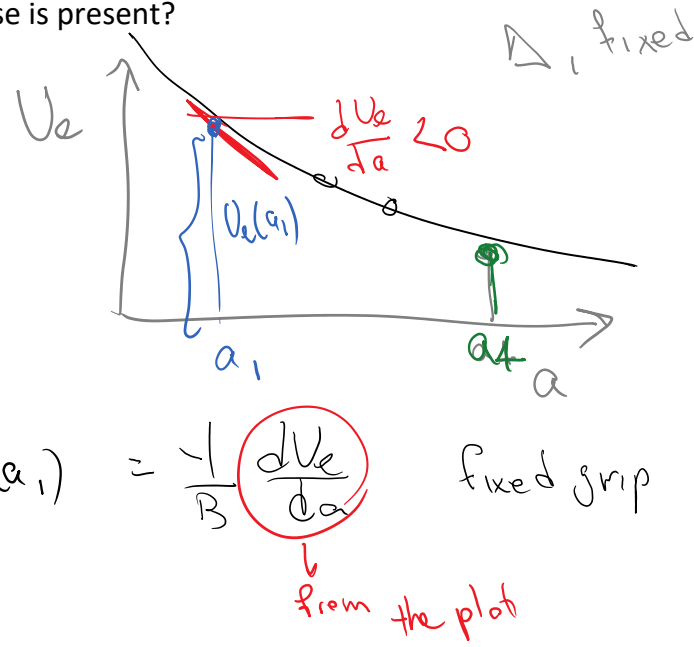
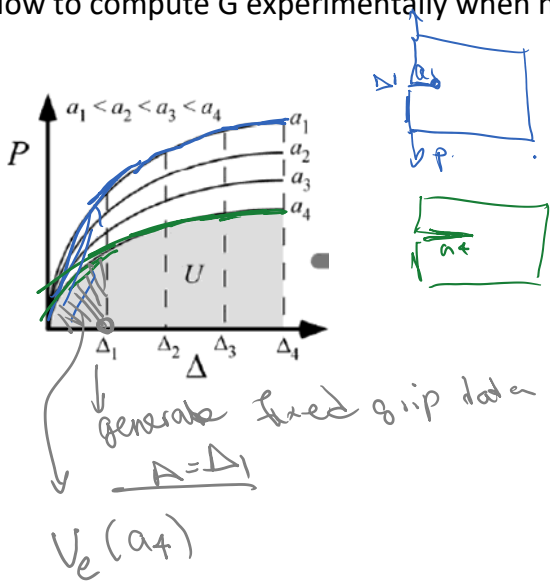


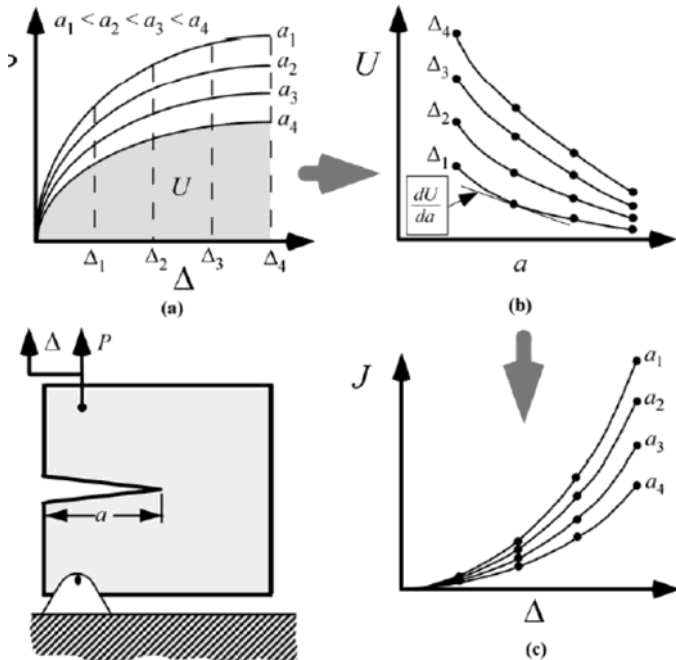
How to compute G experimentally when nonlinear response is present?



