi)$

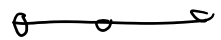
When is the full integrative scheme exact ( $K^e$  is exactly calculated)?

1.  $AE$  should be constant (Homogeneous material)

2.  $J$  constant (Undistorted element)

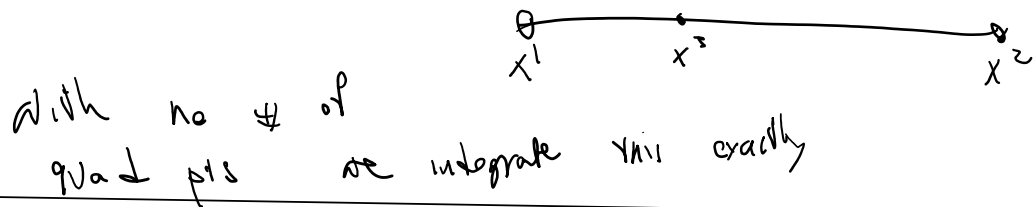
3. (Not seen here for nonlinear problems like plasticity, nonlinear elasticity, nonlinear effects are small)

then  $K$  is exact (we obtained this before



$$\frac{AE}{L} \begin{bmatrix} \frac{7}{3} & -\frac{4}{3} & - \\ - & - & - \\ - & - & - \end{bmatrix}$$

Q2: How many more points are needed to integrate  $K$  exactly when  $J \neq cte$  ( $X_3 \neq X_{ave}$ )



Q3: How many pts should we use when  $J \neq cte$  or  $AE \neq cte$

Almost always full integrative order suffices  
" " " | quadrature error |  $\leq$  | discretization error |

in terms of order of magnitude

Q4: Can we even use fewer quad pts to be more efficient?

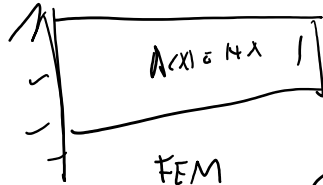
cases for this:

a) Reducing computational costs

b)

Stiffness-based FEM results in over stiff solutions

$$F = Ku$$

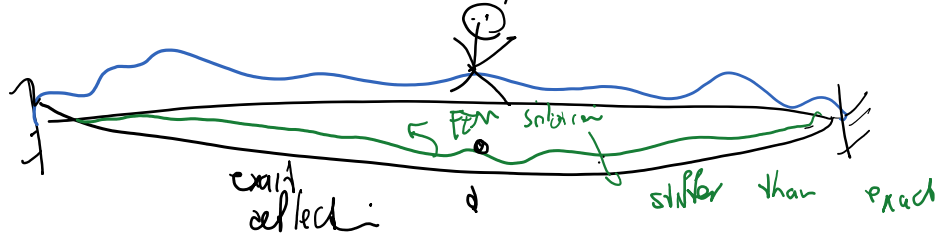


$$k = 1.5 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$k_{\text{exact}} = 1.4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$k_{\text{FEM}}$  stiffer exact  $k$

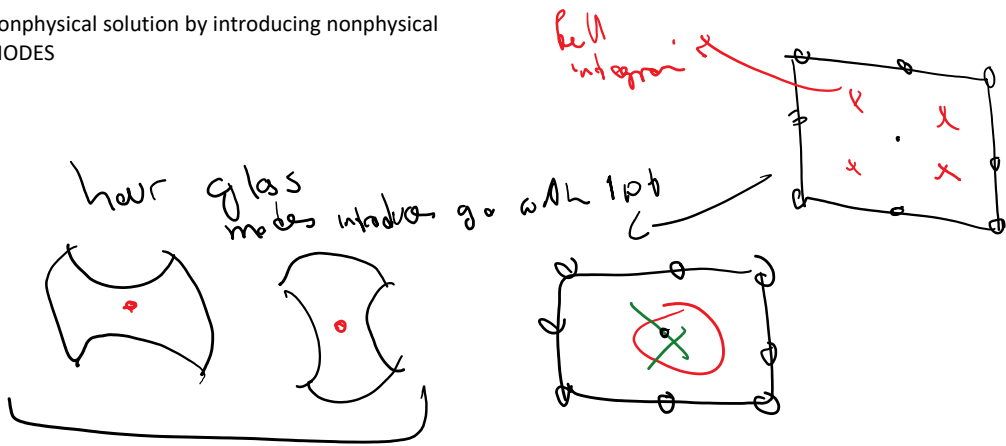
$$(1.5 > 1.4)$$



Reduced order integration can make the structure less stiff:)

Cases against reduced order integration:

It can result in nonphysical solution by introducing nonphysical ZERO ENERGY MODES

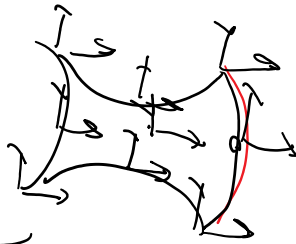


These are the shapes that have zero strain right at the reduced scheme Gauss points (here just 1 point) but realistically have nonzero strains elsewhere. But with reduced order integration we miss these points.

