

Another set of results showing the effect of in-situ defects

Fracture stress: discrepancy between theory and experiment

$$\sigma_{th} = \sqrt{\frac{E\gamma}{a_0}}$$

	a_0 [m]	E [GPa]	σ_{th} [GPa]	σ_b [MPa]	σ_{th}/σ_b
glass	$3 * 10^{-10}$	60	14	170	82
steel	10^{-10}	210	45	250	180
silica fibers	10^{-10}	100	31	25000	1.3
iron whiskers	10^{-10}	295	54	13000	4.2
silicon whiskers	10^{-10}	165	41	6500	6.3
alumina whiskers	10^{-10}	495	70	15000	4.7
ausformed steel	10^{-10}	200	45	3000	15
piano wire	10^{-10}	200	45	2750	16.4

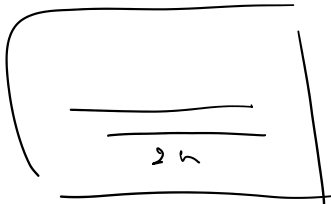
high $\sigma_c \gg \sigma_f$

as we get to finer length scales we get close to the theoretical estimate

From last time

$$\sigma_f = \sqrt{\frac{\pi \sigma_c}{4a}}$$

$\sigma_c \rightarrow$ theoretical estimate



$$\sigma_f \propto \frac{1}{\sqrt{a}}$$

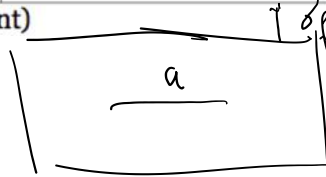
we want to experimentally verify this

Griffith's verification experiment

- Glass fibers with artificial cracks (much larger than natural crack-like flaws), tension tests

	Crack Length, $2a$ mm	Measured Strength, σ_f MPa	$\sigma_f \sqrt{a}$ MPa \sqrt{m}
sample 1	3.8	6.0	0.26
sample 2	6.9	4.3	0.25
sample 3	13.7	3.3	0.27
sample 4	22.6	2.5	0.27

(Data from the Griffith experiment)



$$\sigma_f = \sqrt{\frac{\pi_0}{4a}} \sigma_c \rightarrow$$

$$\sigma_f \sqrt{a} = \sqrt{\frac{\pi_0}{4}} \sigma_c = \text{const}$$

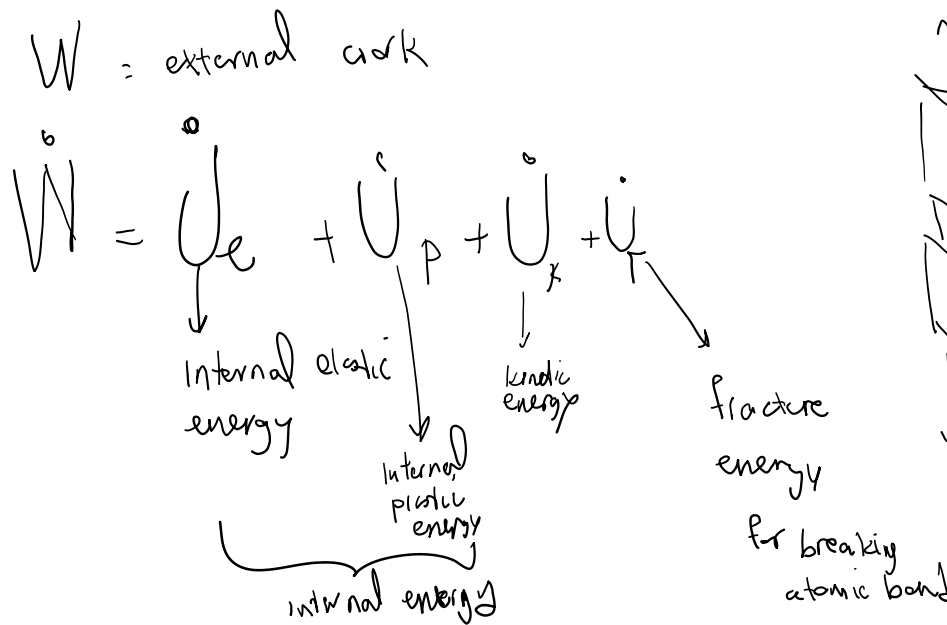
So, this experiment verifies the power of -0.5 of strength versus crack length.