$$G(a_1) = \frac{1}{B} \frac{dV_e}{da}$$

↓
from the plot

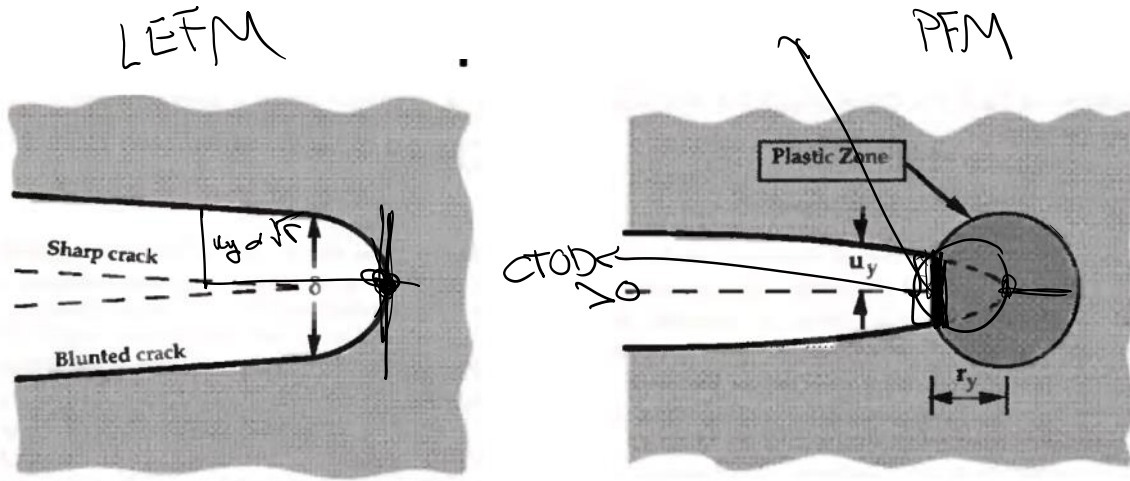
Landes and Begley, ASTM 1972



Rice proposes a method to obtain $J = G$, with only one test for certain geometries.

Crack tip opening displacement (CTOD) versus J-integral

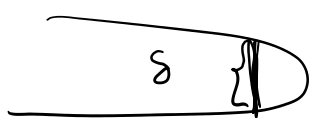
5.4. Crack tip opening displacement (CTOD), relations with J and G



LEFM $u_y \propto \sqrt{r}$
 $\delta \propto \frac{1}{\sqrt{r}}$

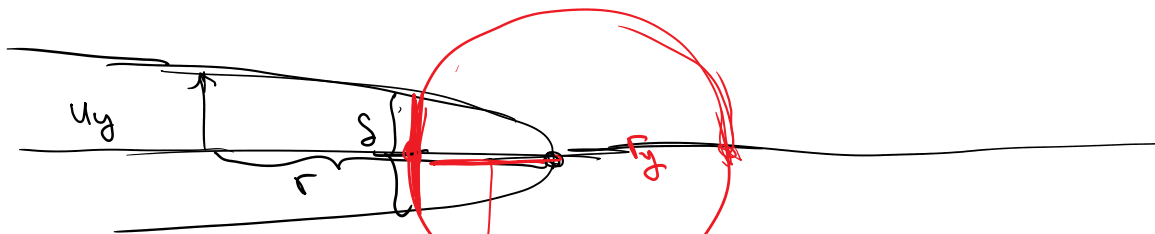
$\delta \rightarrow$ bounded by δ_{eff} - δ_0

Parallel to Rice's work in the US, Wells in the UK looked at the CTOD as a measure of nonlinear material response in the Fracture Process Zone (FPZ)



$\delta \uparrow \rightarrow$ more nonlinear response
 we want to relate δ to σ

Estimates for CTOD (δ)