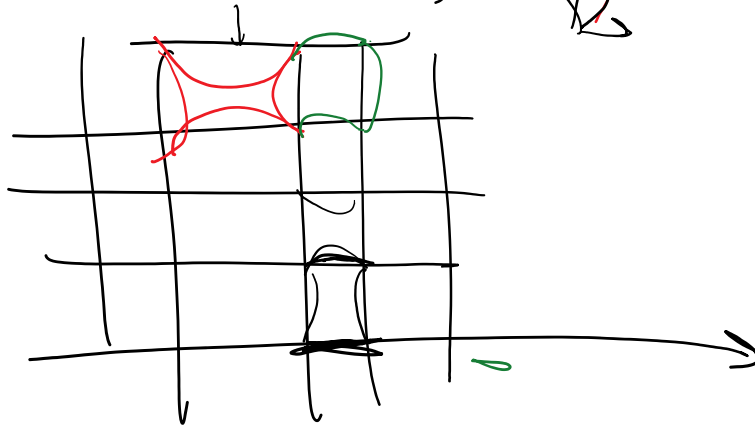
elsewhere. But with reduced order integration we miss these points.

18 dots

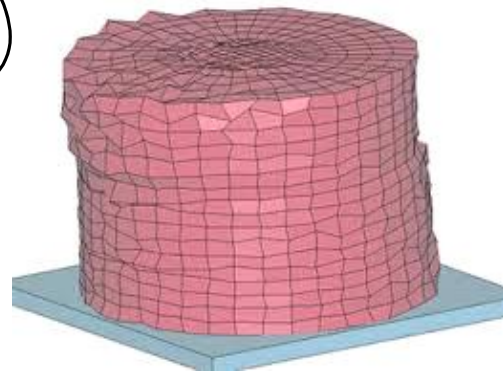
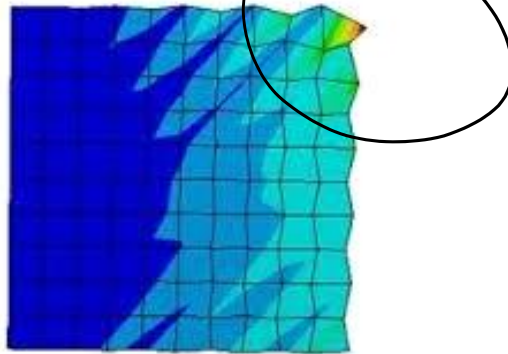
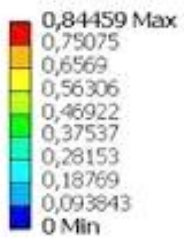
$u_1 \dots u_8 \neq 0$



Forces = 0



Total Deformation  
Type: Total Deformation  
Unit: mm  
Time: 1  
04.02.2008 14:13



How to check if the under-integration is safe, that is, it does not introduce nonphysical zero modes

$p=1$  element

Are there any nonzero  $u$ 's  $u_i \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \neq 0$

$$\Rightarrow F = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix} = 0$$

$$k^e = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$F = k^e u$$

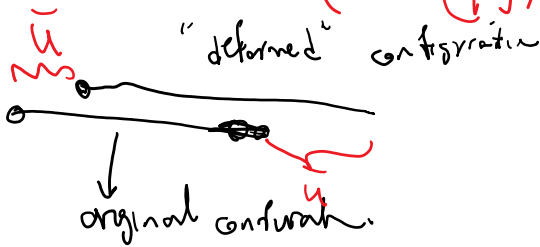
$$\begin{bmatrix} F_1 \\ F_2 \end{bmatrix} = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \frac{AE}{L} \begin{bmatrix} u_1 - u_2 \\ -u_1 + u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



$$-L^{-1} \quad \left[ \begin{matrix} F_1 \\ F_2 \end{matrix} \right] = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \frac{AE}{L} \begin{bmatrix} u_1 - u_2 \\ u_2 - u_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \boxed{u_1 = u_2}$$