We had the stress-based (using stress concentration concept) explanation why $\sigma_f \ll \sigma_c$

Energy-based explanation:

4.1.3. Cause of discrepancy:

2. Energy approach



Simplification:

1. Ignore plastic part (acceptable for more brittle fracture)
2. Ignore dynamic effect → Kinetic energy (rate) is almost zero

→ quasi-static

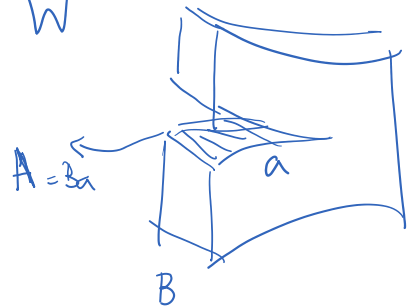
$$\dot{W} = \dot{U}_e + \dot{U}_f \rightarrow \dot{U}_f = -(\dot{U}_e - \dot{W})$$

potential ← $\Pi = U_e - W$ →

potential energy $\Pi = U_e - W$

$$\frac{dU_{\Gamma}}{dt} = -\frac{d\Pi}{dt}, \quad \Pi = U_e - W$$

$$\frac{d(\cdot)}{dt} = \frac{d(\cdot)}{da} \left(\frac{da}{dt}\right) \rightarrow \text{crack speed}$$



$$\frac{1}{B} \frac{dU_{\Gamma}}{da} \checkmark_c = -\frac{1}{B} \frac{d\Pi}{da} \checkmark_c \rightarrow \frac{\delta U_{\Gamma}}{\delta A} = -\frac{1}{B} \frac{\delta \Pi}{\delta a}$$

↓ thickness

$$\frac{\delta U_{\Gamma}}{\delta A} = -\frac{1}{B} \frac{\delta \Pi}{\delta a}$$

|| $2\delta_s$

$2\delta_s = -\frac{1}{B} \frac{\delta \Pi}{\delta a}$

Π potential energy = $U_e - W$

ⓐ

area

energy release rate

material resistance

Use equation (*) to explain why strength is much lower than theoretical strength

From Inglis solution

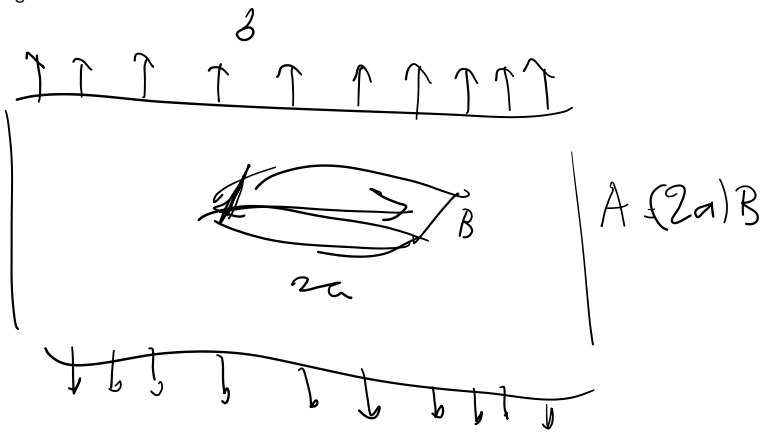
2a crack in an infinite domain

$$\Pi(a) - \Pi(0) = \frac{\sigma^2 a^3 B}{E}$$

$$\frac{d\Pi}{dA} = \frac{1}{B} \frac{d\Pi}{da} = -\frac{\sigma a \sigma^2}{E}$$

If the crack can propagate the minimum far field stress needed is $\sigma = \sigma_f$ (material strength)

($\sigma a \sigma^2$)



$$-\left(-\frac{\pi a \sigma_f^2}{E}\right) = 2\gamma_s \rightarrow$$

(last time)

Energy argument

$$\sigma_f = \sqrt{\frac{E\gamma_s}{4a}}$$

$$\sigma_f = 0.5 \sqrt{\frac{E\gamma_s}{a}}$$

Stress-concentration argument

$$\sigma_f = \sqrt{\frac{E\gamma_s}{\pi/4 a}}$$

$$\sigma_f \approx 0.8 \sqrt{\frac{E\gamma_s}{a}}$$

Both approaches predict the same formula for the strength, except the factor upfront.

Recall $\sigma_c = \sqrt{\frac{E\sigma_f}{\lambda_0}} \gg \sqrt{\frac{E\gamma_s}{4a}} = \sigma_f$

How can we incorporate plasticity (with some approximation)