LEFM crack opening
 $u_y = \frac{(K+1)KI\sqrt{r}}{2\mu}$

$r \rightarrow r_p \implies u_y(r_p) = \frac{\delta}{2}$

$$\sigma \rightarrow r_y \implies u_y(r_y) = \frac{\delta}{2}$$

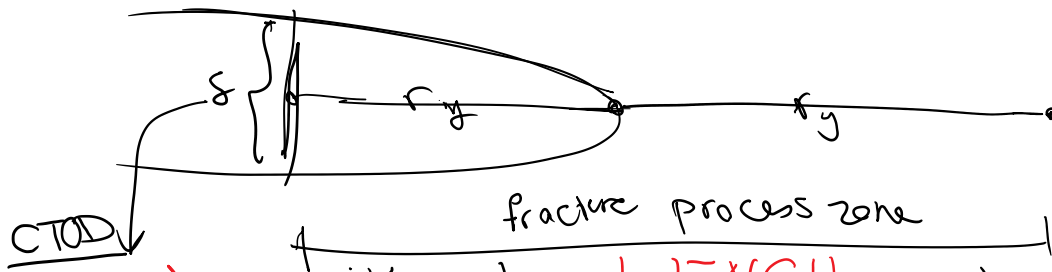
$$r_y = \left(\frac{K_I}{\sigma_{ys}} \right)^2$$

$$K = \frac{3P}{1+\nu} \quad \text{p. strain}$$

$$\mu = \frac{E}{2(1+\nu)}$$

$$\delta \approx \frac{4}{\pi} \frac{K_I^2}{\sigma_{ys} E}$$

estimate for CTOD



CTOD
Displacement quantity

it's the **LENGTH** of the region that is undergoing significant nonlinear response

$$r_y = \left(\frac{K_I}{\sigma_{ys}} \right)^2$$

length

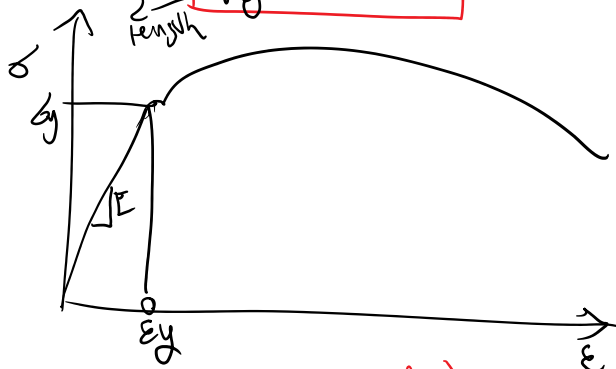
FPZS

$$\frac{\delta}{r_y} \propto \frac{\sigma_{ys}}{E}$$

strain scale

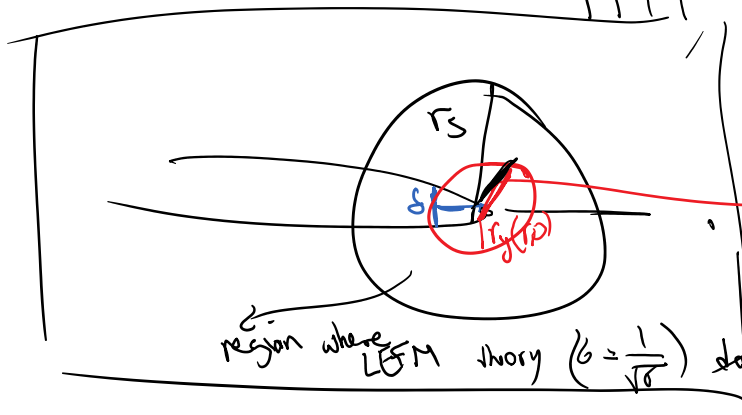
$$\delta = \left(\frac{K_I}{\sigma_{ys} E} \right)^2$$

displacement scale



$$r_s = \left(\frac{K_I}{\sigma} \right)^2$$

$\delta \uparrow \uparrow \uparrow \uparrow$



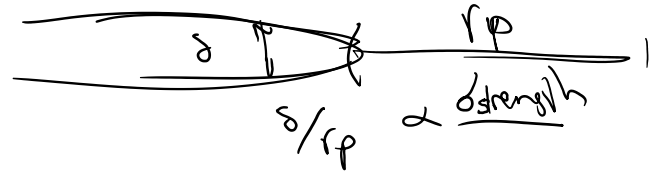
(length scale)
size where material is significantly yielding, ...