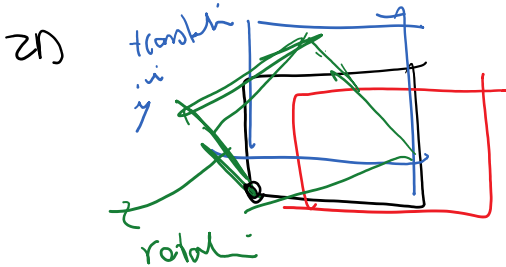
If  $u_1 = u_2$  ( $u = \vec{0} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ )  $\rightarrow F = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$



$$\epsilon = \frac{\Delta u}{L} = \frac{u_2 - u_1}{L}$$

$$\epsilon = 0 \rightarrow \delta = 0 \rightarrow F = 0$$

Rigid motion



translation in x

3 rigid modes in 2D

6 " " " " 3D

more generally Look for solutions for which  $\overbrace{L_m(u) = 0}$

we can conclude  $L_m = \nabla$

only 1 zero mode

Going back to p-el element

$$\# \text{ zero modes} = \# \text{ zero eigenvalues} = 1$$

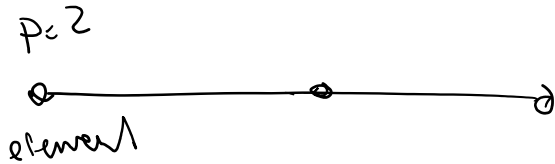
$n = \text{size of } k \quad k = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad (n=2)$

$\text{Rank}(K) = n - \# \text{ zero modes}$

$K_{n \times n}$

Matlab has a rank funcn

$K$  known  $n \checkmark$   $\text{rank}(k) \xrightarrow{\text{matlab}}$   $\# \text{ zero modes} = n - \text{rank}(K)$



$K_{3 \times 3} \quad [n=3]$

what if  $\text{rank}(K) = 1$   
 $\# \text{ zero modes} = 3 - 1 = 2$   
should be 1



and only this one

anything beyond this is nonphysical zero mode!

$U = \bar{U} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$

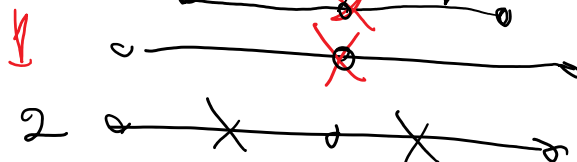
physically acceptable  
 correct rank =  $n - \# \text{ zeros} = 3 - 1 = 2$

$K_{3 \times 3}$

HW

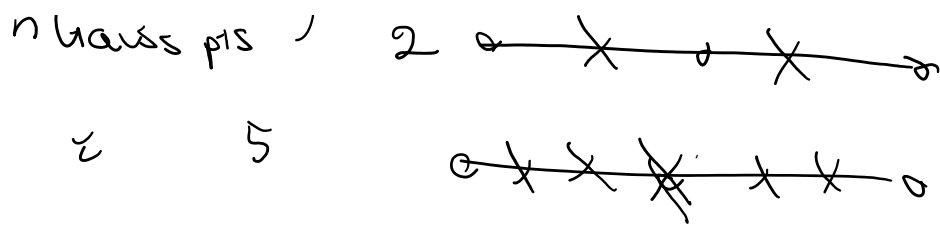
$P=2$

$n$  Gauss pts



rank=1  
 rank=2..



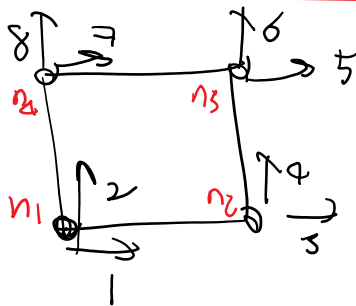


rank = 2 ..  
= 2

Another example:  
2D elasticity

8 dofs

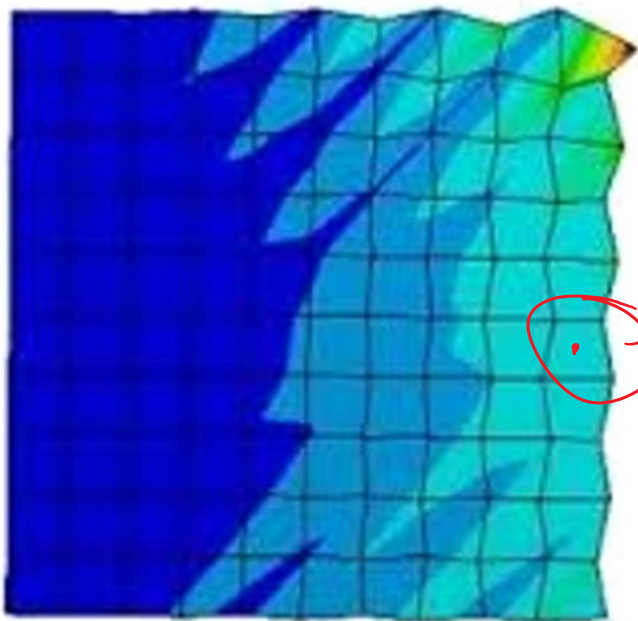
↓  
 $K_{8 \times 8}$



→ how many zero modes  
3

Correct rank =  $8 - 3 = 5$

Unacceptable reduced integral has rank  $< 5$



physically unacceptable  
zero modes