Energy equation for ductile materials

Plane stress

$$\sigma_c = \sqrt{\frac{2E\gamma_s}{\pi a}}$$

Griffith (1921), ideally brittle solids

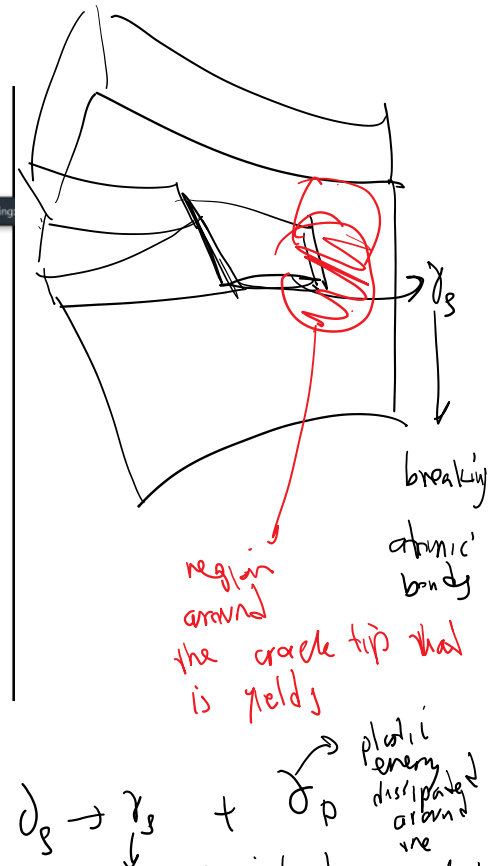
$$\sigma_c = \sqrt{\frac{2E(\gamma_s + \gamma_p)}{\pi a}}$$

Irwin, Orowan (1948), metals

γ_p plastic work per unit area of surface created

$$\gamma_p \gg \gamma_s$$

$$\gamma_p \approx 10^3 \gamma_s \text{ (metals)}$$



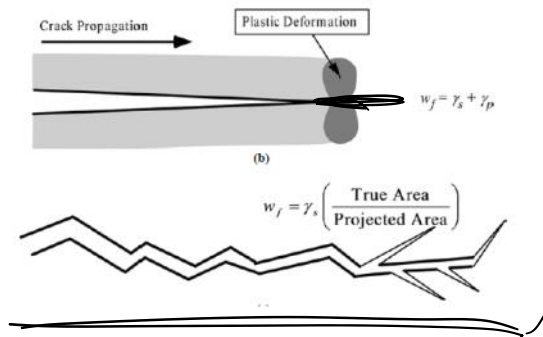
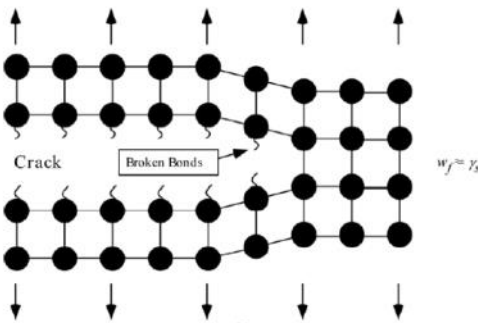


$\sigma_f \rightarrow \gamma_s + \sigma_p$
 ↓
 breaking atomic bonds
 dissipated strain energy
 crack tip

Generalization of Energy equation

$$\sigma_f = \sqrt{\frac{2Kw_f}{\pi a}}$$

- w_f : Fracture energy from plastic, viscoelastic, or viscoplastic effects
- w_f can also be influenced by crack meandering and branching
- Caution: If nonlinear displacement regions are large enough this equation is not accurate as it is based on linear elastic solution ($\Pi = \Pi_0 - \frac{\pi\sigma^2 a^2 B}{E}$)



Energy release rate

Irwin 1956

$$G \equiv -\frac{d\Pi}{dA}$$

a.k.a

Crack extension force
Crack driving force

here
↓
per
unit area
of crack
growth

when the crack grows

$$-\frac{d\Pi}{dA} \geq 2\gamma_s$$

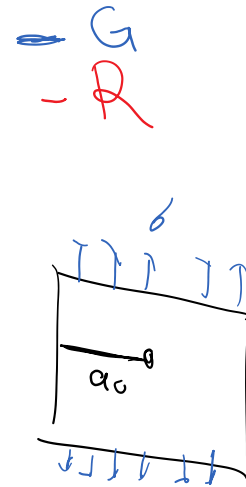
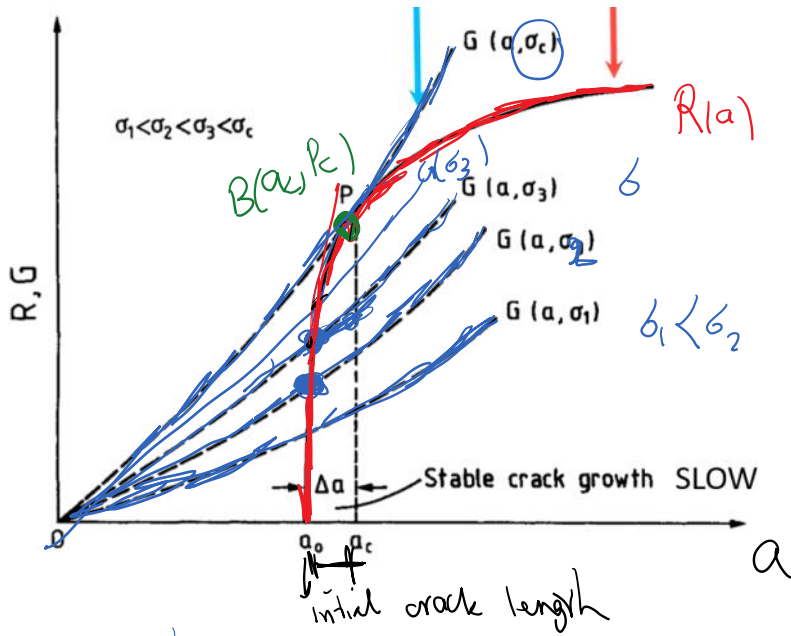
R
resistance