$$\delta \ll r_y \ll r_s \ll \frac{r_s}{\sigma_{ys}} \text{ holds } \left(\frac{\delta}{\sigma_y} \right)^2 \ll 1$$

$$\frac{r_y}{r_s} \propto \left(\frac{\sigma}{\sigma_y} \right)^2$$

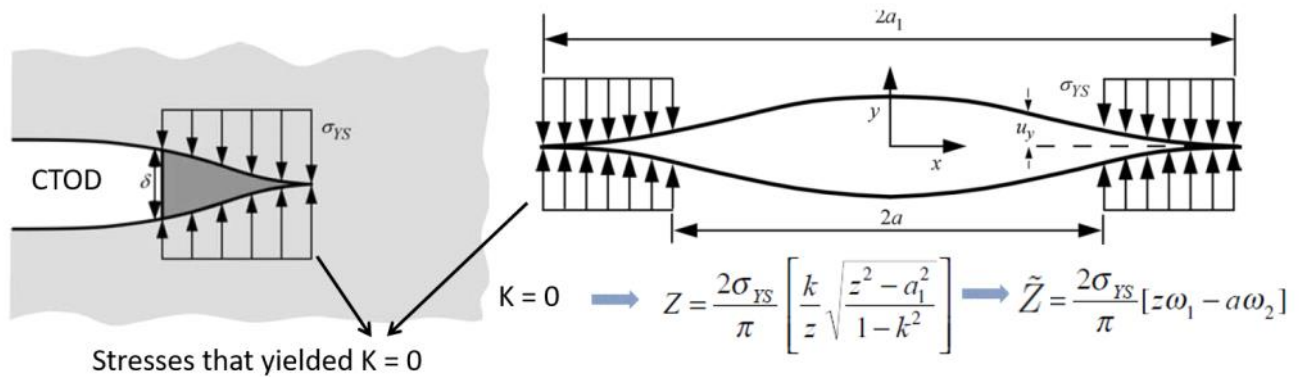
In many instances, LEFM, PFM, Traction separation relations, frictional laws

In many instances, LEFM, PFM, Traction separation relations, frictional laws, ...
 FPZ size (**length** scale) is much larger than the **displacement** scale of the model and typically proportional to **E/strength**



The above estimate for CTOD was very crude and can be improved with better models

Crack Tip Opening Displacement: Strip yield model



Stresses that yielded $K = 0$

$$\rightarrow u_y = \frac{2}{E} \text{Im} \tilde{Z} = \frac{4\sigma_{YS}}{\pi E} \left[a \coth^{-1} \left(\frac{1}{a_1} \sqrt{\frac{a_1^2 - z^2}{1 - k^2}} \right) - z \coth^{-1} \left(\frac{k}{z} \sqrt{\frac{a_1^2 - z^2}{1 - k^2}} \right) \right]$$

$$z = a \rightarrow \delta = 2u_y = \frac{8\sigma_{YS}a}{\pi E} \ln \left(\frac{1}{k} \right) = \frac{8\sigma_{YS}a}{\pi E} \left[\frac{1}{2} \left(\frac{\pi \sigma}{2 \sigma_{YS}} \right)^2 + \frac{1}{12} \left(\frac{\pi \sigma}{2 \sigma_{YS}} \right)^4 + \dots \right] \rightarrow$$

For $\sigma/\sigma_{YS} \rightarrow 0$ $\left\{ \delta = \frac{K_I^2}{\sigma_{YS} E} \right\}$

our crude approach earlier had

$$\delta = \left(\frac{4}{\pi} \right) \frac{K_I^2}{6\sigma_{YS} E}$$

Is there a relation between J and CTOD?

Both measure the extent of material nonlinear response.

$$\delta = \frac{K_I^2}{E \sigma_{YS}} \left. \begin{matrix} \\ \\ \end{matrix} \right\} \rightarrow \delta \propto \frac{J}{\sigma_y} \quad (1)$$

$$J = G = \frac{K_I^2}{E'} \quad \left. \begin{array}{l} \text{Edps} \\ \text{or} \end{array} \right\} \rightarrow \delta \propto \frac{\sigma}{\sigma_y} \quad (1)$$

$$J = m \delta \sigma_y$$

or $J \nearrow$ (higher loads)
 $\sigma_y \searrow$ (more ductile response) $\rightarrow \delta \nearrow$



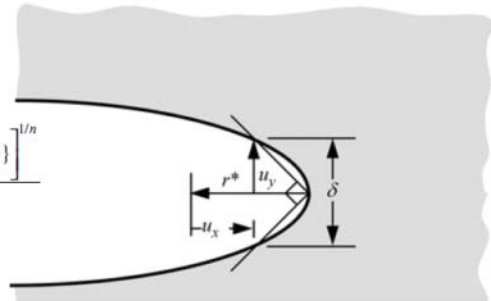
CTOD-J relation

- When SSY is satisfied $G = J$ so we expect:

$$G = m \sigma_y \delta \Rightarrow J = m \sigma_y \delta$$

- In fact this equation is valid well beyond validity of LEFM and SSY
- E.g. for HRR solution Shih showed that:

$$u_i = \frac{\alpha \sigma_o}{E} \left(\frac{EJ}{\alpha \sigma_o^2 I_n r} \right)^{\frac{n}{n+1}} r \tilde{u}_i(\theta, n) \quad d_n = \frac{2 \tilde{u}_y(\pi, n) \left[\frac{\alpha \sigma_o}{E} \{ \tilde{u}_x(\pi, n) + \tilde{u}_y(\pi, n) \} \right]^{1/n}}{I_n}$$

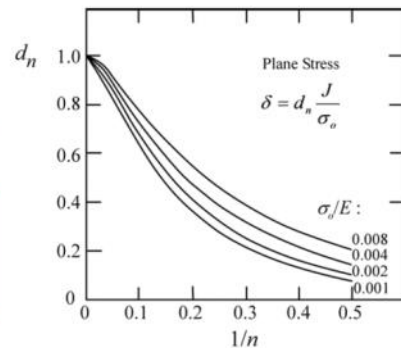


- δ is obtained by 90 degree method:
 Deformed position corresponding to $r^* = r$
 $\phi = -\pi$ forms 45 degree w.r.t crack tip)

$$\frac{\delta}{2} = u_y(r^*, \pi) = r^* - u_x(r^*, \pi)$$

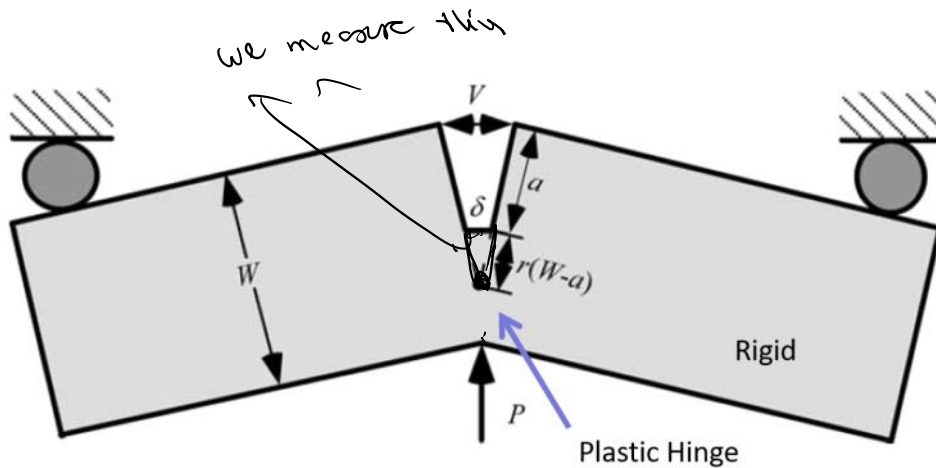
$$r^* = \left(\frac{\alpha \sigma_o}{E} \right)^{1/n} \{ \tilde{u}_x(\pi, n) + \tilde{u}_y(\pi, n) \}^{\frac{n+1}{n}} \frac{J}{\sigma_o I_n} \Rightarrow J = m \sigma_o \delta$$