$$G = -\frac{d\Pi}{dA}$$

$< R = 2\gamma_s$ crack won't propagate
 $= R$ propagate
 $> R$ " in dynamic ... do

$L > R$ " in dynamic mode

G, R plots (curves)

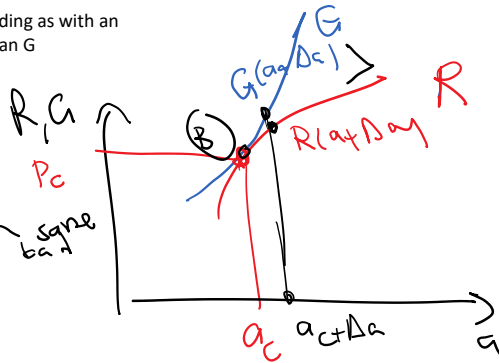


$$\sigma_1 < \sigma_2 < \sigma_3 < \sigma_c$$

σ_3 : crack propagation initiation stage: $G = R$

The crack will not grow with this sustained loading as with an increment of crack length R becomes larger than G

$\downarrow \sigma$ same



for continued propagation with same σ

$$G(a + \Delta a) > R(a + \Delta a)$$

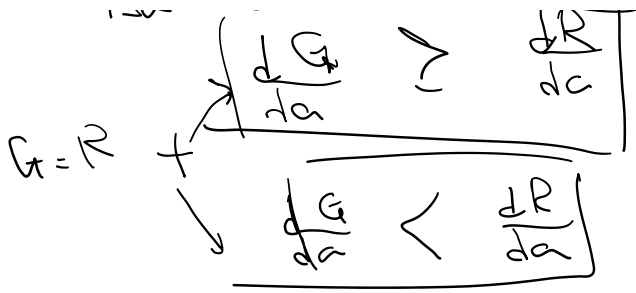
initially

$$G(a) = R(a)$$

$$\lim_{\Delta a \rightarrow 0} \frac{G(a + \Delta a) - G(a)}{\Delta a} > \frac{R(a + \Delta a) - R(a)}{\Delta a}$$

$$\frac{dG}{da} > \frac{dR}{da}$$

condition for unstable crack growth (beyond σ_c)



condition for unstable crack growth (beyond critical)

stable crack growth, loading should increase for the crack to grow

$$G_3 \rightarrow G_c$$

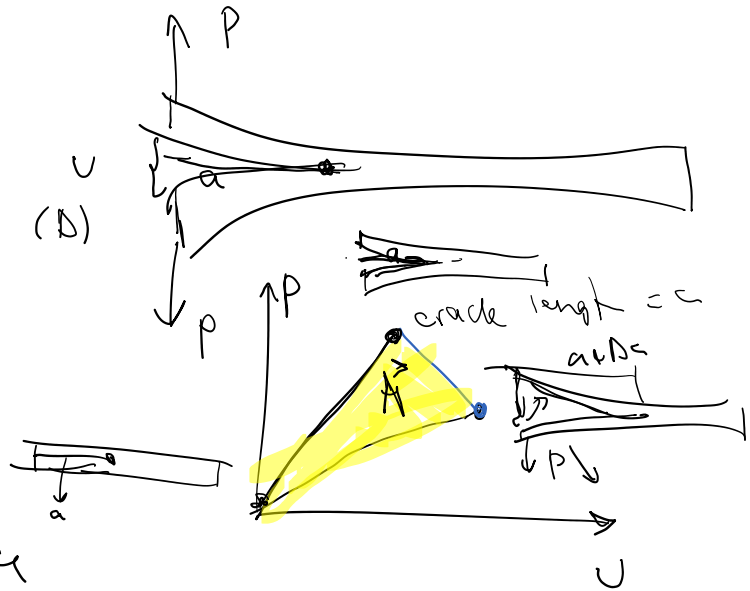
How to calculate G?

1. For P-Delta (u) systems

$$G = - \frac{d\pi}{da} = \frac{\text{shaded area}}{B}$$

$$= \frac{P^2}{2B} \frac{dC}{da}$$

Compliance



2. Using Stress intensity factor (SIF)

$$G = \frac{K_I^2 + K_{II}^2}{E'}$$

elastic modulus or ...