for $m = \frac{1}{d_n}, d_n = \frac{2 \tilde{u}_y(\pi, n) \left[\frac{\alpha \sigma_o}{E} \{ \tilde{u}_x(\pi, n) + \tilde{u}_y(\pi, n) \} \right]^{1/n}}{I_n}$



We can experimentally measure CTOD (and needed obtain J yet from another way)
 Anderson

CTOD experimental determination



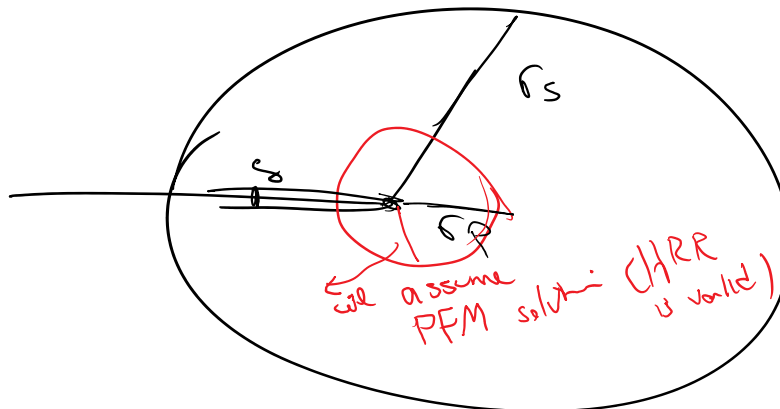
$$\frac{\delta_f}{CMOD} = \frac{r(W-a)}{r(W-a)+a} \quad \text{similarity of triangles}$$

r : rotational factor [-], between 0 and 1

For high elastic deformation contribution, elastic corrections should be added

261

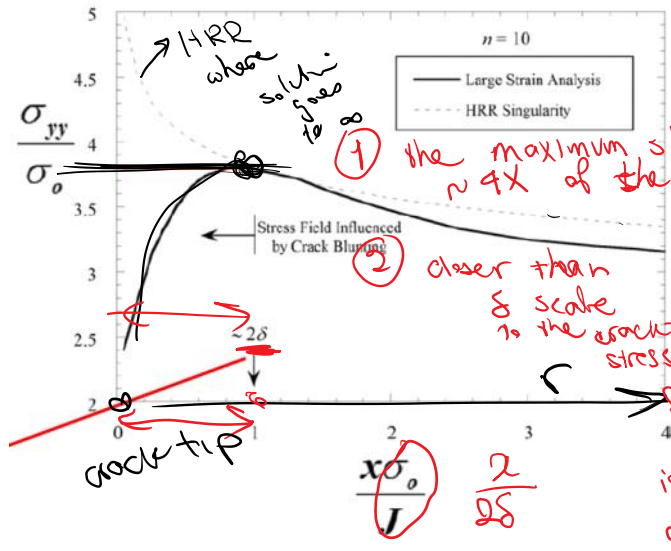
When to use LEFM, PFM, ...



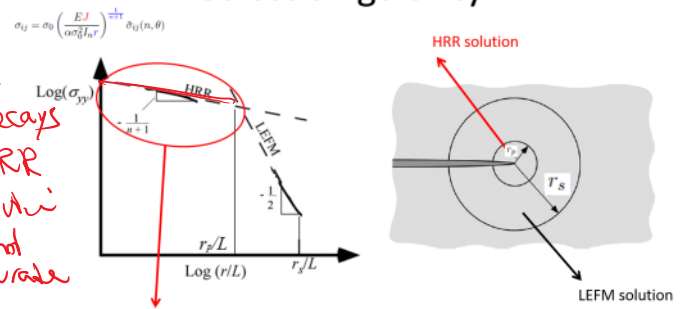
SSY: r_p is significantly smaller than all relevant length scale of the problem.
As a necessary condition (but not sufficient)

$$r_p \ll r_s$$

$$\left(\frac{\sigma}{\sigma_y}\right)^2 \ll 1$$



HRR solution: Stress singularity



Stress is still singular but with a weaker power of singularity!

McMeeking and Parks, ASTM STP 668, ASTM 1979

$$\delta = \frac{1}{m} \frac{J}{\sigma_y}$$

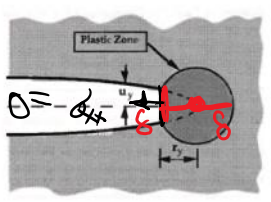
Limitations of HRR analysis

- Small strain: $\epsilon = \frac{1}{2} (\nabla \mathbf{u} + \nabla^T \mathbf{u})$ (accurate for $\epsilon \lesssim 0.1$)
- Small deformation theory (e.g., not using PK stresses, etc)
- Elastic HRR model instead of plastic model
- Crack tip blunting: $\Rightarrow \sigma_{xx} = 0$

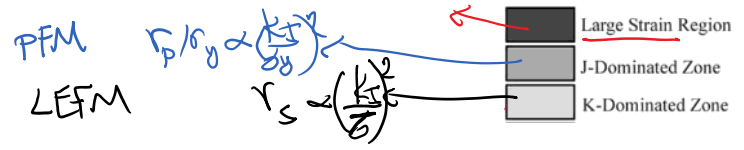
prev. HRR solution used infinitesimal deformation theory

$$\mathbf{G} = \frac{1}{2} (\mathbf{C} - \mathbf{I}) \quad , \quad \mathbf{C} = \nabla \mathbf{u} \nabla \mathbf{u}^T$$

HRR solution did not allow plastic unloading



delta size proportional to CTOD

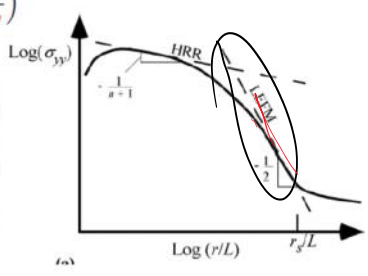


From SSY to LSY

Large strain radius $r_n \propto \delta$ (CTOD): $\delta = O\left(\frac{K^2}{E\sigma_y}\right)$

plastic radius: $r_p = O\left(\frac{K^2}{\sigma_y^2}\right)$

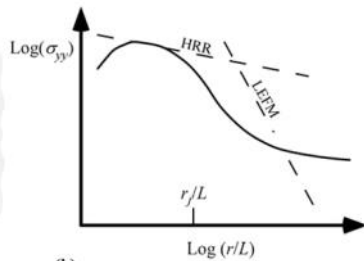
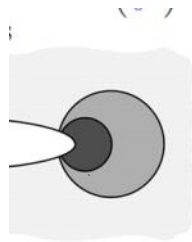
K-dominant radius: $r_s = O\left(\frac{K^2}{\sigma^2}\right)$



SSY (Small Scale Yielding)

$$r_n \ll r_p \ll r_s \Rightarrow$$

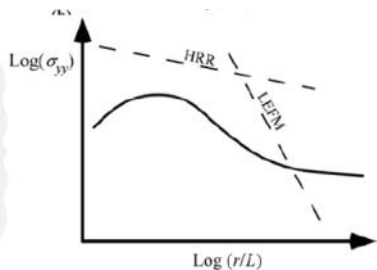
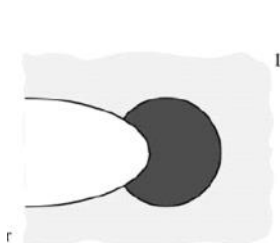
$$\frac{r_p}{r_s} \propto \left(\frac{\bar{\sigma}}{\sigma_y}\right)^2 \ll 1$$



Elastic plastic condition

$$r_n \ll r_p \approx r_s \Rightarrow$$

$$\frac{r_n}{r_p} \ll 1, \quad \frac{r_p}{r_s} \propto \left(\frac{\bar{\sigma}}{\sigma_y}\right)^2 \approx 1$$



LSJ (Large Scale Yielding)

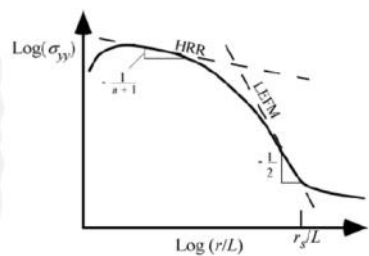
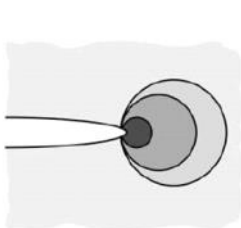
$$r_n \approx r_p$$

$$\text{Note that } \frac{\delta}{r_p} \propto \left(\frac{\sigma_y}{E}\right)$$

blinde strain
and/or plastic unloading zone

can become significant comparable to r_y

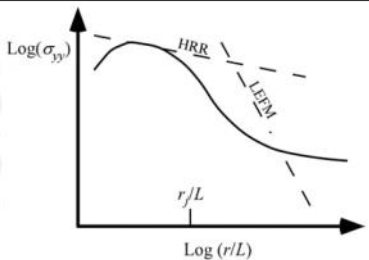
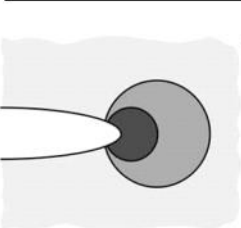
From SSY to LSJ



LEFM: SSY satisfied and generally have

$$\bar{\sigma} \ll \sigma_y$$

Relevant parameters:
G (energy) K (stress)

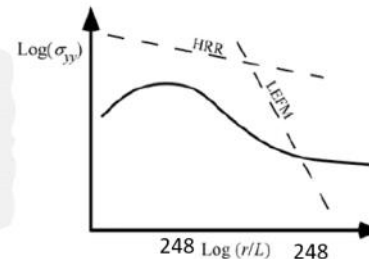
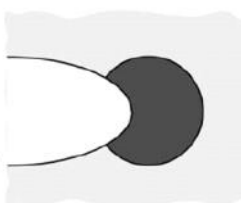


PFM (or NFM): SSY is gradually violated and

$$\bar{\sigma} \approx \sigma_y$$

Relevant parameters:
J (energy & used for stress)

- Large Strain Region
- J-Dominated Zone
- K-Dominated Zone
- No Single-Parameter Characterization

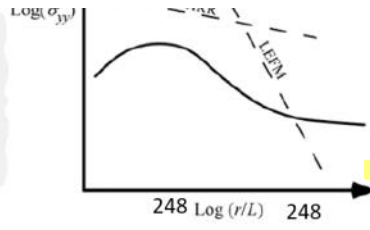
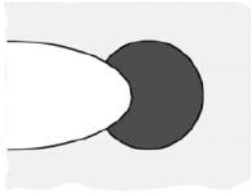


LSJ condition:

No single parameter can characterize fracture!

J + other parameters (e.g. T stress, Q-J, etc)

- Large Strain Region
- J-Dominated Zone
- K-Dominated Zone
- No Single-Parameter Characterization



No single parameter can characterize fracture!

J + other parameters (e.g. T stress, Q-J, etc)